

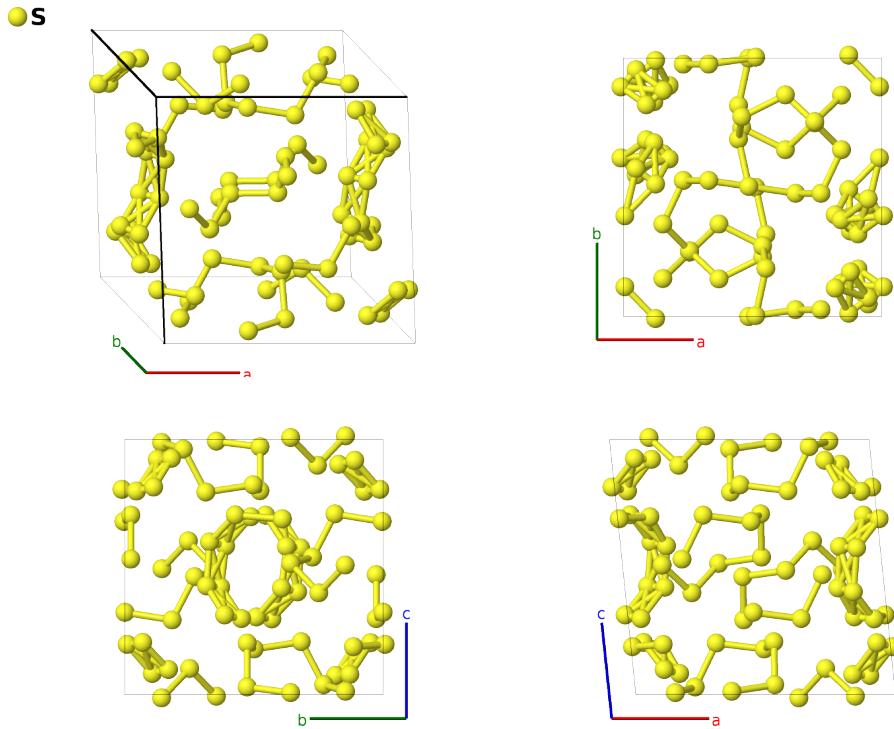
β -monoclinic Sulfur Structure:

