

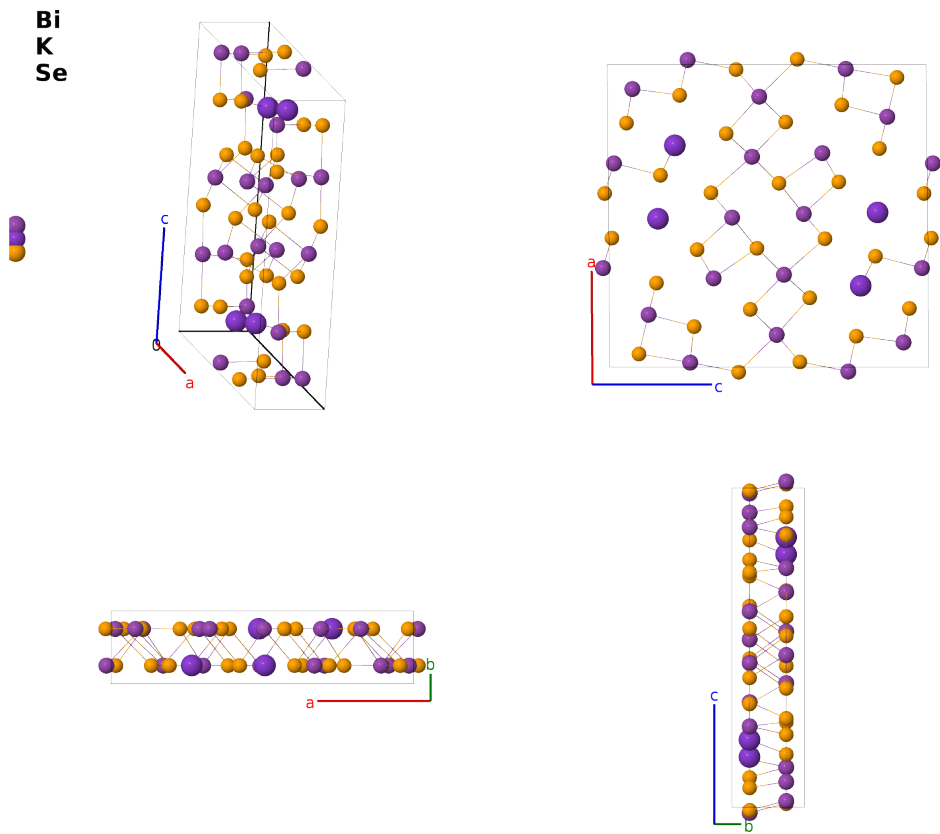
# $\beta$ -K<sub>2</sub>Bi<sub>8</sub>Se<sub>13</sub> Structure: A8B2C13\_mP46\_11\_8e\_2e\_13e-001

Cite this page as:

- H. Eckert, S. Divilov, M. J. Mehl, D. Hicks, A. C. Zettl, M. Esters, X. Campilongo, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*, Comput. Mater. Sci. **240**, 112988 (2024), doi: 10.1016/j.commatsci.2024.112988.
- D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/68FX>

[https://aflow.org/prototype-encyclopedia/A8B2C13\\_mP46\\_11\\_8e\\_2e\\_13e-001](https://aflow.org/prototype-encyclopedia/A8B2C13_mP46_11_8e_2e_13e-001)



|                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |
|-------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Prototype               | Bi <sub>8</sub> K <sub>2</sub> Se <sub>13</sub>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |
| AFLOW prototype label   | A8B2C13_mP46_11_8e_2e_13e-001                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
| ICSD                    | 84268                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
| CCDC                    | 1644272                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |
| Pearson symbol          | mP46                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |
| Space group number      | 11                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
| Space group symbol      | $P2_1/m$                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| AFLOW prototype command | <pre>aflow --proto=A8B2C13_mP46_11_8e_2e_13e-001 --params=a,b/a,c/a,<math>\beta</math>,<math>x_1</math>,<math>z_1</math>,<math>x_2</math>,<math>z_2</math>,<math>x_3</math>,<math>z_3</math>,<math>x_4</math>,<math>z_4</math>,<math>x_5</math>,<math>z_5</math>,<math>x_6</math>,<math>z_6</math>,<math>x_7</math>,<math>z_7</math>,<math>x_8</math>,<math>z_8</math>,<math>x_9</math>,<math>z_9</math>,<math>x_{10}</math>,<math>z_{10}</math>,<math>x_{11}</math>,<math>z_{11}</math>,<math>x_{12}</math>,<math>z_{12}</math>,<math>x_{13}</math>,<math>z_{13}</math>,<math>x_{14}</math>,<math>z_{14}</math>,<math>x_{15}</math>,<math>z_{15}</math>,<math>x_{16}</math>,<math>z_{16}</math>,<math>x_{17}</math>,<math>z_{17}</math>,<math>x_{18}</math>,<math>z_{18}</math>,<math>x_{19}</math>,<math>z_{19}</math>,<math>x_{20}</math>,<math>z_{20}</math>,<math>x_{21}</math>,<math>z_{21}</math>,<math>x_{22}</math>,<math>z_{22}</math>,<math>x_{23}</math>,<math>z_{23}</math></pre> |

