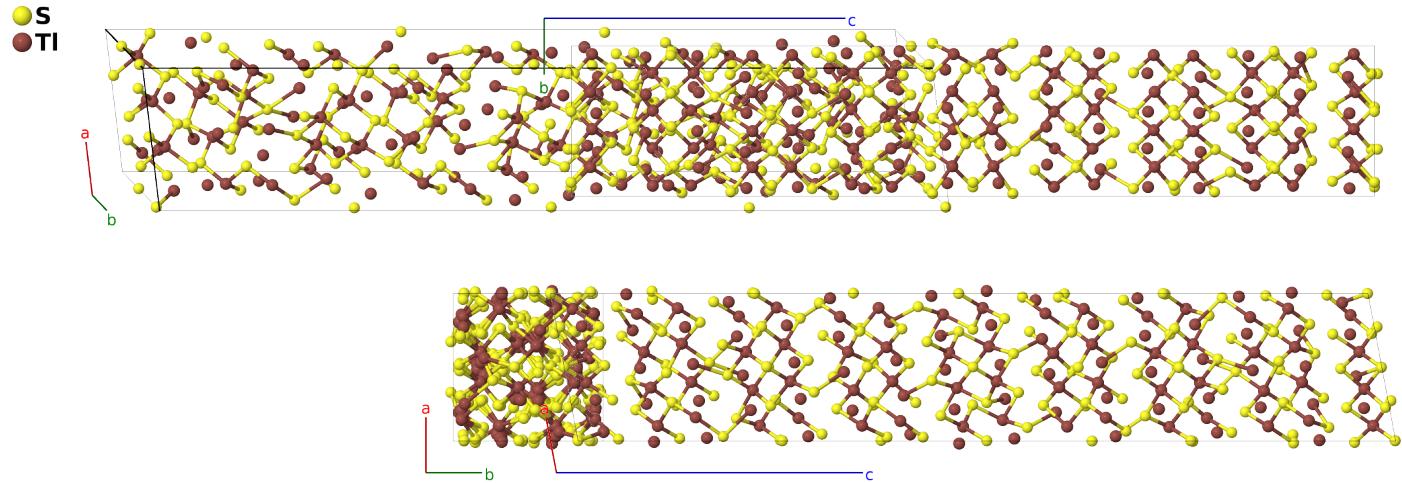


High Temperature Monoclinic TlS Structure: AB_mC₂₅₆.5_2a2b30c_32c-001

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<https://aflow.org/p/J6WY>

https://aflow.org/p/AB_mC256_5_2a2b30c_32c-001



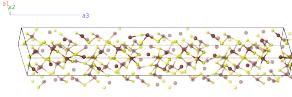
Prototype	STl
AFLOW prototype label	AB_mC256_5_2a2b30c_32c-001
ICSD	74446
Pearson symbol	mC256
Space group number	5
Space group symbol	C2
AFLOW prototype command	<pre>aflow --proto=AB_mC256_5_2a2b30c_32c-001 --params=a,b/a,c/a,β,y1,y2,y3,y4,x5,y5,z5,x6,y6,z6,x7,y7,z7,x8,y8,z8,x9,y9,z9, x10,y10,z10,x11,y11,z11,x12,y12,z12,x13,y13,z13,x14,y14,z14,x15,y15,z15,x16,y16,z16,x17, y17,z17,x18,y18,z18,x19,y19,z19,x20,y20,z20,x21,y21,z21,x22,y22,z22,x23,y23,z23,x24,y24, z24,x25,y25,z25,x26,y26,z26,x27,y27,z27,x28,y28,z28,x29,y29,z29,x30,y30,z30,x31,y31,z31, x32,y32,z32,x33,y33,z33,x34,y34,z34,x35,y35,z35,x36,y36,z36,x37,y37,z37,x38,y38,z38,x39, y39,z39,x40,y40,z40,x41,y41,z41,x42,y42,z42,x43,y43,z43,x44,y44,z44,x45,y45,z45,x46,y46, z46,x47,y47,z47,x48,y48,z48,x49,y49,z49,x50,y50,z50,x51,y51,z51,x52,y52,z52,x53,y53,z53, x54,y54,z54,x55,y55,z55,x56,y56,z56,x57,y57,z57,x58,y58,z58,x59,y59,z59,x60,y60,z60,x61, y61,z61,x62,y62,z62,x63,y63,z63,x64,y64,z64,x65,y65,z65,x66,y66,z66</pre>

- TlS occurs naturally in three forms (Villars, 2018):
 - The ground state is tetragonal in the TlSe (*B37*) structure which (Villars, 2018) calls “Tet-I” and (Kishida, 1994) calls “Type I.”
 - An intermediate tetragonal structure, which (Villars, 2018) calls “Tetragonal II,” and (Kashida, 1994) calls Type III.
 - A high temperature monoclinic structure, called “Mon” by (Villars, 2018) and “Type II” by (Kishida, 1994). (this structure)

- If we replaced the conventional cell primitive vector \mathbf{a}_3 used by (Nakamura, 1993) with $\mathbf{a}'_3 = \mathbf{a}_1 + \mathbf{a}_3$ both the conventional and primitive cells would be very close to tetragonal cells.

