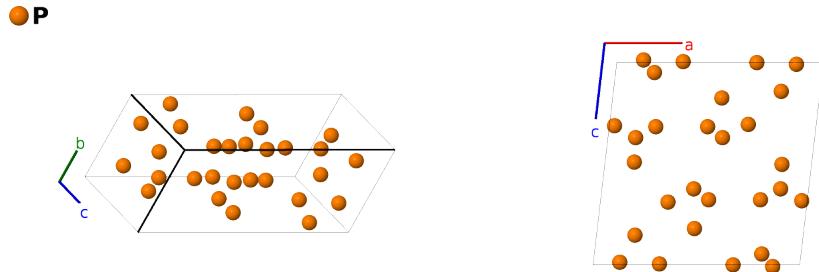


Low Temperature “White” Phosphorous Structure: A_aP24_2_12i-001

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<https://aflow.org/p/YLP3>

https://aflow.org/p/A_aP24_2_12i-001



Prototype

P

AFLOW prototype label

A_aP24_2_12i-001

ICSD

68326

Pearson symbol

aP24

Space group number

2

Space group symbol

$P\bar{1}$

AFLOW prototype command

```
aflow --proto=A_aP24_2_12i-001  
--params=a,b/a,c/a, $\alpha$ , $\beta$ , $\gamma$ ,x1,y1,z1,x2,y2,z2,x3,y3,z3,x4,y4,z4,x5,y5,z5,x6,y6,  
z6,x7,y7,z7,x8,y8,z8,x9,y9,z9,x10,y10,z10,x11,y11,z11,x12,y12,z12
```

- Phosphorus is found in at least three forms:

- Black phosphorus, *Strukturbericht A17*,
 - Monoclinic Hittorf’s phosphorus, and
 - Low temperature triclinic “white” phosphorus, stable below 197K. (this structure)

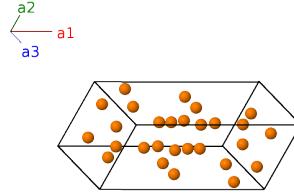
- We use the data taken at 162K.

- The P₄ molecules exhibit considerable rigid-body motion, both rotational and translational (Simon, 1987).

- There is considerable disagreement about the name of this structure. Most authors refer to it as β -white phosphorous, but (Donohue, 1982) refers to it as α -white phosphorous. Other authors refer to this as yellow phosphorous. Simply referring to this as low temperature phosphorous seems the easiest way to avoid confusion.

Triclinic primitive vectors

$$\begin{aligned}
 \mathbf{a}_1 &= a \hat{\mathbf{x}} \\
 \mathbf{a}_2 &= b \cos \gamma \hat{\mathbf{x}} + b \sin \gamma \hat{\mathbf{y}} \\
 \mathbf{a}_3 &= c_x \hat{\mathbf{x}} + c_y \hat{\mathbf{y}} + c_z \hat{\mathbf{z}} \\
 c_x &= c \cos \beta \\
 c_y &= c(\cos \alpha - \cos \beta \cos \gamma) / \sin \gamma \\
 c_z &= \sqrt{c^2 - c_x^2 - c_y^2}
 \end{aligned}$$



Basis vectors

	Lattice coordinates	=	Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	=	$(ax_1 + by_1 \cos \gamma + c_x z_1) \hat{\mathbf{x}} + (by_1 \sin \gamma + c_y z_1) \hat{\mathbf{y}} + c_z z_1 \hat{\mathbf{z}}$	(2i)	P I
\mathbf{B}_2	$-x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	=	$-(ax_1 + by_1 \cos \gamma + c_x z_1) \hat{\mathbf{x}} - (by_1 \sin \gamma + c_y z_1) \hat{\mathbf{y}} - c_z z_1 \hat{\mathbf{z}}$	(2i)	P I
\mathbf{B}_3	$x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	=	$(ax_2 + by_2 \cos \gamma + c_x z_2) \hat{\mathbf{x}} + (by_2 \sin \gamma + c_y z_2) \hat{\mathbf{y}} + c_z z_2 \hat{\mathbf{z}}$	(2i)	P II
\mathbf{B}_4	$-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	=	$-(ax_2 + by_2 \cos \gamma + c_x z_2) \hat{\mathbf{x}} - (by_2 \sin \gamma + c_y z_2) \hat{\mathbf{y}} - c_z z_2 \hat{\mathbf{z}}$	(2i)	P II
\mathbf{B}_5	$x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	=	$(ax_3 + by_3 \cos \gamma + c_x z_3) \hat{\mathbf{x}} + (by_3 \sin \gamma + c_y z_3) \hat{\mathbf{y}} + c_z z_3 \hat{\mathbf{z}}$	(2i)	P III
\mathbf{B}_6	$-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	=	$-(ax_3 + by_3 \cos \gamma + c_x z_3) \hat{\mathbf{x}} - (by_3 \sin \gamma + c_y z_3) \hat{\mathbf{y}} - c_z z_3 \hat{\mathbf{z}}$	(2i)	P III
\mathbf{B}_7	$x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	=	$(ax_4 + by_4 \cos \gamma + c_x z_4) \hat{\mathbf{x}} + (by_4 \sin \gamma + c_y z_4) \hat{\mathbf{y}} + c_z z_4 \hat{\mathbf{z}}$	(2i)	P IV
\mathbf{B}_8	$-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	=	$-(ax_4 + by_4 \cos \gamma + c_x z_4) \hat{\mathbf{x}} - (by_4 \sin \gamma + c_y z_4) \hat{\mathbf{y}} - c_z z_4 \hat{\mathbf{z}}$	(2i)	P IV
\mathbf{B}_9	$x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	=	$(ax_5 + by_5 \cos \gamma + c_x z_5) \hat{\mathbf{x}} + (by_5 \sin \gamma + c_y z_5) \hat{\mathbf{y}} + c_z z_5 \hat{\mathbf{z}}$	(2i)	P V
\mathbf{B}_{10}	$-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	=	$-(ax_5 + by_5 \cos \gamma + c_x z_5) \hat{\mathbf{x}} - (by_5 \sin \gamma + c_y z_5) \hat{\mathbf{y}} - c_z z_5 \hat{\mathbf{z}}$	(2i)	P V
\mathbf{B}_{11}	$x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	=	$(ax_6 + by_6 \cos \gamma + c_x z_6) \hat{\mathbf{x}} + (by_6 \sin \gamma + c_y z_6) \hat{\mathbf{y}} + c_z z_6 \hat{\mathbf{z}}$	(2i)	P VI
\mathbf{B}_{12}	$-x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	=	$-(ax_6 + by_6 \cos \gamma + c_x z_6) \hat{\mathbf{x}} - (by_6 \sin \gamma + c_y z_6) \hat{\mathbf{y}} - c_z z_6 \hat{\mathbf{z}}$	(2i)	P VI
\mathbf{B}_{13}	$x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3$	=	$(ax_7 + by_7 \cos \gamma + c_x z_7) \hat{\mathbf{x}} + (by_7 \sin \gamma + c_y z_7) \hat{\mathbf{y}} + c_z z_7 \hat{\mathbf{z}}$	(2i)	P VII
\mathbf{B}_{14}	$-x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3$	=	$-(ax_7 + by_7 \cos \gamma + c_x z_7) \hat{\mathbf{x}} - (by_7 \sin \gamma + c_y z_7) \hat{\mathbf{y}} - c_z z_7 \hat{\mathbf{z}}$	(2i)	P VII
\mathbf{B}_{15}	$x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3$	=	$(ax_8 + by_8 \cos \gamma + c_x z_8) \hat{\mathbf{x}} + (by_8 \sin \gamma + c_y z_8) \hat{\mathbf{y}} + c_z z_8 \hat{\mathbf{z}}$	(2i)	P VIII

