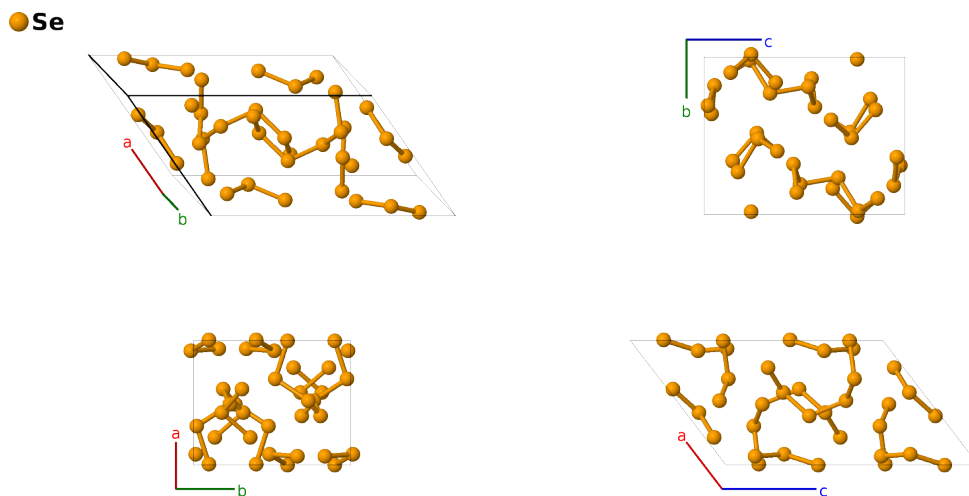


α -monoclinic Selenium Structure: A_mP32_14_8e-002

Cite this page as: H. Eckert, S. Divilov, A. Zettel, M. J. Mehl, D. Hicks, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*. In preparation.

<https://aflow.org/p/VEFR>

https://aflow.org/p/A_mP32_14_8e-002

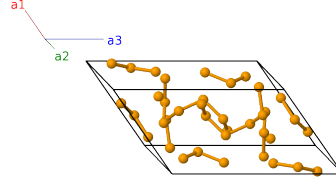


Prototype	Se
AFLOW prototype label	A_mP32_14_8e-002
ICSD	2718
Pearson symbol	mP32
Space group number	14
Space group symbol	$P2_1/c$
AFLOW prototype command	<code>aflow --proto=A_mP32_14_8e-002 --params=a, b/a, c/a, β, $x_1, y_1, z_1, x_2, y_2, z_2, x_3, y_3, z_3, x_4, y_4, z_4, x_5, y_5, z_5, x_6, y_6, z_6, x_7, y_7, z_7, x_8, y_8, z_8$</code>

- There is no consistency in the naming convention of selenium structures, and we have generally tried to avoid the Greek-letter-monoclinic form in favor of something less confusing. This structure, however, has no other name that we are aware of, so we follow (Cherin, 1972) and call it α -monoclinic selenium, a designation followed by (Donohue, 1974).
- Although this structure has the same AFLOW prototype label, A_mP32_14_e, as β -Se (A_I), the two structures are distinct. They are generated by the same symmetry operations with different sets of parameters (`--params`) specified in their corresponding CIF files.

Simple Monoclinic primitive vectors

$$\begin{aligned}
\mathbf{a}_1 &= a \hat{\mathbf{x}} \\
\mathbf{a}_2 &= b \hat{\mathbf{y}} \\
\mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}
\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$= x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Se I
\mathbf{B}_2	$= -x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se I
\mathbf{B}_3	$= -x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Se I
\mathbf{B}_4	$= x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se I
\mathbf{B}_5	$= x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	Se II
\mathbf{B}_6	$= -x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se II
\mathbf{B}_7	$= -x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	Se II
\mathbf{B}_8	$= x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se II
\mathbf{B}_9	$= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	Se III
\mathbf{B}_{10}	$= -x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se III
\mathbf{B}_{11}	$= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	Se III
\mathbf{B}_{12}	$= x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se III
\mathbf{B}_{13}	$= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	Se IV
\mathbf{B}_{14}	$= -x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se IV
\mathbf{B}_{15}	$= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	Se IV
\mathbf{B}_{16}	$= x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se IV
\mathbf{B}_{17}	$= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	Se V
\mathbf{B}_{18}	$= -x_5 \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se V
\mathbf{B}_{19}	$= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	Se V
\mathbf{B}_{20}	$= x_5 \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se V
\mathbf{B}_{21}	$= x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	Se VI
\mathbf{B}_{22}	$= -x_6 \mathbf{a}_1 + (y_6 + \frac{1}{2}) \mathbf{a}_2 - (z_6 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Se VI
\mathbf{B}_{23}	$= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	$=$	$-(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	Se VI

$$\begin{aligned}
\mathbf{B}_{24} &= x_6 \mathbf{a}_1 - \left(y_6 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_6 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} &(ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ &b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{Se VI} \\
\mathbf{B}_{25} &= x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3 = (ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}} & (4e) & \text{Se VII} \\
\mathbf{B}_{26} &= -x_7 \mathbf{a}_1 + \left(y_7 + \frac{1}{2}\right) \mathbf{a}_2 - \begin{aligned} &(z_7 - \frac{1}{2}) \mathbf{a}_3 = \\ &-(ax_7 + c(z_7 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + \\ &b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{Se VII} \\
\mathbf{B}_{27} &= -x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3 = -(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}} & (4e) & \text{Se VII} \\
\mathbf{B}_{28} &= x_7 \mathbf{a}_1 - \left(y_7 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_7 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} &(ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ &b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{Se VII} \\
\mathbf{B}_{29} &= x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3 = (ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}} & (4e) & \text{Se VIII} \\
\mathbf{B}_{30} &= -x_8 \mathbf{a}_1 + \left(y_8 + \frac{1}{2}\right) \mathbf{a}_2 - \begin{aligned} &(z_8 - \frac{1}{2}) \mathbf{a}_3 = \\ &-(ax_8 + c(z_8 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + \\ &b(y_8 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{Se VIII} \\
\mathbf{B}_{31} &= -x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3 = -(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}} & (4e) & \text{Se VIII} \\
\mathbf{B}_{32} &= x_8 \mathbf{a}_1 - \left(y_8 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_8 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} &(ax_8 + c(z_8 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ &b(y_8 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{Se VIII}
\end{aligned}$$

References

- [1] P. Cherin and P. Unger, *Refinement of the Crystal Structure of α -Monoclinic Se*, Acta Crystallogr. Sect. B **28**, 313–317 (1972), doi:10.1107/S0567740872002249.

Found in

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