

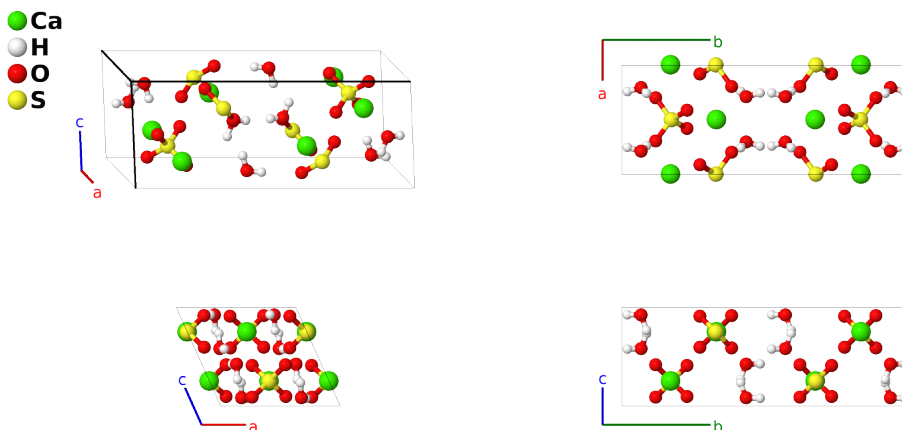
Gypsum ($\text{CaSO}_4 \cdot 2\text{H}_2\text{O}$, $H4_6$) Structure: AB4C6D_mC48_15_e_2f_3f_e-001

This structure originally had the label AB4C6D_mC48_15_e_2f_3f_e. Calls to that address will be redirected here.

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<https://aflow.org/p/8924>

https://aflow.org/p/AB4C6D_mC48_15_e_2f_3f_e-001

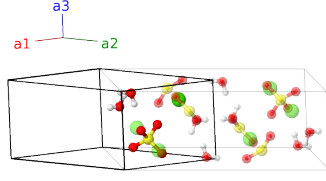


Prototype	$\text{CaH}_4\text{O}_6\text{S}$
AFLOW prototype label	AB4C6D_mC48_15_e_2f_3f_e-001
<i>Strukturbericht</i> designation	$H4_6$
Mineral name	gypsum
ICSD	161622
Pearson symbol	mC48
Space group number	15
Space group symbol	$C2/c$
AFLOW prototype command	<pre>aflow --proto=AB4C6D_mC48_15_e_2f_3f_e-001 --params=a, b/a, c/a, β, $y_1, y_2, x_3, y_3, z_3, x_4, y_4, z_4, x_5, y_5, z_5, x_6, y_6, z_6, x_7, y_7, z_7$</pre>

- (Onorato, 1929) determined that gypsum was in space group $C2/m$ #13, and (Hermann, 1937) assigned this to *Strukturbericht* $H4_6$. However, (Wooster, 1936) and other determined that the correct space group was $C2/c$ #15, and (Gottfried, 1938) assigned the $H4_6$ symbol to this structure. We use the 1 atmosphere data of (Comodi, 2008), who also determine the positions of the hydrogen atoms.

Base-centered Monoclinic primitive vectors

$$\begin{aligned}
\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}b \hat{\mathbf{y}} \\
\mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} \\
\mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}
\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$= -y_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}c \cos \beta \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + \frac{1}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	Ca I
\mathbf{B}_2	$= y_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}c \cos \beta \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} + \frac{3}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	Ca I
\mathbf{B}_3	$= -y_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}c \cos \beta \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + \frac{1}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	S I
\mathbf{B}_4	$= y_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}c \cos \beta \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + \frac{3}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	S I
\mathbf{B}_5	$= (x_3 - y_3) \mathbf{a}_1 + (x_3 + y_3) \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(8f)	H I
\mathbf{B}_6	$= -(x_3 + y_3) \mathbf{a}_1 - (x_3 - y_3) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	H I
\mathbf{B}_7	$= -(x_3 - y_3) \mathbf{a}_1 - (x_3 + y_3) \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(8f)	H I
\mathbf{B}_8	$= (x_3 + y_3) \mathbf{a}_1 + (x_3 - y_3) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	H I
\mathbf{B}_9	$= (x_4 - y_4) \mathbf{a}_1 + (x_4 + y_4) \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(8f)	H II
\mathbf{B}_{10}	$= -(x_4 + y_4) \mathbf{a}_1 - (x_4 - y_4) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	H II
\mathbf{B}_{11}	$= -(x_4 - y_4) \mathbf{a}_1 - (x_4 + y_4) \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(8f)	H II
\mathbf{B}_{12}	$= (x_4 + y_4) \mathbf{a}_1 + (x_4 - y_4) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	H II
\mathbf{B}_{13}	$= (x_5 - y_5) \mathbf{a}_1 + (x_5 + y_5) \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(8f)	O I
\mathbf{B}_{14}	$= -(x_5 + y_5) \mathbf{a}_1 - (x_5 - y_5) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	O I
\mathbf{B}_{15}	$= -(x_5 - y_5) \mathbf{a}_1 - (x_5 + y_5) \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(8f)	O I
\mathbf{B}_{16}	$= (x_5 + y_5) \mathbf{a}_1 + (x_5 - y_5) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	O I
\mathbf{B}_{17}	$= (x_6 - y_6) \mathbf{a}_1 + (x_6 + y_6) \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(8f)	O II
\mathbf{B}_{18}	$= -(x_6 + y_6) \mathbf{a}_1 - (x_6 - y_6) \mathbf{a}_2 - (z_6 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	O II
\mathbf{B}_{19}	$= -(x_6 - y_6) \mathbf{a}_1 - (x_6 + y_6) \mathbf{a}_2 - z_6 \mathbf{a}_3$	$=$	$-(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}}$	(8f)	O II
\mathbf{B}_{20}	$= (x_6 + y_6) \mathbf{a}_1 + (x_6 - y_6) \mathbf{a}_2 + (z_6 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	O II

$$\mathbf{B}_{21} = \begin{matrix} (x_7 - y_7) \mathbf{a}_1 + (x_7 + y_7) \mathbf{a}_2 + \\ z_7 \mathbf{a}_3 \end{matrix} = (ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}} \quad (8f) \quad \text{O III}$$

$$\mathbf{B}_{22} = \begin{matrix} -(x_7 + y_7) \mathbf{a}_1 - (x_7 - y_7) \mathbf{a}_2 - \\ (z_7 - \frac{1}{2}) \mathbf{a}_3 \end{matrix} = \begin{matrix} -(ax_7 + c(z_7 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} - \\ c(z_7 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{matrix} \quad (8f) \quad \text{O III}$$

$$\mathbf{B}_{23} = \begin{matrix} -(x_7 - y_7) \mathbf{a}_1 - (x_7 + y_7) \mathbf{a}_2 - \\ z_7 \mathbf{a}_3 \end{matrix} = -(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}} \quad (8f) \quad \text{O III}$$

$$\mathbf{B}_{24} = \begin{matrix} (x_7 + y_7) \mathbf{a}_1 + (x_7 - y_7) \mathbf{a}_2 + \\ (z_7 + \frac{1}{2}) \mathbf{a}_3 \end{matrix} = \begin{matrix} (ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + \\ c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{matrix} \quad (8f) \quad \text{O III}$$

References

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