

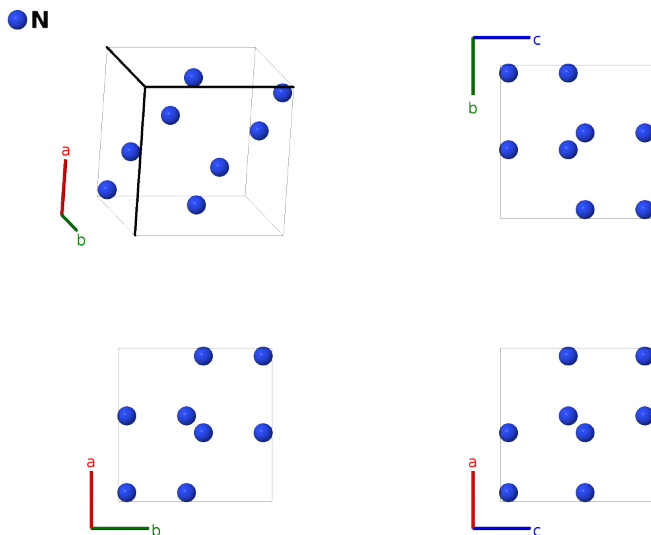
α -N ($Pa\bar{3}$) Structure: A_cP8_205_c-001

This structure originally had the label A.cP8_205.c. Calls to that address will be redirected here.

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<https://aflow.org/p/84Y3>

https://aflow.org/p/A_cP8_205_c-001



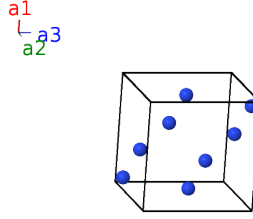
Prototype	N
AFLOW prototype label	A_cP8_205_c-001
ICSD	28179
Pearson symbol	cP8
Space group number	205
Space group symbol	$Pa\bar{3}$
AFLOW prototype command	<code>aflow --proto=A_cP8_205_c-001 --params=a, x₁</code>

- Solid nitrogen is found in three forms (Mills, 1969; Donohue, 1974):
 - The ground state α -N structure, stable below 35.6K, found either in a centrosymmetric or a non-centrosymmetric cubic structure.
 - The hexagonal β -phase, which has freely rotating N₂ molecules and is stable up to the melting point, and
 - High-pressure γ -N, stable above 355 MPa.
- There is considerable controversy about the crystal structure of α -N, as outlined in (Donohue, 1982, pp. 280-285). This page assumes the centrosymmetric $Pa\bar{3}$ #205 structure. The other possibility is the $P2_13$ #198 structure, where the N₂ dimers are offset from the inversion site. (Venables, 1974) makes a convincing case that the ground state is $Pa\bar{3}$, but we present both structures. Density Functional Theory calculations show no appreciable difference in energy between the Pa_3 and $P2_13$ structures. (Mehl, 2015)

- The ICSD entry for this structure is from (Venables, 1974).

Simple Cubic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= a \hat{\mathbf{y}} \\ \mathbf{a}_3 &= a \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates	=	Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$= x_1 \mathbf{a}_1 + x_1 \mathbf{a}_2 + x_1 \mathbf{a}_3$	=	$ax_1 \hat{\mathbf{x}} + ax_1 \hat{\mathbf{y}} + ax_1 \hat{\mathbf{z}}$	(8c)	N I
\mathbf{B}_2	$= -\left(x_1 - \frac{1}{2}\right) \mathbf{a}_1 - x_1 \mathbf{a}_2 + \left(x_1 + \frac{1}{2}\right) \mathbf{a}_3$	=	$-a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{x}} - ax_1 \hat{\mathbf{y}} + a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{z}}$	(8c)	N I
\mathbf{B}_3	$= -x_1 \mathbf{a}_1 + \left(x_1 + \frac{1}{2}\right) \mathbf{a}_2 - \left(x_1 - \frac{1}{2}\right) \mathbf{a}_3$	=	$-ax_1 \hat{\mathbf{x}} + a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{y}} - a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(8c)	N I
\mathbf{B}_4	$= \left(x_1 + \frac{1}{2}\right) \mathbf{a}_1 - \left(x_1 - \frac{1}{2}\right) \mathbf{a}_2 - x_1 \mathbf{a}_3$	=	$a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{x}} - a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{y}} - ax_1 \hat{\mathbf{z}}$	(8c)	N I
\mathbf{B}_5	$= -x_1 \mathbf{a}_1 - x_1 \mathbf{a}_2 - x_1 \mathbf{a}_3$	=	$-ax_1 \hat{\mathbf{x}} - ax_1 \hat{\mathbf{y}} - ax_1 \hat{\mathbf{z}}$	(8c)	N I
\mathbf{B}_6	$= \left(x_1 + \frac{1}{2}\right) \mathbf{a}_1 + x_1 \mathbf{a}_2 - \left(x_1 - \frac{1}{2}\right) \mathbf{a}_3$	=	$a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{x}} + ax_1 \hat{\mathbf{y}} - a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{z}}$	(8c)	N I
\mathbf{B}_7	$= x_1 \mathbf{a}_1 - \left(x_1 - \frac{1}{2}\right) \mathbf{a}_2 + \left(x_1 + \frac{1}{2}\right) \mathbf{a}_3$	=	$ax_1 \hat{\mathbf{x}} - a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{y}} + a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{z}}$	(8c)	N I
\mathbf{B}_8	$= -\left(x_1 - \frac{1}{2}\right) \mathbf{a}_1 + \left(x_1 + \frac{1}{2}\right) \mathbf{a}_2 + x_1 \mathbf{a}_3$	=	$-a\left(x_1 - \frac{1}{2}\right) \hat{\mathbf{x}} + a\left(x_1 + \frac{1}{2}\right) \hat{\mathbf{y}} + ax_1 \hat{\mathbf{z}}$	(8c)	N I

References

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Found in

- [1] J. Donohue, *The Structures of the Elements* (Robert E. Krieger Publishing Company, New York, 1974).