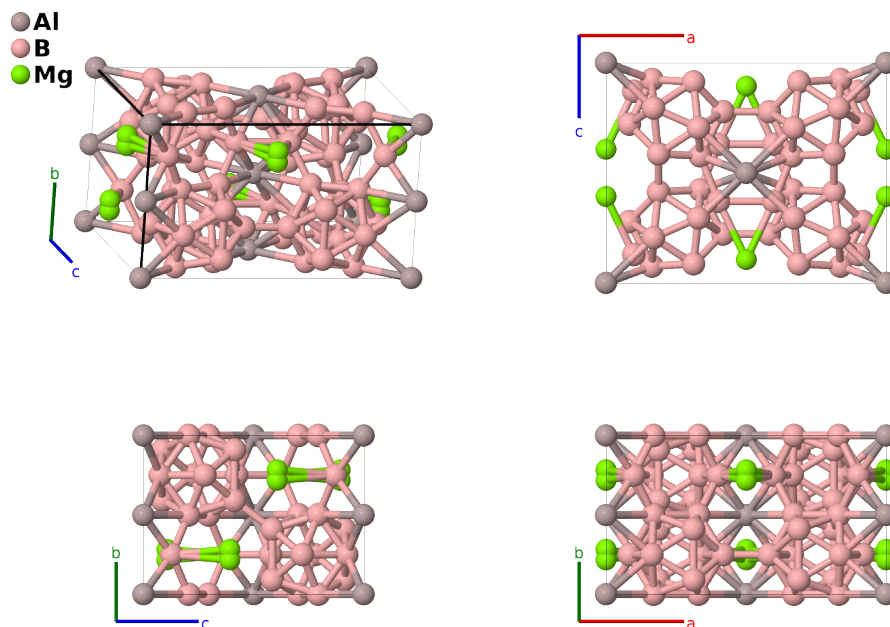


MgAlB₁₄ Structure: AB14C2_oI68_74_a_3i2j_h-001

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<https://afLOW.org/p/U35P>

https://afLOW.org/p/AB14C2_oI68_74_a_3i2j_h-001



Prototype	AlB ₁₄ Mg
AFLOW prototype label	AB14C2_oI68_74_a_3i2j_h-001
ICSD	30728
Pearson symbol	oI68
Space group number	74
Space group symbol	<i>Imma</i>
AFLOW prototype command	<code>afLOW --proto=AB14C2_oI68_74_a_3i2j_h-001 --params=a, b/a, c/a, y2, z2, x3, z3, x4, z4, x5, z5, x6, y6, z6, x7, y7, z7</code>

Other compounds with this structure

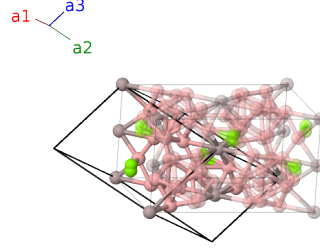
ErAlB₁₄, LuAlB₁₄, TmAlB₁₄, YbAlB₁₄

- The Al (4a) sites are only occupied 74.8% of the time, and the Mg (8h) sites is only occupied 39.0% of the time, so the the actual composition of this sample is Mg_{0.780}Al_{0.748}B₁₄.
- The atoms on the Mg (8h) site form pairs separated by 0.4Å, much too close to be physical, so at most only one site in each pair can be occupied. Alternatively, if we set $x_5 = 0$ then the pairs merge to become a (4e) site, with occupation 0.78. This structure may be more convenient for electronic structure calculations.

- (Higashi, 1983) give the structure in the *Imam* setting of space group #74. We used FINDSYM and AFLOW to transform this to the standard *Imma* setting.

