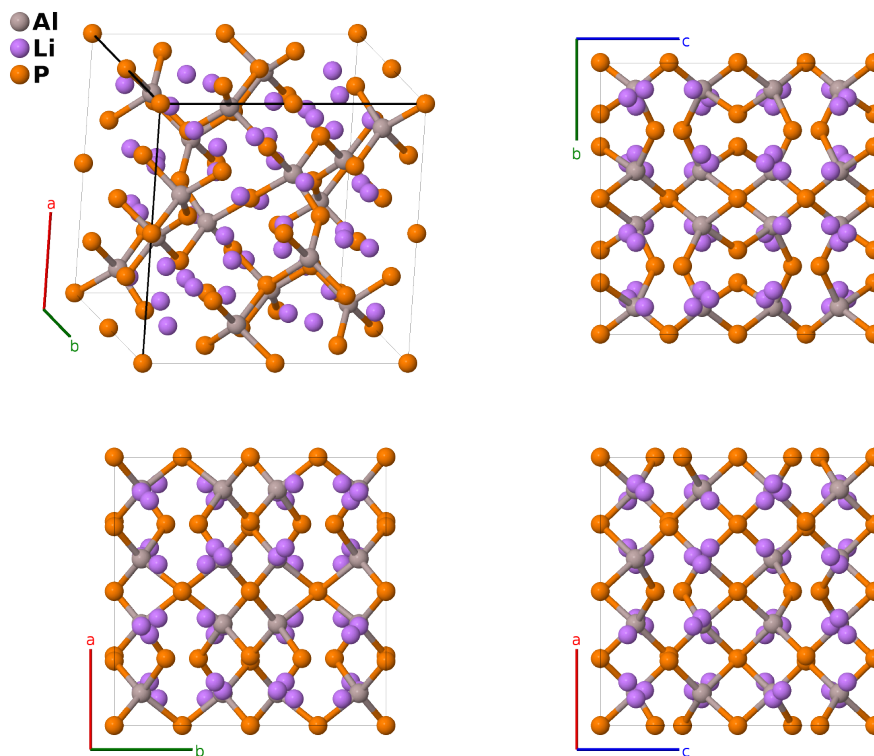


Predicted Li_3AlP_2 Structure: AB3C2_oI96_73_f_3f_acde-001

Cite this page as: H. Eckert, S. Divilov, A. Zettel, M. J. Mehl, D. Hicks, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*. In preparation.

<https://aflow.org/p/QKN5>

https://aflow.org/p/AB3C2_oI96_73_f_3f_acde-001



Prototype	AlLi_3P_2
AFLOW prototype label	AB3C2_oI96_73_f_3f_acde-001
ICSD	186820
Pearson symbol	oI96
Space group number	73
Space group symbol	<i>Ibca</i>
AFLOW prototype command	<code>aflow --proto=AB3C2_oI96_73_f_3f_acde-001</code> <code>--params=a, b/a, c/a, x2, y3, z4, x5, y5, z5, x6, y6, z6, x7, y7, z7, x8, y8, z8</code>

Other compounds with this structure

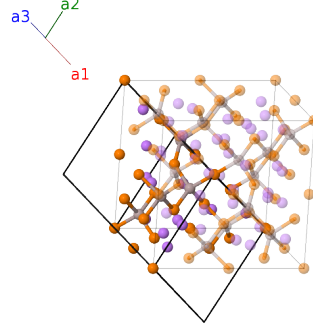
Li_3AlAs_2 , Li_3Ga_2

- The first experimental information we have for this structure is from (Juza, 1952), who placed the system in space group *Ibca* #71 but could not locate the lithium atoms, except to note that they are on a (16f) site.

- (Dadsetani, 2011) used this work as the starting point for first-principles calculations to minimize the total energy of the structure, including the positions of the lithium atoms, keeping the structure in space group $Ibca$, shown here.
- (Restle, 2020) used ball milling and annealing to produce samples of Li_3AlP_2 and Li_3GaP_2 and found them to be in space group $Cmce$ #64. While we believe that this work is correct, we present both structures.
- (Dadsetani, 2011) only gave one (16f) position for the lithium atoms, so we generated the other two sets by taking $x \rightarrow y \rightarrow z \rightarrow x$.
- ICSD entry 186820 is no longer in the database. This suggests that this structure was withdrawn, but we have no confirmation of that.

