

Monoclinic (Hittorf's) Phosphorus Structure: A_mP84_13_21g-001

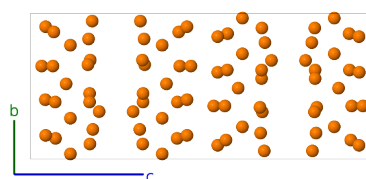
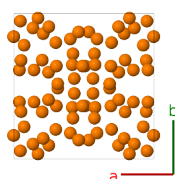
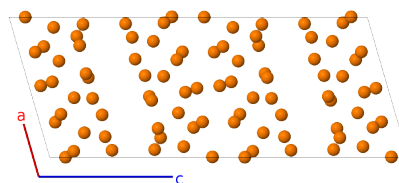
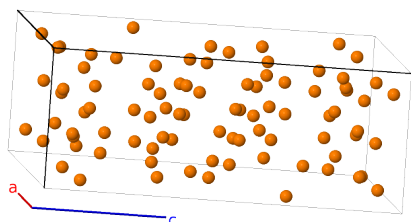
This structure originally had the label A_mP84_13_21g. Calls to that address will be redirected here.

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<https://aflow.org/p/SEQF>

https://aflow.org/p/A_mP84_13_21g-001

●P



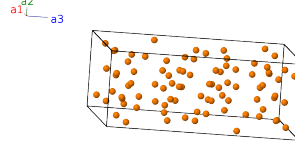
Prototype	P
AFLOW prototype label	A_mP84_13_21g-001
Mineral name	hittorf's phosphorus
ICSD	29273
Pearson symbol	mP84
Space group number	13
Space group symbol	$P2/c$
AFLOW prototype command	<pre>aflow --proto=A_mP84_13_21g-001 --params=a,b/a,c/a,β,x₁,y₁,z₁,x₂,y₂,z₂,x₃,y₃,z₃,x₄,y₄,z₄,x₅,y₅,z₅,x₆,y₆,z₆,x₇, y₇,z₇,x₈,y₈,z₈,x₉,y₉,z₉,x₁₀,y₁₀,z₁₀,x₁₁,y₁₁,z₁₁,x₁₂,y₁₂,z₁₂,x₁₃,y₁₃,z₁₃,x₁₄,y₁₄,z₁₄,x₁₅, y₁₅,z₁₅,x₁₆,y₁₆,z₁₆,x₁₇,y₁₇,z₁₇,x₁₈,y₁₈,z₁₈,x₁₉,y₁₉,z₁₉,x₂₀,y₂₀,z₂₀,x₂₁,y₂₁,z₂₁</pre>

- Phosphorus is found in at least three forms:

- Black phosphorus, *Strukturbericht* A17,
- Monoclinic Hittorf's phosphorus, (this structure) and
- Low temperature triclinic “white” phosphorus, stable below 197K.

Simple Monoclinic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	=	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4g)	P I
\mathbf{B}_2	$-x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P I
\mathbf{B}_3	$-x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	=	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4g)	P I
\mathbf{B}_4	$x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P I
\mathbf{B}_5	$x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	=	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4g)	P II
\mathbf{B}_6	$-x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P II
\mathbf{B}_7	$-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	=	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4g)	P II
\mathbf{B}_8	$x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P II
\mathbf{B}_9	$x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	=	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4g)	P III
\mathbf{B}_{10}	$-x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P III
\mathbf{B}_{11}	$-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	=	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4g)	P III
\mathbf{B}_{12}	$x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P III
\mathbf{B}_{13}	$x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	=	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4g)	P IV
\mathbf{B}_{14}	$-x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P IV
\mathbf{B}_{15}	$-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	=	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4g)	P IV
\mathbf{B}_{16}	$x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P IV
\mathbf{B}_{17}	$x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	=	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4g)	P V
\mathbf{B}_{18}	$-x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P V
\mathbf{B}_{19}	$-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	=	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(4g)	P V
\mathbf{B}_{20}	$x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P V
\mathbf{B}_{21}	$x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	=	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(4g)	P VI