Body-centered Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= -\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} - \frac{1}{2}c \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	0	$=$	0	(4a)	Al I
\mathbf{B}_2	$\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2}b \hat{\mathbf{y}}$	(4a)	Al I
\mathbf{B}_3	$(y_2 + z_2) \mathbf{a}_1 + z_2 \mathbf{a}_2 + y_2 \mathbf{a}_3$	$=$	$by_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8h)	Mg I
\mathbf{B}_4	$(-y_2 + z_2 + \frac{1}{2}) \mathbf{a}_1 + z_2 \mathbf{a}_2 - (y_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8h)	Mg I
\mathbf{B}_5	$(y_2 - z_2 + \frac{1}{2}) \mathbf{a}_1 - z_2 \mathbf{a}_2 + (y_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(8h)	Mg I
\mathbf{B}_6	$-(y_2 + z_2) \mathbf{a}_1 - z_2 \mathbf{a}_2 - y_2 \mathbf{a}_3$	$=$	$-by_2 \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(8h)	Mg I
\mathbf{B}_7	$(z_3 + \frac{1}{4}) \mathbf{a}_1 + (x_3 + z_3) \mathbf{a}_2 + (x_3 + \frac{1}{4}) \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8i)	B I
\mathbf{B}_8	$(z_3 + \frac{1}{4}) \mathbf{a}_1 - (x_3 - z_3) \mathbf{a}_2 - (x_3 - \frac{1}{4}) \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8i)	B I
\mathbf{B}_9	$-(z_3 - \frac{3}{4}) \mathbf{a}_1 - (x_3 + z_3) \mathbf{a}_2 - (x_3 - \frac{3}{4}) \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_3 \hat{\mathbf{z}}$	(8i)	B I
\mathbf{B}_{10}	$-(z_3 - \frac{3}{4}) \mathbf{a}_1 + (x_3 - z_3) \mathbf{a}_2 + (x_3 + \frac{3}{4}) \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_3 \hat{\mathbf{z}}$	(8i)	B I
\mathbf{B}_{11}	$(z_4 + \frac{1}{4}) \mathbf{a}_1 + (x_4 + z_4) \mathbf{a}_2 + (x_4 + \frac{1}{4}) \mathbf{a}_3$	$=$	$ax_4 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8i)	B II
\mathbf{B}_{12}	$(z_4 + \frac{1}{4}) \mathbf{a}_1 - (x_4 - z_4) \mathbf{a}_2 - (x_4 - \frac{1}{4}) \mathbf{a}_3$	$=$	$-ax_4 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8i)	B II
\mathbf{B}_{13}	$-(z_4 - \frac{3}{4}) \mathbf{a}_1 - (x_4 + z_4) \mathbf{a}_2 - (x_4 - \frac{3}{4}) \mathbf{a}_3$	$=$	$-ax_4 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(8i)	B II
\mathbf{B}_{14}	$-(z_4 - \frac{3}{4}) \mathbf{a}_1 + (x_4 - z_4) \mathbf{a}_2 + (x_4 + \frac{3}{4}) \mathbf{a}_3$	$=$	$ax_4 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(8i)	B II
\mathbf{B}_{15}	$(z_5 + \frac{1}{4}) \mathbf{a}_1 + (x_5 + z_5) \mathbf{a}_2 + (x_5 + \frac{1}{4}) \mathbf{a}_3$	$=$	$ax_5 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8i)	B III
\mathbf{B}_{16}	$(z_5 + \frac{1}{4}) \mathbf{a}_1 - (x_5 - z_5) \mathbf{a}_2 - (x_5 - \frac{1}{4}) \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8i)	B III
\mathbf{B}_{17}	$-(z_5 - \frac{3}{4}) \mathbf{a}_1 - (x_5 + z_5) \mathbf{a}_2 - (x_5 - \frac{3}{4}) \mathbf{a}_3$	$=$	$-ax_5 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$	(8i)	B III