Body-centered Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= -\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} - \frac{1}{2}c \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	0	$=$	0	(8a)	P I
\mathbf{B}_2	$\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2}b \hat{\mathbf{y}}$	(8a)	P I
\mathbf{B}_3	$\frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2}a \hat{\mathbf{x}}$	(8a)	P I
\mathbf{B}_4	$\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2$	$=$	$\frac{1}{2}c \hat{\mathbf{z}}$	(8a)	P I
\mathbf{B}_5	$\frac{1}{4} \mathbf{a}_1 + (x_2 + \frac{1}{4}) \mathbf{a}_2 + x_2 \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} + \frac{1}{4}c \hat{\mathbf{z}}$	(8c)	P II
\mathbf{B}_6	$\frac{3}{4} \mathbf{a}_1 - (x_2 - \frac{1}{4}) \mathbf{a}_2 - (x_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{4}c \hat{\mathbf{z}}$	(8c)	P II
\mathbf{B}_7	$\frac{3}{4} \mathbf{a}_1 - (x_2 - \frac{3}{4}) \mathbf{a}_2 - x_2 \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + \frac{3}{4}c \hat{\mathbf{z}}$	(8c)	P II
\mathbf{B}_8	$\frac{1}{4} \mathbf{a}_1 + (x_2 + \frac{3}{4}) \mathbf{a}_2 + (x_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$a(x_2 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}c \hat{\mathbf{z}}$	(8c)	P II
\mathbf{B}_9	$y_3 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + (y_3 + \frac{1}{4}) \mathbf{a}_3$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}}$	(8d)	P III
\mathbf{B}_{10}	$-(y_3 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - (y_3 - \frac{1}{4}) \mathbf{a}_3$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$	(8d)	P III
\mathbf{B}_{11}	$-y_3 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - (y_3 - \frac{3}{4}) \mathbf{a}_3$	$=$	$\frac{3}{4}a \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}}$	(8d)	P III
\mathbf{B}_{12}	$(y_3 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + (y_3 + \frac{3}{4}) \mathbf{a}_3$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}}$	(8d)	P III
\mathbf{B}_{13}	$(z_4 + \frac{1}{4}) \mathbf{a}_1 + z_4 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}b \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8e)	P IV
\mathbf{B}_{14}	$-(z_4 - \frac{1}{4}) \mathbf{a}_1 - (z_4 - \frac{1}{2}) \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(8e)	P IV
\mathbf{B}_{15}	$-(z_4 - \frac{3}{4}) \mathbf{a}_1 - z_4 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}b \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(8e)	P IV
\mathbf{B}_{16}	$(z_4 + \frac{3}{4}) \mathbf{a}_1 + (z_4 + \frac{1}{2}) \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}b \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \hat{\mathbf{z}}$	(8e)	P IV
\mathbf{B}_{17}	$(y_5 + z_5) \mathbf{a}_1 + (x_5 + z_5) \mathbf{a}_2 + (x_5 + y_5) \mathbf{a}_3$	$=$	$ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(16f)	Al I
\mathbf{B}_{18}	$(-y_5 + z_5 + \frac{1}{2}) \mathbf{a}_1 - (x_5 - z_5) \mathbf{a}_2 - (x_5 + y_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(16f)	Al I

