α-N ($P2_13$) Structure: A_cP8_198_2a-001

This structure originally had the label `A_cP8_198_2a`. Calls to that address will be redirected here.

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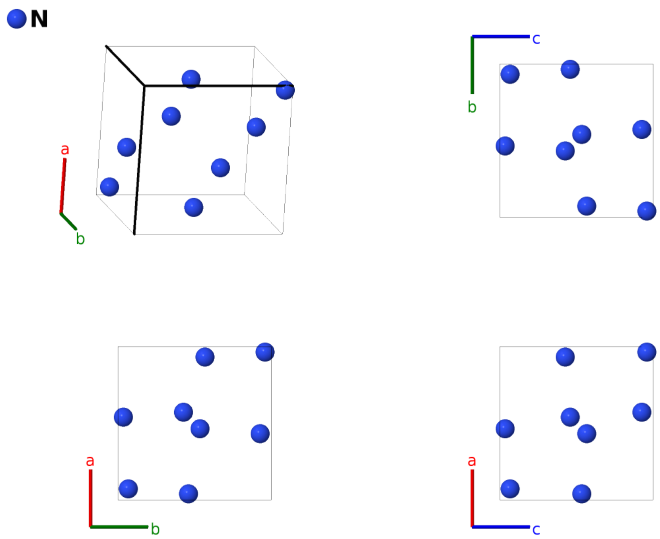
https://aflow.org/p/VHKA

https://aflow.org/p/A_cP8_198_2a-001

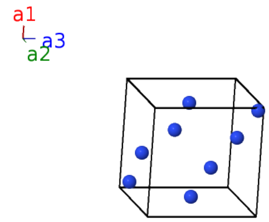


Prototype	N
AFLOW prototype label	A_cP8_198_2a-001
ICSD	27249
Pearson symbol	cP8
Space group number	198
Space group symbol	$P2_13$
AFLOW prototype command	`aflow --proto=A_cP8_198_2a-001` `--params=`a, x_1, x_2

- Solid nitrogen is found in three forms (Mills, 1969; Donohue, 1974):
  - The ground state α-N structure, stable below 35.6K, found either in a centrosymmetric or a non-centrosymmetric cubic structure.
  - The hexagonal β-phase, which has freely rotating N_2 molecules and is stable up to the melting point, and
  - High-pressure γ-N, stable above 355 MPa.
- There is considerable controversy about the crystal structure of α-N, as outlined in (Donohue, 1982, pp. 280-285). This page assumes the non-centrosymmetric $P2_13$ #198 structure. The other possibility is the $Pa\overline{3}$ #205 structure, where the N_2 dimers are centered on an inversion site. (Venables, 1974) makes a convincing case that the ground state is $Pa\overline{3}$, but we present both structures. Density Functional Theory calculations show no appreciable difference in energy between the Pa_3 and $P2_13$ structures. (Mehl, 2015)

Simple Cubic primitive vectors

$$\mathbf{a_1} = a\,\hat{\mathbf{x}}$$
$$\mathbf{a_2} = a\,\hat{\mathbf{y}}$$
$$\mathbf{a_3} = a\,\hat{\mathbf{z}}$$



Basis vectors

		Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B_1}$	=	$x_1\,\mathbf{a}_1 + x_1\,\mathbf{a}_2 + x_1\,\mathbf{a}_3$	=	$ax_1\,\hat{\mathbf{x}} + ax_1\,\hat{\mathbf{y}} + ax_1\,\hat{\mathbf{z}}$	(4a)	N I
$\mathbf{B_2}$	=	$-\left(x_1 - \frac{1}{2}\right)\,\mathbf{a}_1 - x_1\,\mathbf{a}_2 + \left(x_1 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$-a\left(x_1 - \frac{1}{2}\right)\,\hat{\mathbf{x}} - ax_1\,\hat{\mathbf{y}} + a\left(x_1 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4a)	N I
$\mathbf{B_3}$	=	$-x_1\,\mathbf{a}_1 + \left(x_1 + \frac{1}{2}\right)\,\mathbf{a}_2 - \left(x_1 - \frac{1}{2}\right)\,\mathbf{a}_3$	=	$-ax_1\,\hat{\mathbf{x}} + a\left(x_1 + \frac{1}{2}\right)\,\hat{\mathbf{y}} - a\left(x_1 - \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4a)	N I
$\mathbf{B_4}$	=	$\left(x_1 + \frac{1}{2}\right)\,\mathbf{a}_1 - \left(x_1 - \frac{1}{2}\right)\,\mathbf{a}_2 - x_1\,\mathbf{a}_3$	=	$a\left(x_1 + \frac{1}{2}\right)\,\hat{\mathbf{x}} - a\left(x_1 - \frac{1}{2}\right)\,\hat{\mathbf{y}} - ax_1\,\hat{\mathbf{z}}$	(4a)	N I
$\mathbf{B_5}$	=	$x_2\,\mathbf{a}_1 + x_2\,\mathbf{a}_2 + x_2\,\mathbf{a}_3$	=	$ax_2\,\hat{\mathbf{x}} + ax_2\,\hat{\mathbf{y}} + ax_2\,\hat{\mathbf{z}}$	(4a)	N II
$\mathbf{B_6}$	=	$-\left(x_2 - \frac{1}{2}\right)\,\mathbf{a}_1 - x_2\,\mathbf{a}_2 + \left(x_2 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$-a\left(x_2 - \frac{1}{2}\right)\,\hat{\mathbf{x}} - ax_2\,\hat{\mathbf{y}} + a\left(x_2 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4a)	N II
$\mathbf{B_7}$	=	$-x_2\,\mathbf{a}_1 + \left(x_2 + \frac{1}{2}\right)\,\mathbf{a}_2 - \left(x_2 - \frac{1}{2}\right)\,\mathbf{a}_3$	=	$-ax_2\,\hat{\mathbf{x}} + a\left(x_2 + \frac{1}{2}\right)\,\hat{\mathbf{y}} - a\left(x_2 - \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4a)	N II
$\mathbf{B_8}$	=	$\left(x_2 + \frac{1}{2}\right)\,\mathbf{a}_1 - \left(x_2 - \frac{1}{2}\right)\,\mathbf{a}_2 - x_2\,\mathbf{a}_3$	=	$a\left(x_2 + \frac{1}{2}\right)\,\hat{\mathbf{x}} - a\left(x_2 - \frac{1}{2}\right)\,\hat{\mathbf{y}} - ax_2\,\hat{\mathbf{z}}$	(4a)	N II

References

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Found in

[1] J. Donohue, *The Structures of the Elements* (Robert E. Krieger Publishing Company, New York, 1974).