$$\begin{aligned}
\mathbf{B}_{22} &= -x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 - \left(z_6 - \frac{1}{2}\right) \mathbf{a}_3 &= -\left(ax_6 + c\left(z_6 - \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} - &(4g) & \text{P VI} \\
&&& c\left(z_6 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{23} &= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3 &= -(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}} &(4g) & \text{P VI} \\
\mathbf{B}_{24} &= x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 + \left(z_6 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_6 + c\left(z_6 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + &(4g) & \text{P VI} \\
&&& c\left(z_6 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{25} &= x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3 &= (ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}} &(4g) & \text{P VII} \\
\mathbf{B}_{26} &= -x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 - \left(z_7 - \frac{1}{2}\right) \mathbf{a}_3 &= -(ax_7 + c\left(z_7 - \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} - &(4g) & \text{P VII} \\
&&& c\left(z_7 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{27} &= -x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3 &= -(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}} &(4g) & \text{P VII} \\
\mathbf{B}_{28} &= x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 + \left(z_7 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_7 + c\left(z_7 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + &(4g) & \text{P VII} \\
&&& c\left(z_7 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{29} &= x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3 &= (ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}} &(4g) & \text{P VIII} \\
\mathbf{B}_{30} &= -x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 - \left(z_8 - \frac{1}{2}\right) \mathbf{a}_3 &= -(ax_8 + c\left(z_8 - \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} - &(4g) & \text{P VIII} \\
&&& c\left(z_8 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{31} &= -x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3 &= -(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}} &(4g) & \text{P VIII} \\
\mathbf{B}_{32} &= x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 + \left(z_8 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_8 + c\left(z_8 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} + &(4g) & \text{P VIII} \\
&&& c\left(z_8 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{33} &= x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3 &= (ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}} &(4g) & \text{P IX} \\
\mathbf{B}_{34} &= -x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 - \left(z_9 - \frac{1}{2}\right) \mathbf{a}_3 &= -(ax_9 + c\left(z_9 - \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} - &(4g) & \text{P IX} \\
&&& c\left(z_9 - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{35} &= -x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3 &= -(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}} &(4g) & \text{P IX} \\
\mathbf{B}_{36} &= x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 + \left(z_9 + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_9 + c\left(z_9 + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} + &(4g) & \text{P IX} \\
&&& c\left(z_9 + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{37} &= x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3 &= (ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}} &(4g) & \text{P X} \\
\mathbf{B}_{38} &= -x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 - \left(z_{10} - \frac{1}{2}\right) \mathbf{a}_3 &= -(ax_{10} + c\left(z_{10} - \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} - &(4g) & \text{P X} \\
&&& c\left(z_{10} - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{39} &= -x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3 &= -(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} - &(4g) & \text{P X} \\
&&& cz_{10} \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{40} &= x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 + \left(z_{10} + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_{10} + c\left(z_{10} + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} + &(4g) & \text{P X} \\
&&& c\left(z_{10} + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{41} &= x_{11} \mathbf{a}_1 + y_{11} \mathbf{a}_2 + z_{11} \mathbf{a}_3 &= (ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} + cz_{11} \sin \beta \hat{\mathbf{z}} &(4g) & \text{P XI} \\
\mathbf{B}_{42} &= -x_{11} \mathbf{a}_1 + y_{11} \mathbf{a}_2 - \left(z_{11} - \frac{1}{2}\right) \mathbf{a}_3 &= -(ax_{11} + c\left(z_{11} - \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} - &(4g) & \text{P XI} \\
&&& c\left(z_{11} - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{43} &= -x_{11} \mathbf{a}_1 - y_{11} \mathbf{a}_2 - z_{11} \mathbf{a}_3 &= -(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} - &(4g) & \text{P XI} \\
&&& cz_{11} \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{44} &= x_{11} \mathbf{a}_1 - y_{11} \mathbf{a}_2 + \left(z_{11} + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_{11} + c\left(z_{11} + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} + &(4g) & \text{P XI} \\
&&& c\left(z_{11} + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{45} &= x_{12} \mathbf{a}_1 + y_{12} \mathbf{a}_2 + z_{12} \mathbf{a}_3 &= (ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} + by_{12} \hat{\mathbf{y}} + cz_{12} \sin \beta \hat{\mathbf{z}} &(4g) & \text{P XII} \\
\mathbf{B}_{46} &= -x_{12} \mathbf{a}_1 + y_{12} \mathbf{a}_2 - \left(z_{12} - \frac{1}{2}\right) \mathbf{a}_3 &= -(ax_{12} + c\left(z_{12} - \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} + by_{12} \hat{\mathbf{y}} - &(4g) & \text{P XII} \\
&&& c\left(z_{12} - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{47} &= -x_{12} \mathbf{a}_1 - y_{12} \mathbf{a}_2 - z_{12} \mathbf{a}_3 &= -(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} - by_{12} \hat{\mathbf{y}} - &(4g) & \text{P XII} \\
&&& cz_{12} \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{48} &= x_{12} \mathbf{a}_1 - y_{12} \mathbf{a}_2 + \left(z_{12} + \frac{1}{2}\right) \mathbf{a}_3 &= \left(ax_{12} + c\left(z_{12} + \frac{1}{2}\right) \cos \beta\right) \hat{\mathbf{x}} - by_{12} \hat{\mathbf{y}} + &(4g) & \text{P XII} \\
&&& c\left(z_{12} + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{49} &= x_{13} \mathbf{a}_1 + y_{13} \mathbf{a}_2 + z_{13} \mathbf{a}_3 &= (ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + by_{13} \hat{\mathbf{y}} + cz_{13} \sin \beta \hat{\mathbf{z}} &(4g) & \text{P XIII}
\end{aligned}$$

