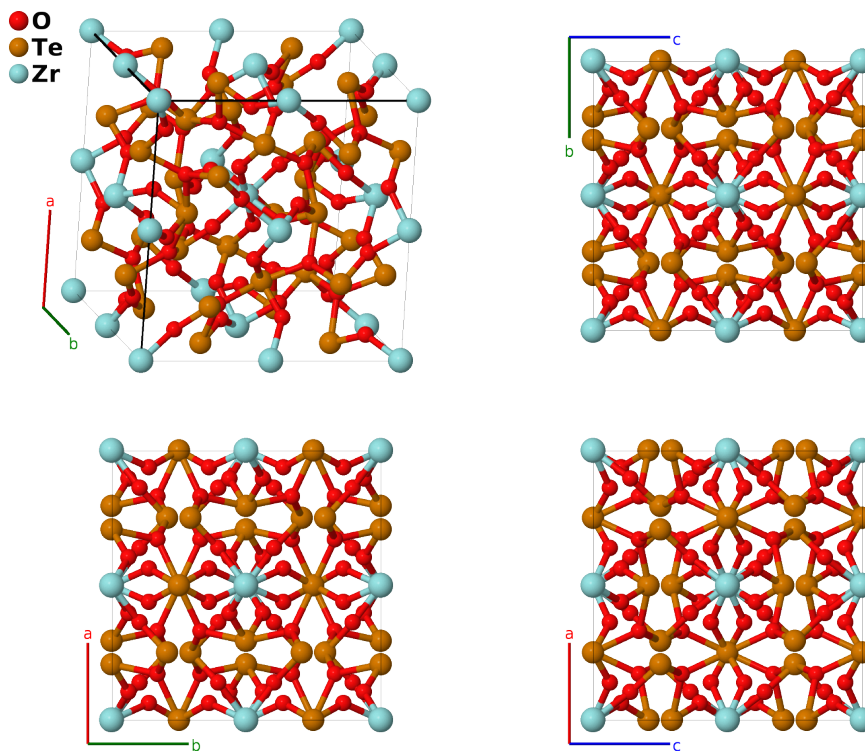


ZrTe₃O₈ Structure: A8B3C_cI96_206_ce_d_a-001

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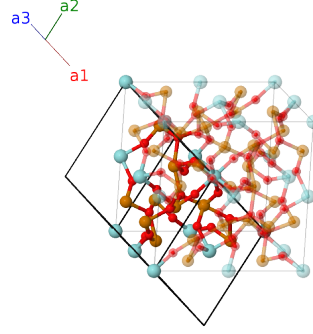
<https://aflow.org/p/3HHF>

https://aflow.org/p/A8B3C_cI96_206_ce_d_a-001



Prototype	O ₈ Te ₃ Zr
AFLOW prototype label	A8B3C_cI96_206_ce_d_a-001
ICSD	409713
Pearson symbol	cI96
Space group number	206
Space group symbol	$Ia\bar{3}$
AFLOW prototype command	<code>aflow --proto=A8B3C_cI96_206_ce_d_a-001 --params=a, x₂, x₃, x₄, y₄, z₄</code>

Body-centered Cubic primitive vectors



$$\mathbf{a}_1 = -\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}}$$

$$\mathbf{a}_2 = \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}}$$

$$\mathbf{a}_3 = \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} - \frac{1}{2}a \hat{\mathbf{z}}$$

Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	= 0	=	0	(8a)	Zr I
\mathbf{B}_2	= $\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_3$	=	$\frac{1}{2}a \hat{\mathbf{y}}$	(8a)	Zr I
\mathbf{B}_3	= $\frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	=	$\frac{1}{2}a \hat{\mathbf{x}}$	(8a)	Zr I
\mathbf{B}_4	= $\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2$	=	$\frac{1}{2}a \hat{\mathbf{z}}$	(8a)	Zr I
\mathbf{B}_5	= $2x_2 \mathbf{a}_1 + 2x_2 \mathbf{a}_2 + 2x_2 \mathbf{a}_3$	=	$ax_2 \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(16c)	O I
\mathbf{B}_6	= $\frac{1}{2} \mathbf{a}_1 - (2x_2 - \frac{1}{2}) \mathbf{a}_3$	=	$-ax_2 \hat{\mathbf{x}} - a(x_2 - \frac{1}{2}) \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(16c)	O I
\mathbf{B}_7	= $-(2x_2 - \frac{1}{2}) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	=	$-a(x_2 - \frac{1}{2}) \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(16c)	O I
\mathbf{B}_8	= $-(2x_2 - \frac{1}{2}) \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2$	=	$ax_2 \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} - a(x_2 - \frac{1}{2}) \hat{\mathbf{z}}$	(16c)	O I
\mathbf{B}_9	= $-2x_2 \mathbf{a}_1 - 2x_2 \mathbf{a}_2 - 2x_2 \mathbf{a}_3$	=	$-ax_2 \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(16c)	O I
\mathbf{B}_{10}	= $\frac{1}{2} \mathbf{a}_1 + (2x_2 + \frac{1}{2}) \mathbf{a}_3$	=	$ax_2 \hat{\mathbf{x}} + a(x_2 + \frac{1}{2}) \hat{\mathbf{y}} - ax_2 \hat{\mathbf{z}}$	(16c)	O I
\mathbf{B}_{11}	= $(2x_2 + \frac{1}{2}) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	=	$a(x_2 + \frac{1}{2}) \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} + ax_2 \hat{\mathbf{z}}$	(16c)	O I
\mathbf{B}_{12}	= $(2x_2 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2$	=	$-ax_2 \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} + a(x_2 + \frac{1}{2}) \hat{\mathbf{z}}$	(16c)	O I
\mathbf{B}_{13}	= $\frac{1}{4} \mathbf{a}_1 + (x_3 + \frac{1}{4}) \mathbf{a}_2 + x_3 \mathbf{a}_3$	=	$ax_3 \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{14}	= $\frac{3}{4} \mathbf{a}_1 - (x_3 - \frac{1}{4}) \mathbf{a}_2 - (x_3 - \frac{1}{2}) \mathbf{a}_3$	=	$-ax_3 \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{4}a \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{15}	= $x_3 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + (x_3 + \frac{1}{4}) \mathbf{a}_3$	=	$\frac{1}{4}a \hat{\mathbf{x}} + ax_3 \hat{\mathbf{y}}$	(24d)	Te I
\mathbf{B}_{16}	= $-(x_3 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - (x_3 - \frac{1}{4}) \mathbf{a}_3$	=	$\frac{1}{4}a \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}} + \frac{1}{2}a \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{17}	= $(x_3 + \frac{1}{4}) \mathbf{a}_1 + x_3 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	=	$\frac{1}{4}a \hat{\mathbf{y}} + ax_3 \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{18}	= $-(x_3 - \frac{1}{4}) \mathbf{a}_1 - (x_3 - \frac{1}{2}) \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	=	$\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{y}} - ax_3 \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{19}	= $\frac{3}{4} \mathbf{a}_1 - (x_3 - \frac{3}{4}) \mathbf{a}_2 - x_3 \mathbf{a}_3$	=	$-ax_3 \hat{\mathbf{x}} + \frac{3}{4}a \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{20}	= $\frac{1}{4} \mathbf{a}_1 + (x_3 + \frac{3}{4}) \mathbf{a}_2 + (x_3 + \frac{1}{2}) \mathbf{a}_3$	=	$a(x_3 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}a \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{21}	= $-x_3 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - (x_3 - \frac{3}{4}) \mathbf{a}_3$	=	$\frac{3}{4}a \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}}$	(24d)	Te I
\mathbf{B}_{22}	= $(x_3 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + (x_3 + \frac{3}{4}) \mathbf{a}_3$	=	$\frac{1}{4}a \hat{\mathbf{x}} + a(x_3 + \frac{1}{2}) \hat{\mathbf{y}}$	(24d)	Te I
\mathbf{B}_{23}	= $-(x_3 - \frac{3}{4}) \mathbf{a}_1 - x_3 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	=	$\frac{3}{4}a \hat{\mathbf{y}} - ax_3 \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{24}	= $(x_3 + \frac{3}{4}) \mathbf{a}_1 + (x_3 + \frac{1}{2}) \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	=	$\frac{1}{4}a \hat{\mathbf{y}} + a(x_3 + \frac{1}{2}) \hat{\mathbf{z}}$	(24d)	Te I
\mathbf{B}_{25}	= $(y_4 + z_4) \mathbf{a}_1 + (x_4 + z_4) \mathbf{a}_2 + (x_4 + y_4) \mathbf{a}_3$	=	$ax_4 \hat{\mathbf{x}} + ay_4 \hat{\mathbf{y}} + az_4 \hat{\mathbf{z}}$	(48e)	O II
\mathbf{B}_{26}	= $(-y_4 + z_4 + \frac{1}{2}) \mathbf{a}_1 - (x_4 - z_4) \mathbf{a}_2 - (x_4 + y_4 - \frac{1}{2}) \mathbf{a}_3$	=	$-ax_4 \hat{\mathbf{x}} - a(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + az_4 \hat{\mathbf{z}}$	(48e)	O II