Base-centered Monoclinic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a\hat{\mathbf{x}} - \frac{1}{2}b\hat{\mathbf{y}} \\ \mathbf{a}_2 &= \frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}b\hat{\mathbf{y}} \\ \mathbf{a}_3 &= c\cos\beta\hat{\mathbf{x}} + c\sin\beta\hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates	Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$-y_1 \mathbf{a}_1 + y_1 \mathbf{a}_2$	$b y_1 \hat{\mathbf{y}}$	(2a)	S I
\mathbf{B}_2	$-y_2 \mathbf{a}_1 + y_2 \mathbf{a}_2$	$b y_2 \hat{\mathbf{y}}$	(2a)	S II
\mathbf{B}_3	$-y_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$\frac{1}{2}c \cos\beta \hat{\mathbf{x}} + b y_3 \hat{\mathbf{y}} + \frac{1}{2}c \sin\beta \hat{\mathbf{z}}$	(2b)	S III
\mathbf{B}_4	$-y_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$\frac{1}{2}c \cos\beta \hat{\mathbf{x}} + b y_4 \hat{\mathbf{y}} + \frac{1}{2}c \sin\beta \hat{\mathbf{z}}$	(2b)	S IV
\mathbf{B}_5	$(x_5 - y_5) \mathbf{a}_1 + (x_5 + y_5) \mathbf{a}_2 + z_5 \mathbf{a}_3$	$(ax_5 + cz_5 \cos\beta) \hat{\mathbf{x}} + b y_5 \hat{\mathbf{y}} + cz_5 \sin\beta \hat{\mathbf{z}}$	(4c)	S V
\mathbf{B}_6	$-(x_5 + y_5) \mathbf{a}_1 - (x_5 - y_5) \mathbf{a}_2 - z_5 \mathbf{a}_3$	$-(ax_5 + cz_5 \cos\beta) \hat{\mathbf{x}} + b y_5 \hat{\mathbf{y}} - cz_5 \sin\beta \hat{\mathbf{z}}$	(4c)	S V
\mathbf{B}_7	$(x_6 - y_6) \mathbf{a}_1 + (x_6 + y_6) \mathbf{a}_2 + z_6 \mathbf{a}_3$	$(ax_6 + cz_6 \cos\beta) \hat{\mathbf{x}} + b y_6 \hat{\mathbf{y}} + cz_6 \sin\beta \hat{\mathbf{z}}$	(4c)	S VI
\mathbf{B}_8	$-(x_6 + y_6) \mathbf{a}_1 - (x_6 - y_6) \mathbf{a}_2 - z_6 \mathbf{a}_3$	$-(ax_6 + cz_6 \cos\beta) \hat{\mathbf{x}} + b y_6 \hat{\mathbf{y}} - cz_6 \sin\beta \hat{\mathbf{z}}$	(4c)	S VI
\mathbf{B}_9	$(x_7 - y_7) \mathbf{a}_1 + (x_7 + y_7) \mathbf{a}_2 + z_7 \mathbf{a}_3$	$(ax_7 + cz_7 \cos\beta) \hat{\mathbf{x}} + b y_7 \hat{\mathbf{y}} + cz_7 \sin\beta \hat{\mathbf{z}}$	(4c)	S VII
\mathbf{B}_{10}	$-(x_7 + y_7) \mathbf{a}_1 - (x_7 - y_7) \mathbf{a}_2 - z_7 \mathbf{a}_3$	$-(ax_7 + cz_7 \cos\beta) \hat{\mathbf{x}} + b y_7 \hat{\mathbf{y}} - cz_7 \sin\beta \hat{\mathbf{z}}$	(4c)	S VII
\mathbf{B}_{11}	$(x_8 - y_8) \mathbf{a}_1 + (x_8 + y_8) \mathbf{a}_2 + z_8 \mathbf{a}_3$	$(ax_8 + cz_8 \cos\beta) \hat{\mathbf{x}} + b y_8 \hat{\mathbf{y}} + cz_8 \sin\beta \hat{\mathbf{z}}$	(4c)	S VIII
\mathbf{B}_{12}	$-(x_8 + y_8) \mathbf{a}_1 - (x_8 - y_8) \mathbf{a}_2 - z_8 \mathbf{a}_3$	$-(ax_8 + cz_8 \cos\beta) \hat{\mathbf{x}} + b y_8 \hat{\mathbf{y}} - cz_8 \sin\beta \hat{\mathbf{z}}$	(4c)	S VIII
\mathbf{B}_{13}	$(x_9 - y_9) \mathbf{a}_1 + (x_9 + y_9) \mathbf{a}_2 + z_9 \mathbf{a}_3$	$(ax_9 + cz_9 \cos\beta) \hat{\mathbf{x}} + b y_9 \hat{\mathbf{y}} + cz_9 \sin\beta \hat{\mathbf{z}}$	(4c)	S IX
\mathbf{B}_{14}	$-(x_9 + y_9) \mathbf{a}_1 - (x_9 - y_9) \mathbf{a}_2 - z_9 \mathbf{a}_3$	$-(ax_9 + cz_9 \cos\beta) \hat{\mathbf{x}} + b y_9 \hat{\mathbf{y}} - cz_9 \sin\beta \hat{\mathbf{z}}$	(4c)	S IX
\mathbf{B}_{15}	$(x_{10} - y_{10}) \mathbf{a}_1 + (x_{10} + y_{10}) \mathbf{a}_2 + z_{10} \mathbf{a}_3$	$(ax_{10} + cz_{10} \cos\beta) \hat{\mathbf{x}} + b y_{10} \hat{\mathbf{y}} + cz_{10} \sin\beta \hat{\mathbf{z}}$	(4c)	S X
\mathbf{B}_{16}	$-(x_{10} + y_{10}) \mathbf{a}_1 - (x_{10} - y_{10}) \mathbf{a}_2 - z_{10} \mathbf{a}_3$	$-(ax_{10} + cz_{10} \cos\beta) \hat{\mathbf{x}} + b y_{10} \hat{\mathbf{y}} - cz_{10} \sin\beta \hat{\mathbf{z}}$	(4c)	S X
