

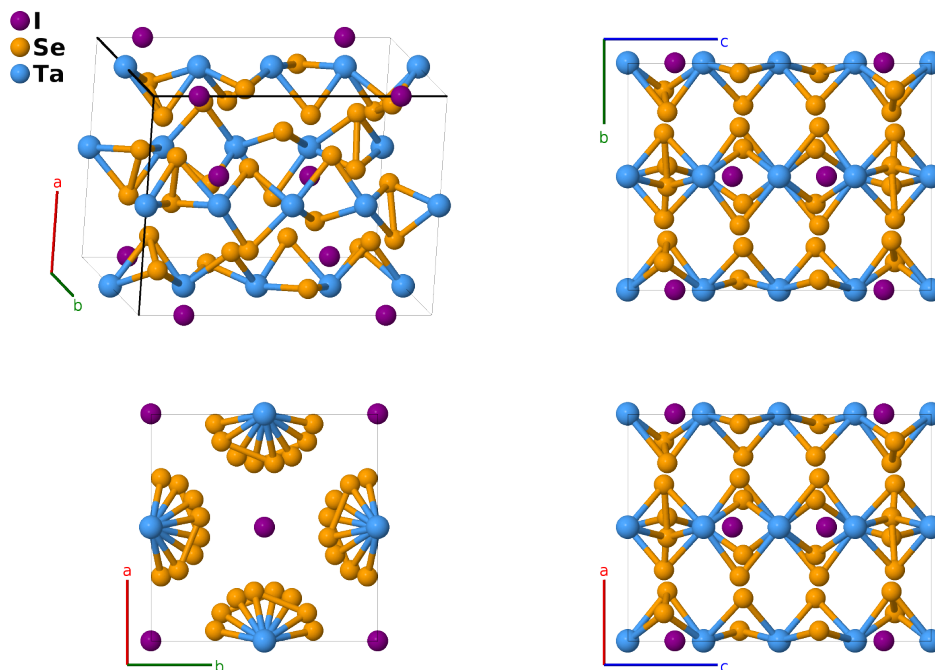
# Ta<sub>2</sub>Se<sub>8</sub>I Structure: AB8C2\_tI44\_97\_e\_2k\_cd-001

This structure originally had the label AB8C2\_tI44\_97\_e\_2k\_cd. Calls to that address will be redirected here.

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<https://afLOW.org/p/4HFE>

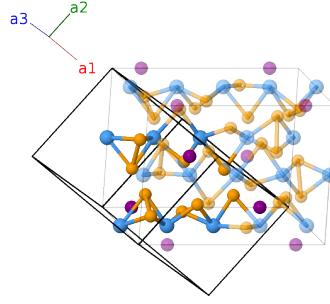
[https://afLOW.org/p/AB8C2\\_tI44\\_97\\_e\\_2k\\_cd-001](https://afLOW.org/p/AB8C2_tI44_97_e_2k_cd-001)



|                         |   |
|-------------------------|---|
| Prototype               | ISe <sub>8</sub> Ta <sub>2</sub>  |
| AFLOW prototype label   | AB8C2_tI44_97_e_2k_cd-001   |
| ICSD                    | 35190   |
| Pearson symbol          | tI44  |
| Space group number      | 97  |
| Space group symbol      | I422  |
| AFLOW prototype command | <code>afLOW --proto=AB8C2_tI44_97_e_2k_cd-001<br/>--params=a, c/a, z<sub>3</sub>, x<sub>4</sub>, y<sub>4</sub>, z<sub>4</sub>, x<sub>5</sub>, y<sub>5</sub>, z<sub>5</sub></code> |

- The ICSD entry is from (Greissier, 1982).

Body-centered Tetragonal primitive vectors



$$\begin{aligned}\mathbf{a}_1 &= -\frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}a\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a\hat{\mathbf{x}} - \frac{1}{2}a\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}a\hat{\mathbf{y}} - \frac{1}{2}c\hat{\mathbf{z}}\end{aligned}$$