B₁₆	=	$-x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3$	=	$-(ax_8 + by_8 \cos \gamma + c_x z_8) \hat{\mathbf{x}} - (by_8 \sin \gamma + c_y z_8) \hat{\mathbf{y}} - c_z z_8 \hat{\mathbf{z}}$	(2i)	P VIII
B₁₇	=	$x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3$	=	$(ax_9 + by_9 \cos \gamma + c_x z_9) \hat{\mathbf{x}} + (by_9 \sin \gamma + c_y z_9) \hat{\mathbf{y}} + c_z z_9 \hat{\mathbf{z}}$	(2i)	P IX
B₁₈	=	$-x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3$	=	$-(ax_9 + by_9 \cos \gamma + c_x z_9) \hat{\mathbf{x}} - (by_9 \sin \gamma + c_y z_9) \hat{\mathbf{y}} - c_z z_9 \hat{\mathbf{z}}$	(2i)	P IX
B₁₉	=	$x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3$	=	$(ax_{10} + by_{10} \cos \gamma + c_x z_{10}) \hat{\mathbf{x}} + (by_{10} \sin \gamma + c_y z_{10}) \hat{\mathbf{y}} + c_z z_{10} \hat{\mathbf{z}}$	(2i)	P X
B₂₀	=	$-x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3$	=	$-(ax_{10} + by_{10} \cos \gamma + c_x z_{10}) \hat{\mathbf{x}} - (by_{10} \sin \gamma + c_y z_{10}) \hat{\mathbf{y}} - c_z z_{10} \hat{\mathbf{z}}$	(2i)	P X
B₂₁	=	$x_{11} \mathbf{a}_1 + y_{11} \mathbf{a}_2 + z_{11} \mathbf{a}_3$	=	$(ax_{11} + by_{11} \cos \gamma + c_x z_{11}) \hat{\mathbf{x}} + (by_{11} \sin \gamma + c_y z_{11}) \hat{\mathbf{y}} + c_z z_{11} \hat{\mathbf{z}}$	(2i)	P XI
B₂₂	=	$-x_{11} \mathbf{a}_1 - y_{11} \mathbf{a}_2 - z_{11} \mathbf{a}_3$	=	$-(ax_{11} + by_{11} \cos \gamma + c_x z_{11}) \hat{\mathbf{x}} - (by_{11} \sin \gamma + c_y z_{11}) \hat{\mathbf{y}} - c_z z_{11} \hat{\mathbf{z}}$	(2i)	P XI
B₂₃	=	$x_{12} \mathbf{a}_1 + y_{12} \mathbf{a}_2 + z_{12} \mathbf{a}_3$	=	$(ax_{12} + by_{12} \cos \gamma + c_x z_{12}) \hat{\mathbf{x}} + (by_{12} \sin \gamma + c_y z_{12}) \hat{\mathbf{y}} + c_z z_{12} \hat{\mathbf{z}}$	(2i)	P XII
B₂₄	=	$-x_{12} \mathbf{a}_1 - y_{12} \mathbf{a}_2 - z_{12} \mathbf{a}_3$	=	$-(ax_{12} + by_{12} \cos \gamma + c_x z_{12}) \hat{\mathbf{x}} - (by_{12} \sin \gamma + c_y z_{12}) \hat{\mathbf{y}} - c_z z_{12} \hat{\mathbf{z}}$	(2i)	P XII

References

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- [2] J. Donohue, *The Structures of the Elements* (Robert E. Krieger Publishing Company, Malabar, Florida, 1982). Reprint of the 1974 John Wiley & Sons edition.