\mathbf{B}_{17}	$(x_{11} - y_{11}) \mathbf{a}_1 + (x_{11} + y_{11}) \mathbf{a}_2 + z_{11} \mathbf{a}_3$	$(ax_{11} + cz_{11} \cos\beta) \hat{\mathbf{x}} + b y_{11} \hat{\mathbf{y}} + cz_{11} \sin\beta \hat{\mathbf{z}}$	(4c)	S XI
\mathbf{B}_{18}	$-(x_{11} + y_{11}) \mathbf{a}_1 - (x_{11} - y_{11}) \mathbf{a}_2 - z_{11} \mathbf{a}_3$	$-(ax_{11} + cz_{11} \cos\beta) \hat{\mathbf{x}} + b y_{11} \hat{\mathbf{y}} - cz_{11} \sin\beta \hat{\mathbf{z}}$	(4c)	S XI
\mathbf{B}_{19}	$(x_{12} - y_{12}) \mathbf{a}_1 + (x_{12} + y_{12}) \mathbf{a}_2 + z_{12} \mathbf{a}_3$	$(ax_{12} + cz_{12} \cos\beta) \hat{\mathbf{x}} + b y_{12} \hat{\mathbf{y}} + cz_{12} \sin\beta \hat{\mathbf{z}}$	(4c)	S XII
\mathbf{B}_{20}	$-(x_{12} + y_{12}) \mathbf{a}_1 - (x_{12} - y_{12}) \mathbf{a}_2 - z_{12} \mathbf{a}_3$	$-(ax_{12} + cz_{12} \cos\beta) \hat{\mathbf{x}} + b y_{12} \hat{\mathbf{y}} - cz_{12} \sin\beta \hat{\mathbf{z}}$	(4c)	S XII

\mathbf{B}_{21}	$=$	$(x_{13} - y_{13}) \mathbf{a}_1 + (x_{13} + y_{13}) \mathbf{a}_2 + z_{13} \mathbf{a}_3$	$=$	$(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + by_{13} \hat{\mathbf{y}} + cz_{13} \sin \beta \hat{\mathbf{z}}$	(4c)	S XIII
\mathbf{B}_{22}	$=$	$-(x_{13} + y_{13}) \mathbf{a}_1 - (x_{13} - y_{13}) \mathbf{a}_2 - z_{13} \mathbf{a}_3$	$=$	$-(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + by_{13} \hat{\mathbf{y}} - cz_{13} \sin \beta \hat{\mathbf{z}}$	(4c)	S XIII
\mathbf{B}_{23}	$=$	$(x_{14} - y_{14}) \mathbf{a}_1 + (x_{14} + y_{14}) \mathbf{a}_2 + z_{14} \mathbf{a}_3$	$=$	$(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} + by_{14} \hat{\mathbf{y}} + cz_{14} \sin \beta \hat{\mathbf{z}}$	(4c)	S XIV
\mathbf{B}_{24}	$=$	$-(x_{14} + y_{14}) \mathbf{a}_1 - (x_{14} - y_{14}) \mathbf{a}_2 - z_{14} \mathbf{a}_3$	$=$	$-(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} + by_{14} \hat{\mathbf{y}} - cz_{14} \sin \beta \hat{\mathbf{z}}$	(4c)	S XIV
\mathbf{B}_{25}	$=$	$(x_{15} - y_{15}) \mathbf{a}_1 + (x_{15} + y_{15}) \mathbf{a}_2 + z_{15} \mathbf{a}_3$	$=$	$(ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} + by_{15} \hat{\mathbf{y}} + cz_{15} \sin \beta \hat{\mathbf{z}}$	(4c)	S XV
\mathbf{B}_{26}	$=$	$-(x_{15} + y_{15}) \mathbf{a}_1 - (x_{15} - y_{15}) \mathbf{a}_2 - z_{15} \mathbf{a}_3$	$=$	$-(ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} + by_{15} \hat{\mathbf{y}} - cz_{15} \sin \beta \hat{\mathbf{z}}$	(4c)	S XV
\mathbf{B}_{27}	$=$	$(x_{16} - y_{16}) \mathbf{a}_1 + (x_{16} + y_{16}) \mathbf{a}_2 + z_{16} \mathbf{a}_3$	$=$	$(ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} + by_{16} \hat{\mathbf{y}} + cz_{16} \sin \beta \hat{\mathbf{z}}$	(4c)	S XVI
\mathbf{B}_{28}	$=$	$-(x_{16} + y_{16}) \mathbf{a}_1 - (x_{16} - y_{16}) \mathbf{a}_2 - z_{16} \mathbf{a}_3$	$=$	$-(ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} + by_{16} \hat{\mathbf{y}} - cz_{16} \sin \beta \hat{\mathbf{z}}$	(4c)	S XVI
\mathbf{B}_{29}	$=$	$(x_{17} - y_{17}) \mathbf{a}_1 + (x_{17} + y_{17}) \mathbf{a}_2 + z_{17} \mathbf{a}_3$	$=$	$(ax_{17} + cz_{17} \cos \beta) \hat{\mathbf{x}} + by_{17} \hat{\mathbf{y}} + cz_{17} \sin \beta \hat{\mathbf{z}}$	(4c)	S XVII
\mathbf{B}_{30}	$=$	$-(x_{17} + y_{17}) \mathbf{a}_1 - (x_{17} - y_{17}) \mathbf{a}_2 - z_{17} \mathbf{a}_3$	$=$	$-(ax_{17} + cz_{17} \cos \beta) \hat{\mathbf{x}} + by_{17} \hat{\mathbf{y}} - cz_{17} \sin \beta \hat{\mathbf{z}}$	(4c)	S XVII