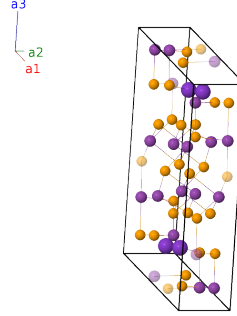
## Other compounds with this structure

Eu<sub>4</sub>Bi<sub>6</sub>Se<sub>13</sub>, Sr<sub>4</sub>Bi<sub>6</sub>Se<sub>13</sub>

- The Bi VIII site is actually 62% bismuth and 38% potassium, while the K I site is 62% potassium and 38% bismuth.
- K<sub>2</sub>Bi<sub>8</sub>Se<sub>13</sub> can also be found in the triclinic  $\alpha$  phase, which has no compositional disorder.

## Simple Monoclinic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}} \end{aligned}$$



## Basis vectors

|                       | Lattice<br>coordinates                                                  |   | Cartesian<br>coordinates                                                                                                 | Wyckoff<br>position | Atom<br>type |
|-----------------------|-------------------------------------------------------------------------|---|--------------------------------------------------------------------------------------------------------------------------|---------------------|--------------|
| <b>B<sub>1</sub></b>  | $x_1 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_1 \mathbf{a}_3$        | = | $(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$           | (2e)                | Bi I         |
| <b>B<sub>2</sub></b>  | $-x_1 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_1 \mathbf{a}_3$       | = | $-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$          | (2e)                | Bi I         |
| <b>B<sub>3</sub></b>  | $x_2 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_2 \mathbf{a}_3$        | = | $(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$           | (2e)                | Bi II        |
| <b>B<sub>4</sub></b>  | $-x_2 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_2 \mathbf{a}_3$       | = | $-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$          | (2e)                | Bi II        |
| <b>B<sub>5</sub></b>  | $x_3 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_3 \mathbf{a}_3$        | = | $(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$           | (2e)                | Bi III       |
| <b>B<sub>6</sub></b>  | $-x_3 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_3 \mathbf{a}_3$       | = | $-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$          | (2e)                | Bi III       |
| <b>B<sub>7</sub></b>  | $x_4 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_4 \mathbf{a}_3$        | = | $(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$           | (2e)                | Bi IV        |
| <b>B<sub>8</sub></b>  | $-x_4 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_4 \mathbf{a}_3$       | = | $-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$          | (2e)                | Bi IV        |
| <b>B<sub>9</sub></b>  | $x_5 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_5 \mathbf{a}_3$        | = | $(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$           | (2e)                | Bi V         |
| <b>B<sub>10</sub></b> | $-x_5 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_5 \mathbf{a}_3$       | = | $-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$          | (2e)                | Bi V         |
| <b>B<sub>11</sub></b> | $x_6 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_6 \mathbf{a}_3$        | = | $(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$           | (2e)                | Bi VI        |
| <b>B<sub>12</sub></b> | $-x_6 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_6 \mathbf{a}_3$       | = | $-(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}}$          | (2e)                | Bi VI        |
| <b>B<sub>13</sub></b> | $x_7 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_7 \mathbf{a}_3$        | = | $(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}}$           | (2e)                | Bi VII       |
| <b>B<sub>14</sub></b> | $-x_7 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_7 \mathbf{a}_3$       | = | $-(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}}$          | (2e)                | Bi VII       |
| <b>B<sub>15</sub></b> | $x_8 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_8 \mathbf{a}_3$        | = | $(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}}$           | (2e)                | Bi VIII      |
| <b>B<sub>16</sub></b> | $-x_8 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_8 \mathbf{a}_3$       | = | $-(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}}$          | (2e)                | Bi VIII      |
| <b>B<sub>17</sub></b> | $x_9 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_9 \mathbf{a}_3$        | = | $(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}}$           | (2e)                | K I          |
| <b>B<sub>18</sub></b> | $-x_9 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_9 \mathbf{a}_3$       | = | $-(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}}$          | (2e)                | K I          |
| <b>B<sub>19</sub></b> | $x_{10} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{10} \mathbf{a}_3$  | = | $(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}}$  | (2e)                | K II         |
| <b>B<sub>20</sub></b> | $-x_{10} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{10} \mathbf{a}_3$ | = | $-(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_{10} \sin \beta \hat{\mathbf{z}}$ | (2e)                | K II         |
| <b>B<sub>21</sub></b> | $x_{11} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{11} \mathbf{a}_3$  | = | $(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_{11} \sin \beta \hat{\mathbf{z}}$  | (2e)                | Se I         |
| <b>B<sub>22</sub></b> | $-x_{11} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{11} \mathbf{a}_3$ | = | $-(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_{11} \sin \beta \hat{\mathbf{z}}$ | (2e)                | Se I         |

