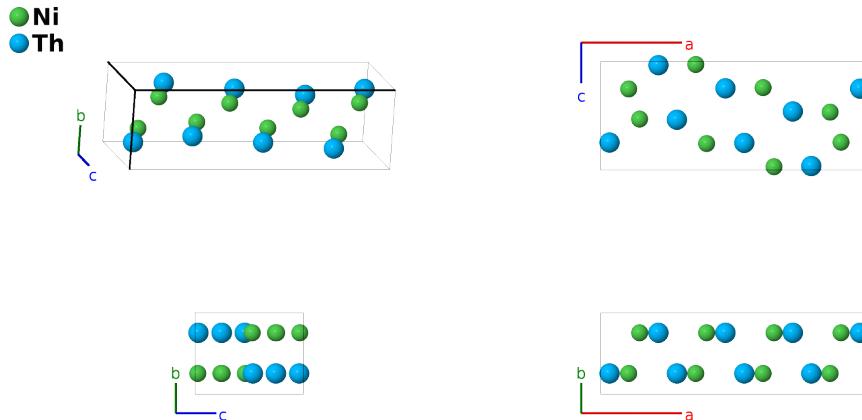


ThNi Structure: AB_oP16_62_2c_2c-002

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<https://aflow.org/p/QLCJ>

https://aflow.org/p/AB_oP16_62_2c_2c-002

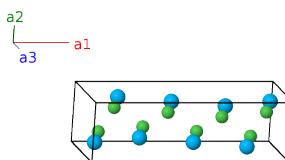


Prototype	NiTh
AFLOW prototype label	AB_oP16_62_2c_2c-002
ICSD	105403
Pearson symbol	oP16
Space group number	62
Space group symbol	$Pnma$
AFLOW prototype command	<code>aflow --proto=AB_oP16_62_2c_2c-002 --params=a, b/a, c/a, x1, z1, x2, z2, x3, z3, x4, z4</code>

Other compounds with this structure
AgSr

Simple Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates	=	Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$x_1 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_1 \mathbf{a}_3$	=	$a x_1 \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + c z_1 \hat{\mathbf{z}}$	(4c)	Ni I
\mathbf{B}_2	$-(x_1 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	=	$-a(x_1 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Ni I
\mathbf{B}_3	$-x_1 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_1 \mathbf{a}_3$	=	$-a x_1 \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - c z_1 \hat{\mathbf{z}}$	(4c)	Ni I
\mathbf{B}_4	$(x_1 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	=	$a(x_1 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Ni I
\mathbf{B}_5	$x_2 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_2 \mathbf{a}_3$	=	$a x_2 \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + c z_2 \hat{\mathbf{z}}$	(4c)	Ni II
\mathbf{B}_6	$-(x_2 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	=	$-a(x_2 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Ni II
\mathbf{B}_7	$-x_2 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_2 \mathbf{a}_3$	=	$-a x_2 \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - c z_2 \hat{\mathbf{z}}$	(4c)	Ni II
\mathbf{B}_8	$(x_2 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	=	$a(x_2 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Ni II
\mathbf{B}_9	$x_3 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_3 \mathbf{a}_3$	=	$a x_3 \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + c z_3 \hat{\mathbf{z}}$	(4c)	Th I
\mathbf{B}_{10}	$-(x_3 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	=	$-a(x_3 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Th I
\mathbf{B}_{11}	$-x_3 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_3 \mathbf{a}_3$	=	$-a x_3 \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - c z_3 \hat{\mathbf{z}}$	(4c)	Th I
\mathbf{B}_{12}	$(x_3 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	=	$a(x_3 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Th I
\mathbf{B}_{13}	$x_4 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_4 \mathbf{a}_3$	=	$a x_4 \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + c z_4 \hat{\mathbf{z}}$	(4c)	Th II
\mathbf{B}_{14}	$-(x_4 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	=	$-a(x_4 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Th II
\mathbf{B}_{15}	$-x_4 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_4 \mathbf{a}_3$	=	$-a x_4 \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - c z_4 \hat{\mathbf{z}}$	(4c)	Th II
\mathbf{B}_{16}	$(x_4 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	=	$a(x_4 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \hat{\mathbf{z}}$	(4c)	Th II

References

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