\mathbf{B}_{31}	$=$	$(x_{18} - y_{18}) \mathbf{a}_1 + (x_{18} + y_{18}) \mathbf{a}_2 + z_{18} \mathbf{a}_3$	$=$	$(ax_{18} + cz_{18} \cos \beta) \hat{\mathbf{x}} + by_{18} \hat{\mathbf{y}} + cz_{18} \sin \beta \hat{\mathbf{z}}$	(4c)	S XVIII
\mathbf{B}_{32}	$=$	$-(x_{18} + y_{18}) \mathbf{a}_1 - (x_{18} - y_{18}) \mathbf{a}_2 - z_{18} \mathbf{a}_3$	$=$	$-(ax_{18} + cz_{18} \cos \beta) \hat{\mathbf{x}} + by_{18} \hat{\mathbf{y}} - cz_{18} \sin \beta \hat{\mathbf{z}}$	(4c)	S XVIII
\mathbf{B}_{33}	$=$	$(x_{19} - y_{19}) \mathbf{a}_1 + (x_{19} + y_{19}) \mathbf{a}_2 + z_{19} \mathbf{a}_3$	$=$	$(ax_{19} + cz_{19} \cos \beta) \hat{\mathbf{x}} + by_{19} \hat{\mathbf{y}} + cz_{19} \sin \beta \hat{\mathbf{z}}$	(4c)	S XIX
\mathbf{B}_{34}	$=$	$-(x_{19} + y_{19}) \mathbf{a}_1 - (x_{19} - y_{19}) \mathbf{a}_2 - z_{19} \mathbf{a}_3$	$=$	$-(ax_{19} + cz_{19} \cos \beta) \hat{\mathbf{x}} + by_{19} \hat{\mathbf{y}} - cz_{19} \sin \beta \hat{\mathbf{z}}$	(4c)	S XIX
\mathbf{B}_{35}	$=$	$(x_{20} - y_{20}) \mathbf{a}_1 + (x_{20} + y_{20}) \mathbf{a}_2 + z_{20} \mathbf{a}_3$	$=$	$(ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} + by_{20} \hat{\mathbf{y}} + cz_{20} \sin \beta \hat{\mathbf{z}}$	(4c)	S XX
\mathbf{B}_{36}	$=$	$-(x_{20} + y_{20}) \mathbf{a}_1 - (x_{20} - y_{20}) \mathbf{a}_2 - z_{20} \mathbf{a}_3$	$=$	$-(ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} + by_{20} \hat{\mathbf{y}} - cz_{20} \sin \beta \hat{\mathbf{z}}$	(4c)	S XX
\mathbf{B}_{37}	$=$	$(x_{21} - y_{21}) \mathbf{a}_1 + (x_{21} + y_{21}) \mathbf{a}_2 + z_{21} \mathbf{a}_3$	$=$	$(ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} + by_{21} \hat{\mathbf{y}} + cz_{21} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXI
\mathbf{B}_{38}	$=$	$-(x_{21} + y_{21}) \mathbf{a}_1 - (x_{21} - y_{21}) \mathbf{a}_2 - z_{21} \mathbf{a}_3$	$=$	$-(ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} + by_{21} \hat{\mathbf{y}} - cz_{21} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXI
\mathbf{B}_{39}	$=$	$(x_{22} - y_{22}) \mathbf{a}_1 + (x_{22} + y_{22}) \mathbf{a}_2 + z_{22} \mathbf{a}_3$	$=$	$(ax_{22} + cz_{22} \cos \beta) \hat{\mathbf{x}} + by_{22} \hat{\mathbf{y}} + cz_{22} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXII
\mathbf{B}_{40}	$=$	$-(x_{22} + y_{22}) \mathbf{a}_1 - (x_{22} - y_{22}) \mathbf{a}_2 - z_{22} \mathbf{a}_3$	$=$	$-(ax_{22} + cz_{22} \cos \beta) \hat{\mathbf{x}} + by_{22} \hat{\mathbf{y}} - cz_{22} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXII
\mathbf{B}_{41}	$=$	$(x_{23} - y_{23}) \mathbf{a}_1 + (x_{23} + y_{23}) \mathbf{a}_2 + z_{23} \mathbf{a}_3$	$=$	$(ax_{23} + cz_{23} \cos \beta) \hat{\mathbf{x}} + by_{23} \hat{\mathbf{y}} + cz_{23} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXIII
\mathbf{B}_{42}	$=$	$-(x_{23} + y_{23}) \mathbf{a}_1 - (x_{23} - y_{23}) \mathbf{a}_2 - z_{23} \mathbf{a}_3$	$=$	$-(ax_{23} + cz_{23} \cos \beta) \hat{\mathbf{x}} + by_{23} \hat{\mathbf{y}} - cz_{23} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXIII
\mathbf{B}_{43}	$=$	$(x_{24} - y_{24}) \mathbf{a}_1 + (x_{24} + y_{24}) \mathbf{a}_2 + z_{24} \mathbf{a}_3$	$=$	$(ax_{24} + cz_{24} \cos \beta) \hat{\mathbf{x}} + by_{24} \hat{\mathbf{y}} + cz_{24} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXIV
\mathbf{B}_{44}	$=$	$-(x_{24} + y_{24}) \mathbf{a}_1 - (x_{24} - y_{24}) \mathbf{a}_2 - z_{24} \mathbf{a}_3$	$=$	$-(ax_{24} + cz_{24} \cos \beta) \hat{\mathbf{x}} + by_{24} \hat{\mathbf{y}} - cz_{24} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXIV

B₄₅	$(x_{25} - y_{25}) \mathbf{a}_1 + (x_{25} + y_{25}) \mathbf{a}_2 + z_{25} \mathbf{a}_3$	$= (ax_{25} + cz_{25} \cos \beta) \hat{\mathbf{x}} + by_{25} \hat{\mathbf{y}} + cz_{25} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXV
B₄₆	$-(x_{25} + y_{25}) \mathbf{a}_1 - (x_{25} - y_{25}) \mathbf{a}_2 - z_{25} \mathbf{a}_3$	$= -(ax_{25} + cz_{25} \cos \beta) \hat{\mathbf{x}} + by_{25} \hat{\mathbf{y}} - cz_{25} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXV
B₄₇	$(x_{26} - y_{26}) \mathbf{a}_1 + (x_{26} + y_{26}) \mathbf{a}_2 + z_{26} \mathbf{a}_3$	$= (ax_{26} + cz_{26} \cos \beta) \hat{\mathbf{x}} + by_{26} \hat{\mathbf{y}} + cz_{26} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXVI
B₄₈	$-(x_{26} + y_{26}) \mathbf{a}_1 - (x_{26} - y_{26}) \mathbf{a}_2 - z_{26} \mathbf{a}_3$	$= -(ax_{26} + cz_{26} \cos \beta) \hat{\mathbf{x}} + by_{26} \hat{\mathbf{y}} - cz_{26} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXVI
B₄₉	$(x_{27} - y_{27}) \mathbf{a}_1 + (x_{27} + y_{27}) \mathbf{a}_2 + z_{27} \mathbf{a}_3$	$= (ax_{27} + cz_{27} \cos \beta) \hat{\mathbf{x}} + by_{27} \hat{\mathbf{y}} + cz_{27} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXVII
B₅₀	$-(x_{27} + y_{27}) \mathbf{a}_1 - (x_{27} - y_{27}) \mathbf{a}_2 - z_{27} \mathbf{a}_3$	$= -(ax_{27} + cz_{27} \cos \beta) \hat{\mathbf{x}} + by_{27} \hat{\mathbf{y}} - cz_{27} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXVII
B₅₁	$(x_{28} - y_{28}) \mathbf{a}_1 + (x_{28} + y_{28}) \mathbf{a}_2 + z_{28} \mathbf{a}_3$	$= (ax_{28} + cz_{28} \cos \beta) \hat{\mathbf{x}} + by_{28} \hat{\mathbf{y}} + cz_{28} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXVIII
B₅₂	$-(x_{28} + y_{28}) \mathbf{a}_1 - (x_{28} - y_{28}) \mathbf{a}_2 - z_{28} \mathbf{a}_3$	$= -(ax_{28} + cz_{28} \cos \beta) \hat{\mathbf{x}} + by_{28} \hat{\mathbf{y}} - cz_{28} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXVIII
B₅₃	$(x_{29} - y_{29}) \mathbf{a}_1 + (x_{29} + y_{29}) \mathbf{a}_2 + z_{29} \mathbf{a}_3$	$= (ax_{29} + cz_{29} \cos \beta) \hat{\mathbf{x}} + by_{29} \hat{\mathbf{y}} + cz_{29} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXIX
B₅₄	$-(x_{29} + y_{29}) \mathbf{a}_1 - (x_{29} - y_{29}) \mathbf{a}_2 - z_{29} \mathbf{a}_3$	$= -(ax_{29} + cz_{29} \cos \beta) \hat{\mathbf{x}} + by_{29} \hat{\mathbf{y}} - cz_{29} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXIX
B₅₅	$(x_{30} - y_{30}) \mathbf{a}_1 + (x_{30} + y_{30}) \mathbf{a}_2 + z_{30} \mathbf{a}_3$	$= (ax_{30} + cz_{30} \cos \beta) \hat{\mathbf{x}} + by_{30} \hat{\mathbf{y}} + cz_{30} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXX
B₅₆	$-(x_{30} + y_{30}) \mathbf{a}_1 - (x_{30} - y_{30}) \mathbf{a}_2 - z_{30} \mathbf{a}_3$	$= -(ax_{30} + cz_{30} \cos \beta) \hat{\mathbf{x}} + by_{30} \hat{\mathbf{y}} - cz_{30} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXX
B₅₇	$(x_{31} - y_{31}) \mathbf{a}_1 + (x_{31} + y_{31}) \mathbf{a}_2 + z_{31} \mathbf{a}_3$	$= (ax_{31} + cz_{31} \cos \beta) \hat{\mathbf{x}} + by_{31} \hat{\mathbf{y}} + cz_{31} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXXI
B₅₈	$-(x_{31} + y_{31}) \mathbf{a}_1 - (x_{31} - y_{31}) \mathbf{a}_2 - z_{31} \mathbf{a}_3$	$= -(ax_{31} + cz_{31} \cos \beta) \hat{\mathbf{x}} + by_{31} \hat{\mathbf{y}} - cz_{31} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXXI
B₅₉	$(x_{32} - y_{32}) \mathbf{a}_1 + (x_{32} + y_{32}) \mathbf{a}_2 + z_{32} \mathbf{a}_3$	$= (ax_{32} + cz_{32} \cos \beta) \hat{\mathbf{x}} + by_{32} \hat{\mathbf{y}} + cz_{32} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXXII
B₆₀	$-(x_{32} + y_{32}) \mathbf{a}_1 - (x_{32} - y_{32}) \mathbf{a}_2 - z_{32} \mathbf{a}_3$	$= -(ax_{32} + cz_{32} \cos \beta) \hat{\mathbf{x}} + by_{32} \hat{\mathbf{y}} - cz_{32} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXXII
B₆₁	$(x_{33} - y_{33}) \mathbf{a}_1 + (x_{33} + y_{33}) \mathbf{a}_2 + z_{33} \mathbf{a}_3$	$= (ax_{33} + cz_{33} \cos \beta) \hat{\mathbf{x}} + by_{33} \hat{\mathbf{y}} + cz_{33} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXXIII
B₆₂	$-(x_{33} + y_{33}) \mathbf{a}_1 - (x_{33} - y_{33}) \mathbf{a}_2 - z_{33} \mathbf{a}_3$	$= -(ax_{33} + cz_{33} \cos \beta) \hat{\mathbf{x}} + by_{33} \hat{\mathbf{y}} - cz_{33} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXXIII
B₆₃	$(x_{34} - y_{34}) \mathbf{a}_1 + (x_{34} + y_{34}) \mathbf{a}_2 + z_{34} \mathbf{a}_3$	$= (ax_{34} + cz_{34} \cos \beta) \hat{\mathbf{x}} + by_{34} \hat{\mathbf{y}} + cz_{34} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXXIV
B₆₄	$-(x_{34} + y_{34}) \mathbf{a}_1 - (x_{34} - y_{34}) \mathbf{a}_2 - z_{34} \mathbf{a}_3$	$= -(ax_{34} + cz_{34} \cos \beta) \hat{\mathbf{x}} + by_{34} \hat{\mathbf{y}} - cz_{34} \sin \beta \hat{\mathbf{z}}$	(4c)	S XXXIV
B₆₅	$(x_{35} - y_{35}) \mathbf{a}_1 + (x_{35} + y_{35}) \mathbf{a}_2 + z_{35} \mathbf{a}_3$	$= (ax_{35} + cz_{35} \cos \beta) \hat{\mathbf{x}} + by_{35} \hat{\mathbf{y}} + cz_{35} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl I
B₆₆	$-(x_{35} + y_{35}) \mathbf{a}_1 - (x_{35} - y_{35}) \mathbf{a}_2 - z_{35} \mathbf{a}_3$	$= -(ax_{35} + cz_{35} \cos \beta) \hat{\mathbf{x}} + by_{35} \hat{\mathbf{y}} - cz_{35} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl I
B₆₇	$(x_{36} - y_{36}) \mathbf{a}_1 + (x_{36} + y_{36}) \mathbf{a}_2 + z_{36} \mathbf{a}_3$	$= (ax_{36} + cz_{36} \cos \beta) \hat{\mathbf{x}} + by_{36} \hat{\mathbf{y}} + cz_{36} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl II
B₆₈	$-(x_{36} + y_{36}) \mathbf{a}_1 - (x_{36} - y_{36}) \mathbf{a}_2 - z_{36} \mathbf{a}_3$	$= -(ax_{36} + cz_{36} \cos \beta) \hat{\mathbf{x}} + by_{36} \hat{\mathbf{y}} - cz_{36} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl II

$\mathbf{B}_{69} =$	$(x_{37} - y_{37}) \mathbf{a}_1 +$	$= (ax_{37} + cz_{37} \cos \beta) \hat{\mathbf{x}} + by_{37} \hat{\mathbf{y}} + cz_{37} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl III
$\mathbf{B}_{70} =$	$-(x_{37} + y_{37}) \mathbf{a}_1 -$	$= -(ax_{37} + cz_{37} \cos \beta) \hat{\mathbf{x}} + by_{37} \hat{\mathbf{y}} -$	(4c)	Tl III
$\mathbf{B}_{71} =$	$(x_{38} - y_{38}) \mathbf{a}_1 +$	$= (ax_{38} + cz_{38} \cos \beta) \hat{\mathbf{x}} + by_{38} \hat{\mathbf{y}} + cz_{38} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl IV
$\mathbf{B}_{72} =$	$-(x_{38} + y_{38}) \mathbf{a}_1 -$	$= -(ax_{38} + cz_{38} \cos \beta) \hat{\mathbf{x}} + by_{38} \hat{\mathbf{y}} -$	(4c)	Tl IV