$$\begin{aligned}
\mathbf{B}_{27} &= (y_4 - z_4) \mathbf{a}_1 - (x_4 + z_4 - \frac{1}{2}) \mathbf{a}_2 + (-x_4 + y_4 + \frac{1}{2}) \mathbf{a}_3 &= & -a(x_4 - \frac{1}{2}) \hat{\mathbf{x}} + ay_4 \hat{\mathbf{y}} - az_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{28} &= -(y_4 + z_4 - \frac{1}{2}) \mathbf{a}_1 + (x_4 - z_4 + \frac{1}{2}) \mathbf{a}_2 + (x_4 - y_4) \mathbf{a}_3 &= & ax_4 \hat{\mathbf{x}} - ay_4 \hat{\mathbf{y}} - a(z_4 - \frac{1}{2}) \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{29} &= (x_4 + y_4) \mathbf{a}_1 + (y_4 + z_4) \mathbf{a}_2 + (x_4 + z_4) \mathbf{a}_3 &= & az_4 \hat{\mathbf{x}} + ax_4 \hat{\mathbf{y}} + ay_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{30} &= -(x_4 + y_4 - \frac{1}{2}) \mathbf{a}_1 + (-y_4 + z_4 + \frac{1}{2}) \mathbf{a}_2 - (x_4 - z_4) \mathbf{a}_3 &= & az_4 \hat{\mathbf{x}} - ax_4 \hat{\mathbf{y}} - a(y_4 - \frac{1}{2}) \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{31} &= (-x_4 + y_4 + \frac{1}{2}) \mathbf{a}_1 + (y_4 - z_4) \mathbf{a}_2 - (x_4 + z_4 - \frac{1}{2}) \mathbf{a}_3 &= & -az_4 \hat{\mathbf{x}} - a(x_4 - \frac{1}{2}) \hat{\mathbf{y}} + ay_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{32} &= (x_4 - y_4) \mathbf{a}_1 - (y_4 + z_4 - \frac{1}{2}) \mathbf{a}_2 + (x_4 - z_4 + \frac{1}{2}) \mathbf{a}_3 &= & -a(z_4 - \frac{1}{2}) \hat{\mathbf{x}} + ax_4 \hat{\mathbf{y}} - ay_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{33} &= (x_4 + z_4) \mathbf{a}_1 + (x_4 + y_4) \mathbf{a}_2 + (y_4 + z_4) \mathbf{a}_3 &= & ay_4 \hat{\mathbf{x}} + az_4 \hat{\mathbf{y}} + ax_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{34} &= -(x_4 - z_4) \mathbf{a}_1 - (x_4 + y_4 - \frac{1}{2}) \mathbf{a}_2 + (-y_4 + z_4 + \frac{1}{2}) \mathbf{a}_3 &= & -a(y_4 - \frac{1}{2}) \hat{\mathbf{x}} + az_4 \hat{\mathbf{y}} - ax_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{35} &= -(x_4 + z_4 - \frac{1}{2}) \mathbf{a}_1 + (-x_4 + y_4 + \frac{1}{2}) \mathbf{a}_2 + (y_4 - z_4) \mathbf{a}_3 &= & ay_4 \hat{\mathbf{x}} - az_4 \hat{\mathbf{y}} - a(x_4 - \frac{1}{2}) \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{36} &= (x_4 - z_4 + \frac{1}{2}) \mathbf{a}_1 + (x_4 - y_4) \mathbf{a}_2 - (y_4 + z_4 - \frac{1}{2}) \mathbf{a}_3 &= & -ay_4 \hat{\mathbf{x}} - a(z_4 - \frac{1}{2}) \hat{\mathbf{y}} + ax_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{37} &= -(y_4 + z_4) \mathbf{a}_1 - (x_4 + z_4) \mathbf{a}_2 - (x_4 + y_4) \mathbf{a}_3 &= & -ax_4 \hat{\mathbf{x}} - ay_4 \hat{\mathbf{y}} - az_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{38} &= (y_4 - z_4 + \frac{1}{2}) \mathbf{a}_1 + (x_4 - z_4) \mathbf{a}_2 + (x_4 + y_4 + \frac{1}{2}) \mathbf{a}_3 &= & ax_4 \hat{\mathbf{x}} + a(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - az_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{39} &= -(y_4 - z_4) \mathbf{a}_1 + (x_4 + z_4 + \frac{1}{2}) \mathbf{a}_2 + (x_4 - y_4 + \frac{1}{2}) \mathbf{a}_3 &= & a(x_4 + \frac{1}{2}) \hat{\mathbf{x}} - ay_4 \hat{\mathbf{y}} + az_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{40} &= (y_4 + z_4 + \frac{1}{2}) \mathbf{a}_1 + (-x_4 + z_4 + \frac{1}{2}) \mathbf{a}_2 - (x_4 - y_4) \mathbf{a}_3 &= & -ax_4 \hat{\mathbf{x}} + ay_4 \hat{\mathbf{y}} + a(z_4 + \frac{1}{2}) \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{41} &= -(x_4 + y_4) \mathbf{a}_1 - (y_4 + z_4) \mathbf{a}_2 - (x_4 + z_4) \mathbf{a}_3 &= & -az_4 \hat{\mathbf{x}} - ax_4 \hat{\mathbf{y}} - ay_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{42} &= (x_4 + y_4 + \frac{1}{2}) \mathbf{a}_1 + (y_4 - z_4 + \frac{1}{2}) \mathbf{a}_2 + (x_4 - z_4) \mathbf{a}_3 &= & -az_4 \hat{\mathbf{x}} + ax_4 \hat{\mathbf{y}} + a(y_4 + \frac{1}{2}) \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{43} &= (x_4 - y_4 + \frac{1}{2}) \mathbf{a}_1 - (y_4 - z_4) \mathbf{a}_2 + (x_4 + z_4 + \frac{1}{2}) \mathbf{a}_3 &= & az_4 \hat{\mathbf{x}} + a(x_4 + \frac{1}{2}) \hat{\mathbf{y}} - ay_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{44} &= -(x_4 - y_4) \mathbf{a}_1 + (y_4 + z_4 + \frac{1}{2}) \mathbf{a}_2 + (-x_4 + z_4 + \frac{1}{2}) \mathbf{a}_3 &= & a(z_4 + \frac{1}{2}) \hat{\mathbf{x}} - ax_4 \hat{\mathbf{y}} + ay_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{45} &= -(x_4 + z_4) \mathbf{a}_1 - (x_4 + y_4) \mathbf{a}_2 - (y_4 + z_4) \mathbf{a}_3 &= & -ay_4 \hat{\mathbf{x}} - az_4 \hat{\mathbf{y}} - ax_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{46} &= (x_4 - z_4) \mathbf{a}_1 + (x_4 + y_4 + \frac{1}{2}) \mathbf{a}_2 + (y_4 - z_4 + \frac{1}{2}) \mathbf{a}_3 &= & a(y_4 + \frac{1}{2}) \hat{\mathbf{x}} - az_4 \hat{\mathbf{y}} + ax_4 \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{47} &= (x_4 + z_4 + \frac{1}{2}) \mathbf{a}_1 + (x_4 - y_4 + \frac{1}{2}) \mathbf{a}_2 - (y_4 - z_4) \mathbf{a}_3 &= & -ay_4 \hat{\mathbf{x}} + az_4 \hat{\mathbf{y}} + a(x_4 + \frac{1}{2}) \hat{\mathbf{z}} & (48e) & \text{O II} \\
\mathbf{B}_{48} &= (-x_4 + z_4 + \frac{1}{2}) \mathbf{a}_1 - (x_4 - y_4) \mathbf{a}_2 + (y_4 + z_4 + \frac{1}{2}) \mathbf{a}_3 &= & ay_4 \hat{\mathbf{x}} + a(z_4 + \frac{1}{2}) \hat{\mathbf{y}} - ax_4 \hat{\mathbf{z}} & (48e) & \text{O II}
\end{aligned}$$

References

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