$$\begin{aligned}
\mathbf{B}_{76} &= x_{19} \mathbf{a}_1 - y_{19} \mathbf{a}_2 + \left(z_{19} + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} & (ax_{19} + c \left(z_{19} + \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} - by_{19} \hat{\mathbf{y}} + \\ & c \left(z_{19} + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4g) & \text{P XIX} \\
\mathbf{B}_{77} &= x_{20} \mathbf{a}_1 + y_{20} \mathbf{a}_2 + z_{20} \mathbf{a}_3 = (ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} + by_{20} \hat{\mathbf{y}} + cz_{20} \sin \beta \hat{\mathbf{z}} & (4g) & \text{P XX} \\
\mathbf{B}_{78} &= -x_{20} \mathbf{a}_1 + y_{20} \mathbf{a}_2 - \left(z_{20} - \frac{1}{2}\right) \mathbf{a}_3 = - \begin{aligned} & (ax_{20} + c \left(z_{20} - \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} + by_{20} \hat{\mathbf{y}} - \\ & c \left(z_{20} - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4g) & \text{P XX} \\
\mathbf{B}_{79} &= -x_{20} \mathbf{a}_1 - y_{20} \mathbf{a}_2 - z_{20} \mathbf{a}_3 = - \begin{aligned} & (ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} - by_{20} \hat{\mathbf{y}} - \\ & cz_{20} \sin \beta \hat{\mathbf{z}} \end{aligned} & (4g) & \text{P XX} \\
\mathbf{B}_{80} &= x_{20} \mathbf{a}_1 - y_{20} \mathbf{a}_2 + \left(z_{20} + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} & (ax_{20} + c \left(z_{20} + \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} - by_{20} \hat{\mathbf{y}} + \\ & c \left(z_{20} + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4g) & \text{P XX} \\
\mathbf{B}_{81} &= x_{21} \mathbf{a}_1 + y_{21} \mathbf{a}_2 + z_{21} \mathbf{a}_3 = (ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} + by_{21} \hat{\mathbf{y}} + cz_{21} \sin \beta \hat{\mathbf{z}} & (4g) & \text{P XXI} \\
\mathbf{B}_{82} &= -x_{21} \mathbf{a}_1 + y_{21} \mathbf{a}_2 - \left(z_{21} - \frac{1}{2}\right) \mathbf{a}_3 = - \begin{aligned} & (ax_{21} + c \left(z_{21} - \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} + by_{21} \hat{\mathbf{y}} - \\ & c \left(z_{21} - \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4g) & \text{P XXI} \\
\mathbf{B}_{83} &= -x_{21} \mathbf{a}_1 - y_{21} \mathbf{a}_2 - z_{21} \mathbf{a}_3 = - \begin{aligned} & (ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} - by_{21} \hat{\mathbf{y}} - \\ & cz_{21} \sin \beta \hat{\mathbf{z}} \end{aligned} & (4g) & \text{P XXI} \\
\mathbf{B}_{84} &= x_{21} \mathbf{a}_1 - y_{21} \mathbf{a}_2 + \left(z_{21} + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} & (ax_{21} + c \left(z_{21} + \frac{1}{2}\right) \cos \beta) \hat{\mathbf{x}} - by_{21} \hat{\mathbf{y}} + \\ & c \left(z_{21} + \frac{1}{2}\right) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4g) & \text{P XXI}
\end{aligned}$$

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