$\mathbf{B}_{73} =$	$(x_{39} - y_{39}) \mathbf{a}_1 +$	$= (ax_{39} + cz_{39} \cos \beta) \hat{\mathbf{x}} + by_{39} \hat{\mathbf{y}} + cz_{39} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl V
$\mathbf{B}_{74} =$	$-(x_{39} + y_{39}) \mathbf{a}_1 -$	$= -(ax_{39} + cz_{39} \cos \beta) \hat{\mathbf{x}} + by_{39} \hat{\mathbf{y}} -$	(4c)	Tl V
$\mathbf{B}_{75} =$	$(x_{40} - y_{40}) \mathbf{a}_1 +$	$= (ax_{40} + cz_{40} \cos \beta) \hat{\mathbf{x}} + by_{40} \hat{\mathbf{y}} + cz_{40} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl VI
$\mathbf{B}_{76} =$	$-(x_{40} + y_{40}) \mathbf{a}_1 -$	$= -(ax_{40} + cz_{40} \cos \beta) \hat{\mathbf{x}} + by_{40} \hat{\mathbf{y}} -$	(4c)	Tl VI
$\mathbf{B}_{77} =$	$(x_{41} - y_{41}) \mathbf{a}_1 +$	$= (ax_{41} + cz_{41} \cos \beta) \hat{\mathbf{x}} + by_{41} \hat{\mathbf{y}} + cz_{41} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl VII
$\mathbf{B}_{78} =$	$-(x_{41} + y_{41}) \mathbf{a}_1 -$	$= -(ax_{41} + cz_{41} \cos \beta) \hat{\mathbf{x}} + by_{41} \hat{\mathbf{y}} -$	(4c)	Tl VII
$\mathbf{B}_{79} =$	$(x_{42} - y_{42}) \mathbf{a}_1 +$	$= (ax_{42} + cz_{42} \cos \beta) \hat{\mathbf{x}} + by_{42} \hat{\mathbf{y}} + cz_{42} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl VIII
$\mathbf{B}_{80} =$	$-(x_{42} + y_{42}) \mathbf{a}_1 -$	$= -(ax_{42} + cz_{42} \cos \beta) \hat{\mathbf{x}} + by_{42} \hat{\mathbf{y}} -$	(4c)	Tl VIII
$\mathbf{B}_{81} =$	$(x_{43} - y_{43}) \mathbf{a}_1 +$	$= (ax_{43} + cz_{43} \cos \beta) \hat{\mathbf{x}} + by_{43} \hat{\mathbf{y}} + cz_{43} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl IX
$\mathbf{B}_{82} =$	$-(x_{43} + y_{43}) \mathbf{a}_1 -$	$= -(ax_{43} + cz_{43} \cos \beta) \hat{\mathbf{x}} + by_{43} \hat{\mathbf{y}} -$	(4c)	Tl IX
$\mathbf{B}_{83} =$	$(x_{44} - y_{44}) \mathbf{a}_1 +$	$= (ax_{44} + cz_{44} \cos \beta) \hat{\mathbf{x}} + by_{44} \hat{\mathbf{y}} + cz_{44} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl X
$\mathbf{B}_{84} =$	$-(x_{44} + y_{44}) \mathbf{a}_1 -$	$= -(ax_{44} + cz_{44} \cos \beta) \hat{\mathbf{x}} + by_{44} \hat{\mathbf{y}} -$	(4c)	Tl X
$\mathbf{B}_{85} =$	$(x_{45} - y_{45}) \mathbf{a}_1 +$	$= (ax_{45} + cz_{45} \cos \beta) \hat{\mathbf{x}} + by_{45} \hat{\mathbf{y}} + cz_{45} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XI
$\mathbf{B}_{86} =$	$-(x_{45} + y_{45}) \mathbf{a}_1 -$	$= -(ax_{45} + cz_{45} \cos \beta) \hat{\mathbf{x}} + by_{45} \hat{\mathbf{y}} -$	(4c)	Tl XI
$\mathbf{B}_{87} =$	$(x_{46} - y_{46}) \mathbf{a}_1 +$	$= (ax_{46} + cz_{46} \cos \beta) \hat{\mathbf{x}} + by_{46} \hat{\mathbf{y}} + cz_{46} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XII
$\mathbf{B}_{88} =$	$-(x_{46} + y_{46}) \mathbf{a}_1 -$	$= -(ax_{46} + cz_{46} \cos \beta) \hat{\mathbf{x}} + by_{46} \hat{\mathbf{y}} -$	(4c)	Tl XII
$\mathbf{B}_{89} =$	$(x_{47} - y_{47}) \mathbf{a}_1 +$	$= (ax_{47} + cz_{47} \cos \beta) \hat{\mathbf{x}} + by_{47} \hat{\mathbf{y}} + cz_{47} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XIII
$\mathbf{B}_{90} =$	$-(x_{47} + y_{47}) \mathbf{a}_1 -$	$= -(ax_{47} + cz_{47} \cos \beta) \hat{\mathbf{x}} + by_{47} \hat{\mathbf{y}} -$	(4c)	Tl XIII
$\mathbf{B}_{91} =$	$(x_{48} - y_{48}) \mathbf{a}_1 +$	$= (ax_{48} + cz_{48} \cos \beta) \hat{\mathbf{x}} + by_{48} \hat{\mathbf{y}} + cz_{48} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XIV
