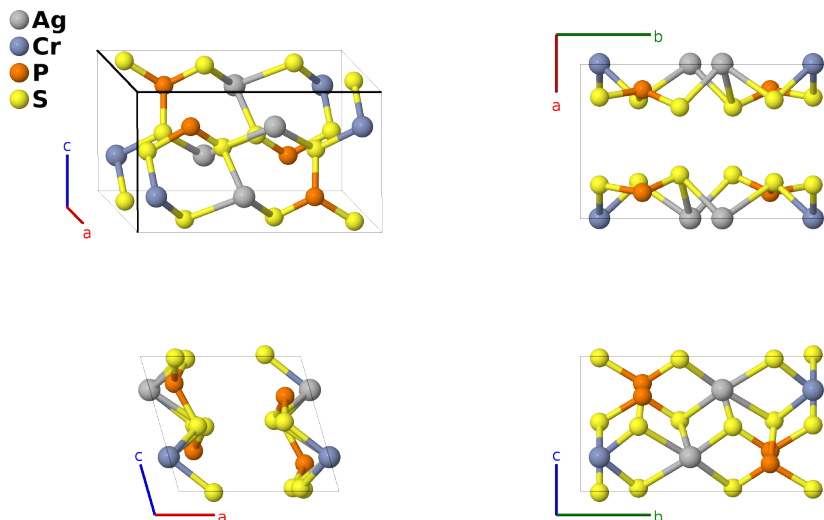


AgCrP₂S₆ Structure: ABC2D6_mP20_13_e_e_g_3g-001

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<https://aflow.org/p/NDG5>

https://aflow.org/p/ABC2D6_mP20_13_e_e_g_3g-001

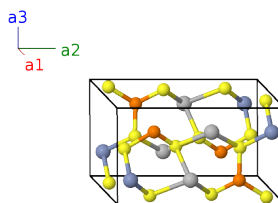


Prototype	AgCrP ₂ S ₆
AFLOW prototype label	ABC2D6_mP20_13_e_e_g_3g-001
ICSD	36456
Pearson symbol	mP20
Space group number	13
Space group symbol	<i>P</i> 2/ <i>c</i>
AFLOW prototype command	aflow --proto=ABC2D6_mP20_13_e_e_g_3g-001 --params= <i>a</i> , <i>b/a</i> , <i>c/a</i> , β , <i>y</i> ₁ , <i>y</i> ₂ , <i>x</i> ₃ , <i>y</i> ₃ , <i>z</i> ₃ , <i>x</i> ₄ , <i>y</i> ₄ , <i>z</i> ₄ , <i>x</i> ₅ , <i>y</i> ₅ , <i>z</i> ₅ , <i>x</i> ₆ , <i>y</i> ₆ , <i>z</i> ₆

- (Selter, 2021) give the coordinates of this structure in the *P*2/*a* setting of space group #13. We used FINDSYM to transform this to the standard *P*2/*c* setting.
- (Selter, 2021) does not yet have an ICSD entry. We list the entry from the earlier work of (Colombet, 1983).

Simple Monoclinic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}} \end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$= y_1 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}c \cos \beta \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + \frac{1}{4}c \sin \beta \hat{\mathbf{z}}$	(2e)	Ag I
\mathbf{B}_2	$= -y_1 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}c \cos \beta \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} + \frac{3}{4}c \sin \beta \hat{\mathbf{z}}$	(2e)	Ag I
\mathbf{B}_3	$= y_2 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}c \cos \beta \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + \frac{1}{4}c \sin \beta \hat{\mathbf{z}}$	(2e)	Cr I
\mathbf{B}_4	$= -y_2 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}c \cos \beta \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + \frac{3}{4}c \sin \beta \hat{\mathbf{z}}$	(2e)	Cr I
\mathbf{B}_5	$= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4g)	P I
\mathbf{B}_6	$= -x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P I
\mathbf{B}_7	$= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4g)	P I
\mathbf{B}_8	$= x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	P I
\mathbf{B}_9	$= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4g)	S I
\mathbf{B}_{10}	$= -x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	S I
\mathbf{B}_{11}	$= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4g)	S I
\mathbf{B}_{12}	$= x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	S I
\mathbf{B}_{13}	$= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4g)	S II
\mathbf{B}_{14}	$= -x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	S II
\mathbf{B}_{15}	$= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(4g)	S II
\mathbf{B}_{16}	$= x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	S II
\mathbf{B}_{17}	$= x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(4g)	S III
\mathbf{B}_{18}	$= -x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 - (z_6 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	S III
\mathbf{B}_{19}	$= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	$=$	$-(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}}$	(4g)	S III
\mathbf{B}_{20}	$= x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 + (z_6 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4g)	S III

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