## Basis vectors

|                   | Lattice coordinates  |     | Cartesian coordinates   | Wyckoff position | Atom type |
|-------------------|--|-----|---|------------------|-----------|
| $\mathbf{B}_1$    | $= \frac{1}{2}\mathbf{a}_1 + \frac{1}{2}\mathbf{a}_3$                            | $=$ | $\frac{1}{2}a\hat{\mathbf{y}}$  | (4c)             | Ta I      |
| $\mathbf{B}_2$    | $= \frac{1}{2}\mathbf{a}_2 + \frac{1}{2}\mathbf{a}_3$                            | $=$ | $\frac{1}{2}a\hat{\mathbf{x}}$  | (4c)             | Ta I      |
| $\mathbf{B}_3$    | $= \frac{3}{4}\mathbf{a}_1 + \frac{1}{4}\mathbf{a}_2 + \frac{1}{2}\mathbf{a}_3$  | $=$ | $\frac{1}{2}a\hat{\mathbf{y}} + \frac{1}{4}c\hat{\mathbf{z}}$         | (4d)             | Ta II     |
| $\mathbf{B}_4$    | $= \frac{1}{4}\mathbf{a}_1 + \frac{3}{4}\mathbf{a}_2 + \frac{1}{2}\mathbf{a}_3$  | $=$ | $\frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{4}c\hat{\mathbf{z}}$         | (4d)             | Ta II     |
| $\mathbf{B}_5$    | $= z_3\mathbf{a}_1 + z_3\mathbf{a}_2$  | $=$ | $cz_3\hat{\mathbf{z}}$  | (4e)             | I I       |
| $\mathbf{B}_6$    | $= -z_3\mathbf{a}_1 - z_3\mathbf{a}_2$   | $=$ | $-cz_3\hat{\mathbf{z}}$   | (4e)             | I I       |
| $\mathbf{B}_7$    | $= (y_4 + z_4)\mathbf{a}_1 + (x_4 + z_4)\mathbf{a}_2 + (x_4 + y_4)\mathbf{a}_3$  | $=$ | $ax_4\hat{\mathbf{x}} + ay_4\hat{\mathbf{y}} + cz_4\hat{\mathbf{z}}$  | (16k)            | Se I      |
| $\mathbf{B}_8$    | $= -(y_4 - z_4)\mathbf{a}_1 - (x_4 - z_4)\mathbf{a}_2 - (x_4 + y_4)\mathbf{a}_3$ | $=$ | $-ax_4\hat{\mathbf{x}} - ay_4\hat{\mathbf{y}} + cz_4\hat{\mathbf{z}}$ | (16k)            | Se I      |
| $\mathbf{B}_9$    | $= (x_4 + z_4)\mathbf{a}_1 - (y_4 - z_4)\mathbf{a}_2 + (x_4 - y_4)\mathbf{a}_3$  | $=$ | $-ay_4\hat{\mathbf{x}} + ax_4\hat{\mathbf{y}} + cz_4\hat{\mathbf{z}}$ | (16k)            | Se I      |
| $\mathbf{B}_{10}$ | $= -(x_4 - z_4)\mathbf{a}_1 + (y_4 + z_4)\mathbf{a}_2 - (x_4 - y_4)\mathbf{a}_3$ | $=$ | $ay_4\hat{\mathbf{x}} - ax_4\hat{\mathbf{y}} + cz_4\hat{\mathbf{z}}$  | (16k)            | Se I      |
| $\mathbf{B}_{11}$ | $= (y_4 - z_4)\mathbf{a}_1 - (x_4 + z_4)\mathbf{a}_2 - (x_4 - y_4)\mathbf{a}_3$  | $=$ | $-ax_4\hat{\mathbf{x}} + ay_4\hat{\mathbf{y}} - cz_4\hat{\mathbf{z}}$ | (16k)            | Se I      |
| $\mathbf{B}_{12}$ | $= -(y_4 + z_4)\mathbf{a}_1 + (x_4 - z_4)\mathbf{a}_2 + (x_4 - y_4)\mathbf{a}_3$ | $=$ | $ax_4\hat{\mathbf{x}} - ay_4\hat{\mathbf{y}} - cz_4\hat{\mathbf{z}}$  | (16k)            | Se I      |
| $\mathbf{B}_{13}$ | $= (x_4 - z_4)\mathbf{a}_1 + (y_4 - z_4)\mathbf{a}_2 + (x_4 + y_4)\mathbf{a}_3$  | $=$ | $ay_4\hat{\mathbf{x}} + ax_4\hat{\mathbf{y}} - cz_4\hat{\mathbf{z}}$  | (16k)            | Se I      |
| $\mathbf{B}_{14}$ | $= -(x_4 + z_4)\mathbf{a}_1 - (y_4 + z_4)\mathbf{a}_2 - (x_4 + y_4)\mathbf{a}_3$ | $=$ | $-ay_4\hat{\mathbf{x}} - ax_4\hat{\mathbf{y}} - cz_4\hat{\mathbf{z}}$ | (16k)            | Se I      |
| $\mathbf{B}_{15}$ | $= (y_5 + z_5)\mathbf{a}_1 + (x_5 + z_5)\mathbf{a}_2 + (x_5 + y_5)\mathbf{a}_3$  | $=$ | $ax_5\hat{\mathbf{x}} + ay_5\hat{\mathbf{y}} + cz_5\hat{\mathbf{z}}$  | (16k)            | Se II     |
| $\mathbf{B}_{16}$ | $= -(y_5 - z_5)\mathbf{a}_1 - (x_5 - z_5)\mathbf{a}_2 - (x_5 + y_5)\mathbf{a}_3$ | $=$ | $-ax_5\hat{\mathbf{x}} - ay_5\hat{\mathbf{y}} + cz_5\hat{\mathbf{z}}$ | (16k)            | Se II     |
| $\mathbf{B}_{17}$ | $= (x_5 + z_5)\mathbf{a}_1 - (y_5 - z_5)\mathbf{a}_2 + (x_5 - y_5)\mathbf{a}_3$  | $=$ | $-ay_5\hat{\mathbf{x}} + ax_5\hat{\mathbf{y}} + cz_5\hat{\mathbf{z}}$ | (16k)            | Se II     |
| $\mathbf{B}_{18}$ | $= -(x_5 - z_5)\mathbf{a}_1 + (y_5 + z_5)\mathbf{a}_2 - (x_5 - y_5)\mathbf{a}_3$ | $=$ | $ay_5\hat{\mathbf{x}} - ax_5\hat{\mathbf{y}} + cz_5\hat{\mathbf{z}}$  | (16k)            | Se II     |
| $\mathbf{B}_{19}$ | $= (y_5 - z_5)\mathbf{a}_1 - (x_5 + z_5)\mathbf{a}_2 - (x_5 - y_5)\mathbf{a}_3$  | $=$ | $-ax_5\hat{\mathbf{x}} + ay_5\hat{\mathbf{y}} - cz_5\hat{\mathbf{z}}$ | (16k)            | Se II     |
| $\mathbf{B}_{20}$ | $= -(y_5 + z_5)\mathbf{a}_1 + (x_5 - z_5)\mathbf{a}_2 + (x_5 - y_5)\mathbf{a}_3$ | $=$ | $ax_5\hat{\mathbf{x}} - ay_5\hat{\mathbf{y}} - cz_5\hat{\mathbf{z}}$  | (16k)            | Se II     |