$\mathbf{B}_{92} =$	$-(x_{48} + y_{48}) \mathbf{a}_1 -$	$= -(ax_{48} + cz_{48} \cos \beta) \hat{\mathbf{x}} + by_{48} \hat{\mathbf{y}} -$	(4c)	Tl XIV

$\mathbf{B}_{117} =$	$(x_{61} - y_{61}) \mathbf{a}_1 +$ $(x_{61} + y_{61}) \mathbf{a}_2 + z_{61} \mathbf{a}_3$	$= (ax_{61} + cz_{61} \cos \beta) \hat{\mathbf{x}} + by_{61} \hat{\mathbf{y}} + cz_{61} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXVII
$\mathbf{B}_{118} =$	$-(x_{61} + y_{61}) \mathbf{a}_1 -$ $(x_{61} - y_{61}) \mathbf{a}_2 - z_{61} \mathbf{a}_3$	$= -(ax_{61} + cz_{61} \cos \beta) \hat{\mathbf{x}} + by_{61} \hat{\mathbf{y}} -$ $cz_{61} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXVII
$\mathbf{B}_{119} =$	$(x_{62} - y_{62}) \mathbf{a}_1 +$ $(x_{62} + y_{62}) \mathbf{a}_2 + z_{62} \mathbf{a}_3$	$= (ax_{62} + cz_{62} \cos \beta) \hat{\mathbf{x}} + by_{62} \hat{\mathbf{y}} + cz_{62} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXVIII
$\mathbf{B}_{120} =$	$-(x_{62} + y_{62}) \mathbf{a}_1 -$ $(x_{62} - y_{62}) \mathbf{a}_2 - z_{62} \mathbf{a}_3$	$= -(ax_{62} + cz_{62} \cos \beta) \hat{\mathbf{x}} + by_{62} \hat{\mathbf{y}} -$ $cz_{62} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXVIII
$\mathbf{B}_{121} =$	$(x_{63} - y_{63}) \mathbf{a}_1 +$ $(x_{63} + y_{63}) \mathbf{a}_2 + z_{63} \mathbf{a}_3$	$= (ax_{63} + cz_{63} \cos \beta) \hat{\mathbf{x}} + by_{63} \hat{\mathbf{y}} + cz_{63} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXIX
$\mathbf{B}_{122} =$	$-(x_{63} + y_{63}) \mathbf{a}_1 -$ $(x_{63} - y_{63}) \mathbf{a}_2 - z_{63} \mathbf{a}_3$	$= -(ax_{63} + cz_{63} \cos \beta) \hat{\mathbf{x}} + by_{63} \hat{\mathbf{y}} -$ $cz_{63} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXIX
$\mathbf{B}_{123} =$	$(x_{64} - y_{64}) \mathbf{a}_1 +$ $(x_{64} + y_{64}) \mathbf{a}_2 + z_{64} \mathbf{a}_3$	$= (ax_{64} + cz_{64} \cos \beta) \hat{\mathbf{x}} + by_{64} \hat{\mathbf{y}} + cz_{64} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXX
$\mathbf{B}_{124} =$	$-(x_{64} + y_{64}) \mathbf{a}_1 -$ $(x_{64} - y_{64}) \mathbf{a}_2 - z_{64} \mathbf{a}_3$	$= -(ax_{64} + cz_{64} \cos \beta) \hat{\mathbf{x}} + by_{64} \hat{\mathbf{y}} -$ $cz_{64} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXX
$\mathbf{B}_{125} =$	$(x_{65} - y_{65}) \mathbf{a}_1 +$ $(x_{65} + y_{65}) \mathbf{a}_2 + z_{65} \mathbf{a}_3$	$= (ax_{65} + cz_{65} \cos \beta) \hat{\mathbf{x}} + by_{65} \hat{\mathbf{y}} + cz_{65} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXXI
$\mathbf{B}_{126} =$	$-(x_{65} + y_{65}) \mathbf{a}_1 -$ $(x_{65} - y_{65}) \mathbf{a}_2 - z_{65} \mathbf{a}_3$	$= -(ax_{65} + cz_{65} \cos \beta) \hat{\mathbf{x}} + by_{65} \hat{\mathbf{y}} -$ $cz_{65} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXXI
$\mathbf{B}_{127} =$	$(x_{66} - y_{66}) \mathbf{a}_1 +$ $(x_{66} + y_{66}) \mathbf{a}_2 + z_{66} \mathbf{a}_3$	$= (ax_{66} + cz_{66} \cos \beta) \hat{\mathbf{x}} + by_{66} \hat{\mathbf{y}} + cz_{66} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXXII
$\mathbf{B}_{128} =$	$-(x_{66} + y_{66}) \mathbf{a}_1 -$ $(x_{66} - y_{66}) \mathbf{a}_2 - z_{66} \mathbf{a}_3$	$= -(ax_{66} + cz_{66} \cos \beta) \hat{\mathbf{x}} + by_{66} \hat{\mathbf{y}} -$ $cz_{66} \sin \beta \hat{\mathbf{z}}$	(4c)	Tl XXXII

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