$$\begin{aligned}
\mathbf{B}_{18} &= -\left(z_5 - \frac{3}{4}\right) \mathbf{a}_1 + (x_5 - z_5) \mathbf{a}_2 + &= & ax_5 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}} & (8i) & \text{B III} \\
&\quad \left(x_5 + \frac{3}{4}\right) \mathbf{a}_3 \\
\mathbf{B}_{19} &= (y_6 + z_6) \mathbf{a}_1 + (x_6 + z_6) \mathbf{a}_2 + &= & ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16j) & \text{B IV} \\
&\quad (x_6 + y_6) \mathbf{a}_3 \\
\mathbf{B}_{20} &= \left(-y_6 + z_6 + \frac{1}{2}\right) \mathbf{a}_1 - &= & -ax_6 \hat{\mathbf{x}} - b\left(y_6 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16j) & \text{B IV} \\
&\quad (x_6 - z_6) \mathbf{a}_2 - \left(x_6 + y_6 - \frac{1}{2}\right) \mathbf{a}_3 \\
\mathbf{B}_{21} &= \left(y_6 - z_6 + \frac{1}{2}\right) \mathbf{a}_1 - (x_6 + z_6) \mathbf{a}_2 + &= & -ax_6 \hat{\mathbf{x}} + b\left(y_6 + \frac{1}{2}\right) \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16j) & \text{B IV} \\
&\quad \left(-x_6 + y_6 + \frac{1}{2}\right) \mathbf{a}_3 \\
\mathbf{B}_{22} &= -(y_6 + z_6) \mathbf{a}_1 + (x_6 - z_6) \mathbf{a}_2 + &= & ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16j) & \text{B IV} \\
&\quad (x_6 - y_6) \mathbf{a}_3 \\
\mathbf{B}_{23} &= -(y_6 + z_6) \mathbf{a}_1 - (x_6 + z_6) \mathbf{a}_2 - &= & -ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16j) & \text{B IV} \\
&\quad (x_6 + y_6) \mathbf{a}_3 \\
\mathbf{B}_{24} &= \left(y_6 - z_6 + \frac{1}{2}\right) \mathbf{a}_1 + &= & ax_6 \hat{\mathbf{x}} + b\left(y_6 + \frac{1}{2}\right) \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (16j) & \text{B IV} \\
&\quad (x_6 - z_6) \mathbf{a}_2 + \left(x_6 + y_6 + \frac{1}{2}\right) \mathbf{a}_3 \\
\mathbf{B}_{25} &= \left(-y_6 + z_6 + \frac{1}{2}\right) \mathbf{a}_1 + &= & ax_6 \hat{\mathbf{x}} - b\left(y_6 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16j) & \text{B IV} \\
&\quad (x_6 + z_6) \mathbf{a}_2 + \left(x_6 - y_6 + \frac{1}{2}\right) \mathbf{a}_3 \\
\mathbf{B}_{26} &= (y_6 + z_6) \mathbf{a}_1 - (x_6 - z_6) \mathbf{a}_2 - &= & -ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16j) & \text{B IV} \\
&\quad (x_6 - y_6) \mathbf{a}_3 \\
\mathbf{B}_{27} &= (y_7 + z_7) \mathbf{a}_1 + (x_7 + z_7) \mathbf{a}_2 + &= & ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16j) & \text{B V} \\
&\quad (x_7 + y_7) \mathbf{a}_3 \\
\mathbf{B}_{28} &= \left(-y_7 + z_7 + \frac{1}{2}\right) \mathbf{a}_1 - &= & -ax_7 \hat{\mathbf{x}} - b\left(y_7 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16j) & \text{B V} \\
&\quad (x_7 - z_7) \mathbf{a}_2 - \left(x_7 + y_7 - \frac{1}{2}\right) \mathbf{a}_3 \\
\mathbf{B}_{29} &= \left(y_7 - z_7 + \frac{1}{2}\right) \mathbf{a}_1 - (x_7 + z_7) \mathbf{a}_2 + &= & -ax_7 \hat{\mathbf{x}} + b\left(y_7 + \frac{1}{2}\right) \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16j) & \text{B V} \\
&\quad \left(-x_7 + y_7 + \frac{1}{2}\right) \mathbf{a}_3 \\
\mathbf{B}_{30} &= -(y_7 + z_7) \mathbf{a}_1 + (x_7 - z_7) \mathbf{a}_2 + &= & ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16j) & \text{B V} \\
&\quad (x_7 - y_7) \mathbf{a}_3 \\
\mathbf{B}_{31} &= -(y_7 + z_7) \mathbf{a}_1 - (x_7 + z_7) \mathbf{a}_2 - &= & -ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16j) & \text{B V} \\
&\quad (x_7 + y_7) \mathbf{a}_3 \\
\mathbf{B}_{32} &= \left(y_7 - z_7 + \frac{1}{2}\right) \mathbf{a}_1 + &= & ax_7 \hat{\mathbf{x}} + b\left(y_7 + \frac{1}{2}\right) \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}} & (16j) & \text{B V} \\
&\quad (x_7 - z_7) \mathbf{a}_2 + \left(x_7 + y_7 + \frac{1}{2}\right) \mathbf{a}_3 \\
\mathbf{B}_{33} &= \left(-y_7 + z_7 + \frac{1}{2}\right) \mathbf{a}_1 + &= & ax_7 \hat{\mathbf{x}} - b\left(y_7 - \frac{1}{2}\right) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16j) & \text{B V} \\
&\quad (x_7 + z_7) \mathbf{a}_2 + \left(x_7 - y_7 + \frac{1}{2}\right) \mathbf{a}_3 \\
\mathbf{B}_{34} &= (y_7 + z_7) \mathbf{a}_1 - (x_7 - z_7) \mathbf{a}_2 - &= & -ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16j) & \text{B V} \\
&\quad (x_7 - y_7) \mathbf{a}_3
\end{aligned}$$

References

- [1] I. Higashi and T. Ito, *Refinement of the Structure of MgAlB₁₄*, J. Less-Common Met. **92**, 239–246 (1983), doi:10.1016/0022-5088(83)90490-3.