$$\begin{aligned}
\mathbf{B}_{19} &= (y_5 - z_5) \mathbf{a}_1 - (x_5 + z_5 - \frac{1}{2}) \mathbf{a}_2 + (-x_5 + y_5 + \frac{1}{2}) \mathbf{a}_3 &= & -a(x_5 - \frac{1}{2}) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{20} &= -(y_5 + z_5 - \frac{1}{2}) \mathbf{a}_1 + (x_5 - z_5 + \frac{1}{2}) \mathbf{a}_2 + (x_5 - y_5) \mathbf{a}_3 &= & ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{21} &= -(y_5 + z_5) \mathbf{a}_1 - (x_5 + z_5) \mathbf{a}_2 - (x_5 + y_5) \mathbf{a}_3 &= & -ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{22} &= (y_5 - z_5 + \frac{1}{2}) \mathbf{a}_1 + (x_5 - z_5) \mathbf{a}_2 + (x_5 + y_5 + \frac{1}{2}) \mathbf{a}_3 &= & ax_5 \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{23} &= -(y_5 - z_5) \mathbf{a}_1 + (x_5 + z_5 + \frac{1}{2}) \mathbf{a}_2 + (x_5 - y_5 + \frac{1}{2}) \mathbf{a}_3 &= & a(x_5 + \frac{1}{2}) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{24} &= (y_5 + z_5 + \frac{1}{2}) \mathbf{a}_1 + (-x_5 + z_5 + \frac{1}{2}) \mathbf{a}_2 - (x_5 - y_5) \mathbf{a}_3 &= & -ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Al I} \\
\mathbf{B}_{25} &= (y_6 + z_6) \mathbf{a}_1 + (x_6 + z_6) \mathbf{a}_2 + (x_6 + y_6) \mathbf{a}_3 &= & ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{26} &= (-y_6 + z_6 + \frac{1}{2}) \mathbf{a}_1 - (x_6 - z_6) \mathbf{a}_2 - (x_6 + y_6 - \frac{1}{2}) \mathbf{a}_3 &= & -ax_6 \hat{\mathbf{x}} - b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{27} &= (y_6 - z_6) \mathbf{a}_1 - (x_6 + z_6 - \frac{1}{2}) \mathbf{a}_2 + (-x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 &= & -a(x_6 - \frac{1}{2}) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{28} &= -(y_6 + z_6 - \frac{1}{2}) \mathbf{a}_1 + (x_6 - z_6 + \frac{1}{2}) \mathbf{a}_2 + (x_6 - y_6) \mathbf{a}_3 &= & ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{29} &= -(y_6 + z_6) \mathbf{a}_1 - (x_6 + z_6) \mathbf{a}_2 - (x_6 + y_6) \mathbf{a}_3 &= & -ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{30} &= (y_6 - z_6 + \frac{1}{2}) \mathbf{a}_1 + (x_6 - z_6) \mathbf{a}_2 + (x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 &= & ax_6 \hat{\mathbf{x}} + b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{31} &= -(y_6 - z_6) \mathbf{a}_1 + (x_6 + z_6 + \frac{1}{2}) \mathbf{a}_2 + (x_6 - y_6 + \frac{1}{2}) \mathbf{a}_3 &= & a(x_6 + \frac{1}{2}) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{32} &= (y_6 + z_6 + \frac{1}{2}) \mathbf{a}_1 + (-x_6 + z_6 + \frac{1}{2}) \mathbf{a}_2 - (x_6 - y_6) \mathbf{a}_3 &= & -ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li I} \\
\mathbf{B}_{33} &= (y_7 + z_7) \mathbf{a}_1 + (x_7 + z_7) \mathbf{a}_2 + (x_7 + y_7) \mathbf{a}_3 &= & ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{34} &= (-y_7 + z_7 + \frac{1}{2}) \mathbf{a}_1 - (x_7 - z_7) \mathbf{a}_2 - (x_7 + y_7 - \frac{1}{2}) \mathbf{a}_3 &= & -ax_7 \hat{\mathbf{x}} - b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{35} &= (y_7 - z_7) \mathbf{a}_1 - (x_7 + z_7 - \frac{1}{2}) \mathbf{a}_2 + (-x_7 + y_7 + \frac{1}{2}) \mathbf{a}_3 &= & -a(x_7 - \frac{1}{2}) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{36} &= -(y_7 + z_7 - \frac{1}{2}) \mathbf{a}_1 + (x_7 - z_7 + \frac{1}{2}) \mathbf{a}_2 + (x_7 - y_7) \mathbf{a}_3 &= & ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{37} &= -(y_7 + z_7) \mathbf{a}_1 - (x_7 + z_7) \mathbf{a}_2 - (x_7 + y_7) \mathbf{a}_3 &= & -ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{38} &= (y_7 - z_7 + \frac{1}{2}) \mathbf{a}_1 + (x_7 - z_7) \mathbf{a}_2 + (x_7 + y_7 + \frac{1}{2}) \mathbf{a}_3 &= & ax_7 \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{39} &= -(y_7 - z_7) \mathbf{a}_1 + (x_7 + z_7 + \frac{1}{2}) \mathbf{a}_2 + (x_7 - y_7 + \frac{1}{2}) \mathbf{a}_3 &= & a(x_7 + \frac{1}{2}) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16f) & \text{Li II} \\
\mathbf{B}_{40} &= (y_7 + z_7 + \frac{1}{2}) \mathbf{a}_1 + (-x_7 + z_7 + \frac{1}{2}) \mathbf{a}_2 - (x_7 - y_7) \mathbf{a}_3 &= & -ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li II}
\end{aligned}$$