$$\mathbf{B}_{21} = \begin{matrix} (x_5 - z_5) \mathbf{a}_1 + (y_5 - z_5) \mathbf{a}_2 + \\ (x_5 + y_5) \mathbf{a}_3 \end{matrix} = ay_5 \hat{\mathbf{x}} + ax_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} \quad (16k) \quad \text{Se II}$$

$$\mathbf{B}_{22} = \begin{matrix} -(x_5 + z_5) \mathbf{a}_1 - (y_5 + z_5) \mathbf{a}_2 - \\ (x_5 + y_5) \mathbf{a}_3 \end{matrix} = -ay_5 \hat{\mathbf{x}} - ax_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} \quad (16k) \quad \text{Se II}$$

## References

- [1] P. Gressier, A. Meerschaut, L. Guemas, J. Rouxel, and P. Monceau, *Characterization of the new series of quasi one-dimensional compounds*  $(MX_4)_n Y$  ( $M = Nb, Ta; X = S, Se; Y = Br, I$ ), *J. Solid State Chem.* **51**, 141–151 (1984), doi:10.1016/0022-4596(84)90327-X.
- [2] P. Gressier, L. Guemas, and A. Meerschaut, *Preparation and structure of ditantalum iodide octaselenide,  $Ta_2ISe_8$* , *Acta Crystallogr. Sect. B* **38**, 2877–2879 (1982), doi:10.1107/S0567740882010176.

## Found in

- [1] P. Villars and K. Cenzual, *Pearson's Crystal Data – Crystal Structure Database for Inorganic Compounds* (2013). ASM International.