A_mP64_14_16e-002

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<https://aflow.org/p/AYZW>

https://aflow.org/p/A_mP64_14_16e-002



Prototype

S

AFLOW prototype label

A_mP64_14_16e-002

ICSD

870

Pearson symbol

mP64

Space group number

14

Space group symbol

$P2_1/c$

AFLOW prototype command

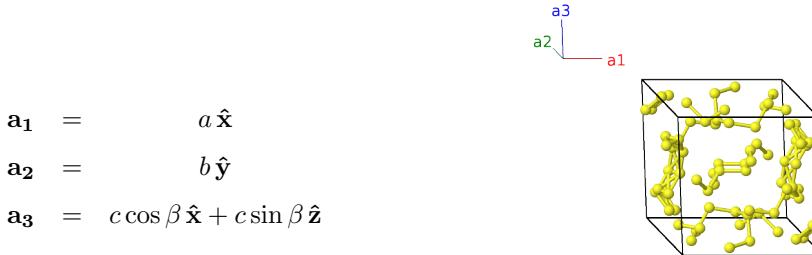
aflow --proto=A_mP64_14_16e-002

```
--params=a,b/a,c/a, $\beta$ ,x1,y1,z1,x2,y2,z2,x3,y3,z3,x4,y4,z4,x5,y5,z5,x6,y6,z6,x7,y7,z7,x8,y8,z8,x9,y9,z9,x10,y10,z10,x11,y11,z11,x12,y12,z12,x13,y13,z13,x14,y14,z14,x15,y15,z15,x16,y16,z16
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- We take the name of this structure from (Donohue, 1976). This is the high temperature phase of sulfur, stable from 95°C to the melting point at 115°C, although it can be kept at room temperatures for some time. (Templeton, 1976)
- This is a refinement of the original structure found by (Sands, 1965). There are two types of sulfur atoms in this sample:

- atoms S-I through S-VIII form stable sulfur rings with all the sites fully occupied, just as in the ground state α -S (A16).
- Atoms S-IX through S-XVI form a ring with one of two orientations, randomly chosen.
- The S-IX through S-XVI sites are thus half occupied, so there are only 48 atoms and six sulfur rings in any unit cell. Contrast this with A_k selenium, which has eight complete rings in the unit cell.
- Both A_k selenium and β -monoclinic sulfur have the same AFLOW prototype label, A_mP64_14_16e. They are generated by the same symmetry operations with different sets of parameters (`--params`) specified in their corresponding CIF files.

Simple Monoclinic primitive vectors



Basis vectors

	Lattice coordinates	Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	S I
\mathbf{B}_2	$-x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S I
\mathbf{B}_3	$-x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	S I
\mathbf{B}_4	$x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S I
\mathbf{B}_5	$x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	S II
\mathbf{B}_6	$-x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S II
\mathbf{B}_7	$-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	S II
\mathbf{B}_8	$x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S II
\mathbf{B}_9	$x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	S III
\mathbf{B}_{10}	$-x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S III
\mathbf{B}_{11}	$-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	S III
\mathbf{B}_{12}	$x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S III
\mathbf{B}_{13}	$x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	S IV
\mathbf{B}_{14}	$-x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S IV
\mathbf{B}_{15}	$-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	S IV
\mathbf{B}_{16}	$x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S IV

B₁₇	=	$x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	=	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	S V
B₁₈	=	$-x_5 \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S V
B₁₉	=	$-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	=	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	S V
B₂₀	=	$x_5 \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S V
B₂₁	=	$x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	=	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	S VI
B₂₂	=	$-x_6 \mathbf{a}_1 + (y_6 + \frac{1}{2}) \mathbf{a}_2 - (z_6 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S VI
B₂₃	=	$-x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	=	$-(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	S VI
B₂₄	=	$x_6 \mathbf{a}_1 - (y_6 - \frac{1}{2}) \mathbf{a}_2 + (z_6 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S VI
B₂₅	=	$x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3$	=	$(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}}$	(4e)	S VII
B₂₆	=	$-x_7 \mathbf{a}_1 + (y_7 + \frac{1}{2}) \mathbf{a}_2 - (z_7 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_7 + c(z_7 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S VII
B₂₇	=	$-x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3$	=	$-(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}}$	(4e)	S VII
B₂₈	=	$x_7 \mathbf{a}_1 - (y_7 - \frac{1}{2}) \mathbf{a}_2 + (z_7 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S VII
B₂₉	=	$x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3$	=	$(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}}$	(4e)	S VIII
B₃₀	=	$-x_8 \mathbf{a}_1 + (y_8 + \frac{1}{2}) \mathbf{a}_2 - (z_8 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_8 + c(z_8 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_8 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S VIII
B₃₁	=	$-x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3$	=	$-(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}}$	(4e)	S VIII
B₃₂	=	$x_8 \mathbf{a}_1 - (y_8 - \frac{1}{2}) \mathbf{a}_2 + (z_8 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_8 + c(z_8 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_8 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S VIII
B₃₃	=	$x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3$	=	$(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}}$	(4e)	S IX
B₃₄	=	$-x_9 \mathbf{a}_1 + (y_9 + \frac{1}{2}) \mathbf{a}_2 - (z_9 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_9 + c(z_9 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_9 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_9 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S IX
B₃₅	=	$-x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3$	=	$-(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}}$	(4e)	S IX
B₃₆	=	$x_9 \mathbf{a}_1 - (y_9 - \frac{1}{2}) \mathbf{a}_2 + (z_9 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_9 + c(z_9 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_9 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_9 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S IX
B₃₇	=	$x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3$	=	$(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}}$	(4e)	S X
B₃₈	=	$-x_{10} \mathbf{a}_1 + (y_{10} + \frac{1}{2}) \mathbf{a}_2 - (z_{10} - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_{10} + c(z_{10} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{10} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{10} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S X
B₃₉	=	$-x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3$	=	$-(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} - cz_{10} \sin \beta \hat{\mathbf{z}}$	(4e)	S X