$$\begin{aligned}
\mathbf{B}_{41} &= \begin{pmatrix} (y_8 + z_8) \mathbf{a}_1 + (x_8 + z_8) \mathbf{a}_2 + \\ (x_8 + y_8) \mathbf{a}_3 \end{pmatrix} = ax_8 \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (16f) & \text{Li III} \\
\mathbf{B}_{42} &= \begin{pmatrix} (-y_8 + z_8 + \frac{1}{2}) \mathbf{a}_1 - \\ (x_8 - z_8) \mathbf{a}_2 - (x_8 + y_8 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ax_8 \hat{\mathbf{x}} - b(y_8 - \frac{1}{2}) \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (16f) & \text{Li III} \\
\mathbf{B}_{43} &= \begin{pmatrix} (y_8 - z_8) \mathbf{a}_1 - (x_8 + z_8 - \frac{1}{2}) \mathbf{a}_2 + \\ (-x_8 + y_8 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(x_8 - \frac{1}{2}) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} - cz_8 \hat{\mathbf{z}} & (16f) & \text{Li III} \\
\mathbf{B}_{44} &= \begin{pmatrix} -(y_8 + z_8 - \frac{1}{2}) \mathbf{a}_1 + \\ (x_8 - z_8 + \frac{1}{2}) \mathbf{a}_2 + (x_8 - y_8) \mathbf{a}_3 \end{pmatrix} = ax_8 \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li III} \\
\mathbf{B}_{45} &= \begin{pmatrix} -(y_8 + z_8) \mathbf{a}_1 - (x_8 + z_8) \mathbf{a}_2 - \\ (x_8 + y_8) \mathbf{a}_3 \end{pmatrix} = -ax_8 \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \hat{\mathbf{z}} & (16f) & \text{Li III} \\
\mathbf{B}_{46} &= \begin{pmatrix} (y_8 - z_8 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_8 - z_8) \mathbf{a}_2 + (x_8 + y_8 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ax_8 \hat{\mathbf{x}} + b(y_8 + \frac{1}{2}) \hat{\mathbf{y}} - cz_8 \hat{\mathbf{z}} & (16f) & \text{Li III} \\
\mathbf{B}_{47} &= \begin{pmatrix} -(y_8 - z_8) \mathbf{a}_1 + \\ (x_8 + z_8 + \frac{1}{2}) \mathbf{a}_2 + \\ (x_8 - y_8 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(x_8 + \frac{1}{2}) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (16f) & \text{Li III} \\
\mathbf{B}_{48} &= \begin{pmatrix} (y_8 + z_8 + \frac{1}{2}) \mathbf{a}_1 + \\ (-x_8 + z_8 + \frac{1}{2}) \mathbf{a}_2 - (x_8 - y_8) \mathbf{a}_3 \end{pmatrix} = -ax_8 \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \hat{\mathbf{z}} & (16f) & \text{Li III}
\end{aligned}$$

References

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