

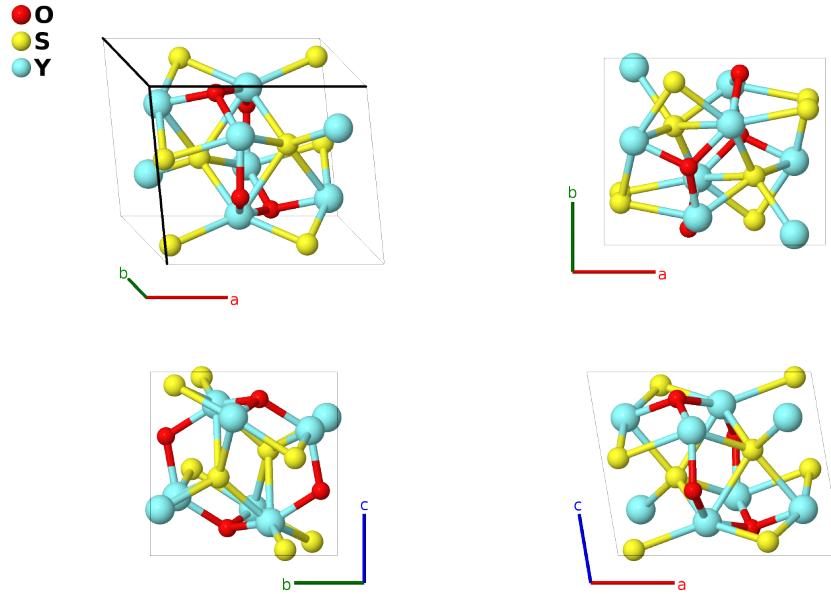
Y_2OS_2 Structure:

AB₂C₂_mP20_14_e_2e_2e-001

Cite this page as: H. Eckert, S. Divilov, A. Zettel, M. J. Mehl, D. Hicks, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*. In preparation.

<https://aflow.org/p/A73U>

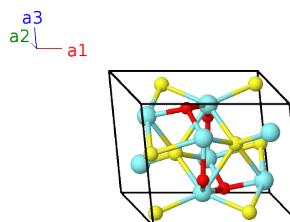
https://aflow.org/p/AB2C2_mP20_14_e_2e_2e-001



| | |
|-------------------------|---|
| Prototype | OS_2Y_2 |
| AFLOW prototype label | AB ₂ C ₂ _mP20_14_e_2e_2e-001 |
| ICSD | 67503 |
| Pearson symbol | mP20 |
| Space group number | 14 |
| Space group symbol | $P2_1/c$ |
| AFLOW prototype command | <pre>aflow --proto=AB2C2_mP20_14_e_2e_2e-001 --params=a, b/a, c/a, beta, x1, y1, z1, x2, y2, z2, x3, y3, z3, x4, y4, z4, x5, y5, z5</pre> |

Simple Monoclinic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

| | Lattice coordinates | Cartesian coordinates | Wyckoff position | Atom type |
|-----------------------|---|---|---------------------|--------------|
| B₁ | = $x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$ | = $(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$ | (4e) | O I |
| B₂ | = $-x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$ | = $-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | O I |
| B₃ | = $-x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$ | = $-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$ | (4e) | O I |
| B₄ | = $x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$ | = $(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | O I |
| B₅ | = $x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$ | = $(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$ | (4e) | S I |
| B₆ | = $-x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$ | = $-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | S I |
| B₇ | = $-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$ | = $-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$ | (4e) | S I |
| B₈ | = $x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$ | = $(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | S I |
| B₉ | = $x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$ | = $(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$ | (4e) | S II |
| B₁₀ | = $-x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$ | = $-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | S II |
| B₁₁ | = $-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$ | = $-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$ | (4e) | S II |
| B₁₂ | = $x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$ | = $(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | S II |
| B₁₃ | = $x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$ | = $(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$ | (4e) | Y I |
| B₁₄ | = $-x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$ | = $-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | Y I |
| B₁₅ | = $-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$ | = $-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$ | (4e) | Y I |
| B₁₆ | = $x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$ | = $(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | Y I |
| B₁₇ | = $x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$ | = $(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$ | (4e) | Y II |
| B₁₈ | = $-x_5 \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$ | = $-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | Y II |
| B₁₉ | = $-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$ | = $-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$ | (4e) | Y II |
| B₂₀ | = $x_5 \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$ | = $(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$ | (4e) | Y II |

References

- [1] T. Schleid, *Crystal structures of D-Y₂S₃ and Y₂OS₂*, Eur. J. of Solid State Inorg. Chem. **29**, 1015–1028 (1992).