B₄₀	=	$x_{10} \mathbf{a}_1 - (y_{10} - \frac{1}{2}) \mathbf{a}_2 + (z_{10} + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_{10} + c(z_{10} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{10} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{10} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S X
B₄₁	=	$x_{11} \mathbf{a}_1 + y_{11} \mathbf{a}_2 + z_{11} \mathbf{a}_3$	=	$(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} + cz_{11} \sin \beta \hat{\mathbf{z}}$	(4e)	S XI
B₄₂	=	$-x_{11} \mathbf{a}_1 + (y_{11} + \frac{1}{2}) \mathbf{a}_2 - (z_{11} - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_{11} + c(z_{11} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{11} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{11} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XI
B₄₃	=	$-x_{11} \mathbf{a}_1 - y_{11} \mathbf{a}_2 - z_{11} \mathbf{a}_3$	=	$-(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} - cz_{11} \sin \beta \hat{\mathbf{z}}$	(4e)	S XI
B₄₄	=	$x_{11} \mathbf{a}_1 - (y_{11} - \frac{1}{2}) \mathbf{a}_2 + (z_{11} + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_{11} + c(z_{11} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{11} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{11} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XI
B₄₅	=	$x_{12} \mathbf{a}_1 + y_{12} \mathbf{a}_2 + z_{12} \mathbf{a}_3$	=	$(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} + by_{12} \hat{\mathbf{y}} + cz_{12} \sin \beta \hat{\mathbf{z}}$	(4e)	S XII

B₄₆	=	$-x_{12} \mathbf{a}_1 + (y_{12} + \frac{1}{2}) \mathbf{a}_2 - (z_{12} - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_{12} + c(z_{12} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{12} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{12} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XII
B₄₇	=	$-x_{12} \mathbf{a}_1 - y_{12} \mathbf{a}_2 - z_{12} \mathbf{a}_3$	=	$-(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} - by_{12} \hat{\mathbf{y}} - cz_{12} \sin \beta \hat{\mathbf{z}}$	(4e)	S XII
B₄₈	=	$x_{12} \mathbf{a}_1 - (y_{12} - \frac{1}{2}) \mathbf{a}_2 + (z_{12} + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_{12} + c(z_{12} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{12} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{12} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XII
B₄₉	=	$x_{13} \mathbf{a}_1 + y_{13} \mathbf{a}_2 + z_{13} \mathbf{a}_3$	=	$(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + by_{13} \hat{\mathbf{y}} + cz_{13} \sin \beta \hat{\mathbf{z}}$	(4e)	S XIII
B₅₀	=	$-x_{13} \mathbf{a}_1 + (y_{13} + \frac{1}{2}) \mathbf{a}_2 - (z_{13} - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_{13} + c(z_{13} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{13} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{13} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XIII
B₅₁	=	$-x_{13} \mathbf{a}_1 - y_{13} \mathbf{a}_2 - z_{13} \mathbf{a}_3$	=	$-(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} - by_{13} \hat{\mathbf{y}} - cz_{13} \sin \beta \hat{\mathbf{z}}$	(4e)	S XIII
B₅₂	=	$x_{13} \mathbf{a}_1 - (y_{13} - \frac{1}{2}) \mathbf{a}_2 + (z_{13} + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_{13} + c(z_{13} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{13} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{13} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XIII
B₅₃	=	$x_{14} \mathbf{a}_1 + y_{14} \mathbf{a}_2 + z_{14} \mathbf{a}_3$	=	$(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} + by_{14} \hat{\mathbf{y}} + cz_{14} \sin \beta \hat{\mathbf{z}}$	(4e)	S XIV
B₅₄	=	$-x_{14} \mathbf{a}_1 + (y_{14} + \frac{1}{2}) \mathbf{a}_2 - (z_{14} - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_{14} + c(z_{14} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{14} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{14} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XIV
B₅₅	=	$-x_{14} \mathbf{a}_1 - y_{14} \mathbf{a}_2 - z_{14} \mathbf{a}_3$	=	$-(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} - by_{14} \hat{\mathbf{y}} - cz_{14} \sin \beta \hat{\mathbf{z}}$	(4e)	S XIV
B₅₆	=	$x_{14} \mathbf{a}_1 - (y_{14} - \frac{1}{2}) \mathbf{a}_2 + (z_{14} + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_{14} + c(z_{14} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{14} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{14} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XIV
B₅₇	=	$x_{15} \mathbf{a}_1 + y_{15} \mathbf{a}_2 + z_{15} \mathbf{a}_3$	=	$(ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} + by_{15} \hat{\mathbf{y}} + cz_{15} \sin \beta \hat{\mathbf{z}}$	(4e)	S XV
B₅₈	=	$-x_{15} \mathbf{a}_1 + (y_{15} + \frac{1}{2}) \mathbf{a}_2 - (z_{15} - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_{15} + c(z_{15} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{15} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{15} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XV
B₅₉	=	$-x_{15} \mathbf{a}_1 - y_{15} \mathbf{a}_2 - z_{15} \mathbf{a}_3$	=	$-(ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} - by_{15} \hat{\mathbf{y}} - cz_{15} \sin \beta \hat{\mathbf{z}}$	(4e)	S XV
B₆₀	=	$x_{15} \mathbf{a}_1 - (y_{15} - \frac{1}{2}) \mathbf{a}_2 + (z_{15} + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_{15} + c(z_{15} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{15} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{15} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XV
B₆₁	=	$x_{16} \mathbf{a}_1 + y_{16} \mathbf{a}_2 + z_{16} \mathbf{a}_3$	=	$(ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} + by_{16} \hat{\mathbf{y}} + cz_{16} \sin \beta \hat{\mathbf{z}}$	(4e)	S XVI
B₆₂	=	$-x_{16} \mathbf{a}_1 + (y_{16} + \frac{1}{2}) \mathbf{a}_2 - (z_{16} - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_{16} + c(z_{16} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{16} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{16} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XVI
B₆₃	=	$-x_{16} \mathbf{a}_1 - y_{16} \mathbf{a}_2 - z_{16} \mathbf{a}_3$	=	$-(ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} - by_{16} \hat{\mathbf{y}} - cz_{16} \sin \beta \hat{\mathbf{z}}$	(4e)	S XVI
B₆₄	=	$x_{16} \mathbf{a}_1 - (y_{16} - \frac{1}{2}) \mathbf{a}_2 + (z_{16} + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_{16} + c(z_{16} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{16} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{16} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	S XVI

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