

δ -LiSmO₂ Structure:

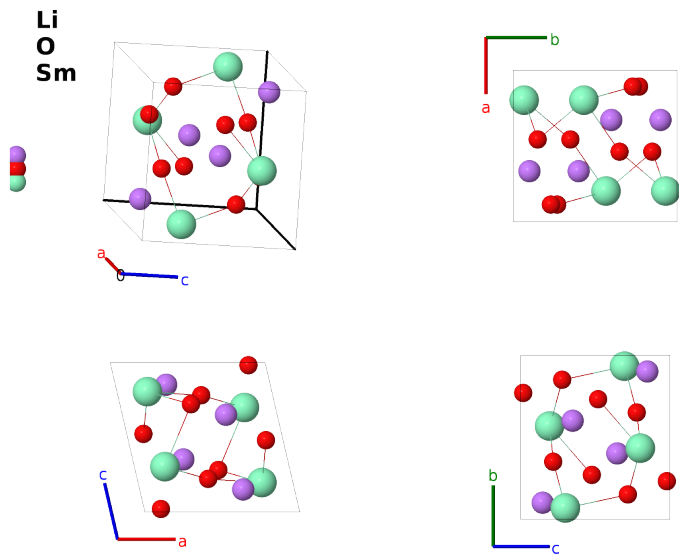
AB2C_mP16_14_e_2e_e-002

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<https://aflow.org/prototype-encyclopedia/70RQ>

https://aflow.org/prototype-encyclopedia/AB2C_mP16_14_e_2e_e-002



Prototype	LiO ₂ Sm
AFLOW prototype label	AB2C_mP16_14_e_2e_e-002
ICSD	23511
CCDC	1599621
Pearson symbol	mP16
Space group number	14
Space group symbol	$P2_1/c$
AFLOW prototype command	<pre>aflow --proto=AB2C_mP16_14_e_2e_e-002 --params=a, b/a, c/a, β, x_1, y_1, z_1, x_2, y_2, z_2, x_3, y_3, z_3, x_4, y_4, z_4</pre>

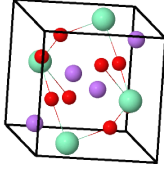
Other compounds with this structure

LiCeO₂, LiEuO₂, LiLaO₂, LiNdO₂, LiPrO₂

- Lanthanide rare-earth lithium oxides (LiLnO₂) come in several different forms (Faucher, 1998):
 - α -LiLnO₂: small ions (Ln = Lu, Yb, Er) form in the γ -LiFeO₂ structure.
 - β -LiLnO₂: medium-sized ions (Ln = Y, Ho, Dy, Er) form in the β -LiErO₂ structure.

- γ -LiLnO₂: (Ln = Tb, Gd, Eu, Sm) form in the SrZnO₂ structure.
- δ -LiLnO₂: (Ln = Eu, Sm, Nd, Pr, La) form in this δ -LiSmO₂ structure.

Simple Monoclinic primitive vectors

$$\begin{aligned}
 \mathbf{a}_1 &= a \hat{\mathbf{x}} \\
 \mathbf{a}_2 &= b \hat{\mathbf{y}} \\
 \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}
 \end{aligned}$$


Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	=	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Li I
$\mathbf{B}_2$	$-x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Li I
$\mathbf{B}_3$	$-x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	=	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Li I
$\mathbf{B}_4$	$x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Li I
$\mathbf{B}_5$	$x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	=	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_6$	$-x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_7$	$-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	=	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_8$	$x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O I
$\mathbf{B}_9$	$x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	=	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{10}$	$-x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{11}$	$-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	=	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{12}$	$x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O II
$\mathbf{B}_{13}$	$x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	=	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	Sm I
$\mathbf{B}_{14}$	$-x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Sm I
$\mathbf{B}_{15}$	$-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	=	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	Sm I
$\mathbf{B}_{16}$	$x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Sm I

References

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