|                     |                                                                         |     |                                                                                                                           |      |         |
|---------------------|-------------------------------------------------------------------------|-----|---------------------------------------------------------------------------------------------------------------------------|------|---------|
| $\mathbf{B}_{23} =$ | $x_{12} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{12} \mathbf{a}_3$  | $=$ | $(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{12} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se II   |
| $\mathbf{B}_{24} =$ | $-x_{12} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{12} \mathbf{a}_3$ | $=$ | $-(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{12} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se II   |
| $\mathbf{B}_{25} =$ | $x_{13} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{13} \mathbf{a}_3$  | $=$ | $(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{13} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se III  |
| $\mathbf{B}_{26} =$ | $-x_{13} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{13} \mathbf{a}_3$ | $=$ | $-(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{13} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se III  |
| $\mathbf{B}_{27} =$ | $x_{14} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{14} \mathbf{a}_3$  | $=$ | $(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{14} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se IV   |
| $\mathbf{B}_{28} =$ | $-x_{14} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{14} \mathbf{a}_3$ | $=$ | $-(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{14} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se IV   |
| $\mathbf{B}_{29} =$ | $x_{15} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{15} \mathbf{a}_3$  | $=$ | $(ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{15} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se V    |
| $\mathbf{B}_{30} =$ | $-x_{15} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{15} \mathbf{a}_3$ | $=$ | $-(ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{15} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se V    |
| $\mathbf{B}_{31} =$ | $x_{16} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{16} \mathbf{a}_3$  | $=$ | $(ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{16} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se VI   |
| $\mathbf{B}_{32} =$ | $-x_{16} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{16} \mathbf{a}_3$ | $=$ | $-(ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{16} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se VI   |
| $\mathbf{B}_{33} =$ | $x_{17} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{17} \mathbf{a}_3$  | $=$ | $(ax_{17} + cz_{17} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{17} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se VII  |
| $\mathbf{B}_{34} =$ | $-x_{17} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{17} \mathbf{a}_3$ | $=$ | $-(ax_{17} + cz_{17} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{17} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se VII  |
| $\mathbf{B}_{35} =$ | $x_{18} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{18} \mathbf{a}_3$  | $=$ | $(ax_{18} + cz_{18} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{18} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se VIII |
| $\mathbf{B}_{36} =$ | $-x_{18} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{18} \mathbf{a}_3$ | $=$ | $-(ax_{18} + cz_{18} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{18} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se VIII |
| $\mathbf{B}_{37} =$ | $x_{19} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{19} \mathbf{a}_3$  | $=$ | $(ax_{19} + cz_{19} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{19} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se IX   |
| $\mathbf{B}_{38} =$ | $-x_{19} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{19} \mathbf{a}_3$ | $=$ | $-(ax_{19} + cz_{19} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{19} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se IX   |
| $\mathbf{B}_{39} =$ | $x_{20} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{20} \mathbf{a}_3$  | $=$ | $(ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{20} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se X    |
| $\mathbf{B}_{40} =$ | $-x_{20} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{20} \mathbf{a}_3$ | $=$ | $-(ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{20} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se X    |
| $\mathbf{B}_{41} =$ | $x_{21} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{21} \mathbf{a}_3$  | $=$ | $(ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{21} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se XI   |
| $\mathbf{B}_{42} =$ | $-x_{21} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{21} \mathbf{a}_3$ | $=$ | $-(ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{21} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se XI   |
| $\mathbf{B}_{43} =$ | $x_{22} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{22} \mathbf{a}_3$  | $=$ | $(ax_{22} + cz_{22} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{22} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se XII  |
| $\mathbf{B}_{44} =$ | $-x_{22} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{22} \mathbf{a}_3$ | $=$ | $-(ax_{22} + cz_{22} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{22} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se XII  |
| $\mathbf{B}_{45} =$ | $x_{23} \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_{23} \mathbf{a}_3$  | $=$ | $(ax_{23} + cz_{23} \cos \beta) \hat{\mathbf{x}} + \frac{1}{4} b \hat{\mathbf{y}} + cz_{23} \sin \beta \hat{\mathbf{z}}$  | (2e) | Se XIII |
| $\mathbf{B}_{46} =$ | $-x_{23} \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_{23} \mathbf{a}_3$ | $=$ | $-(ax_{23} + cz_{23} \cos \beta) \hat{\mathbf{x}} + \frac{3}{4} b \hat{\mathbf{y}} - cz_{23} \sin \beta \hat{\mathbf{z}}$ | (2e) | Se XIII |

## References

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## First cited in

N. Anderson, M. J. Mehl, H. Eckert, S. Divilov, X. Campilongo, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 5*. Submitted to Computational Materials Science (2026).