

# $\alpha$ -K<sub>2</sub>Bi<sub>8</sub>Se<sub>13</sub> Structure:

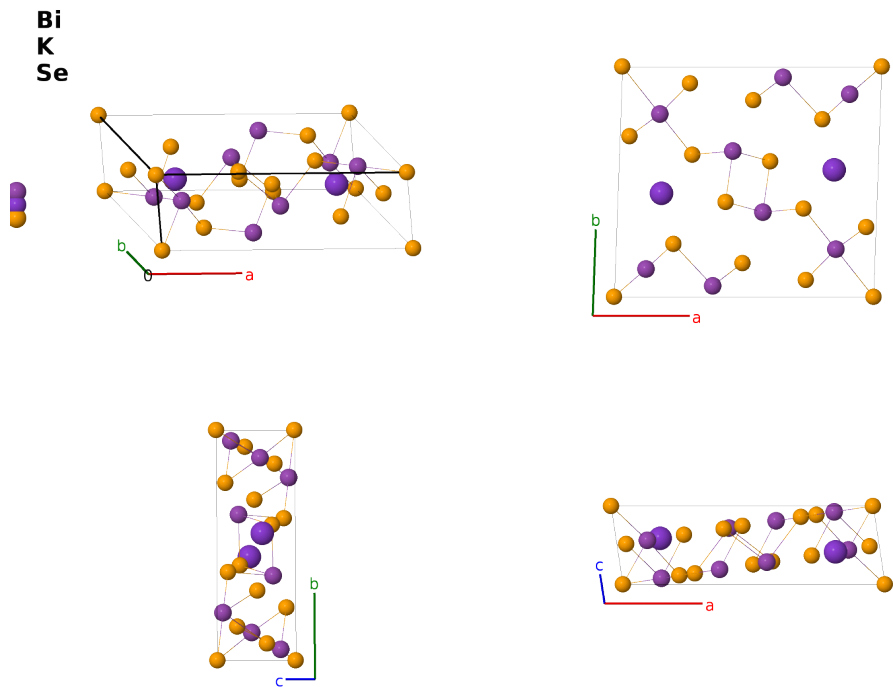
## A8B2C13\_aP23\_2\_4i\_i\_a6i-001

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- D. Hicks, M. J. Mehl, M. Esters, C. Osos, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/AT7V>

[https://aflow.org/prototype-encyclopedia/A8B2C13\\_aP23\\_2\\_4i\\_i\\_a6i-001](https://aflow.org/prototype-encyclopedia/A8B2C13_aP23_2_4i_i_a6i-001)



|                         |                                                                                                                                                                                                                   |
|-------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Prototype               | Bi <sub>8</sub> K <sub>2</sub> Se <sub>13</sub>                                                                                                                                                                   |
| AFLOW prototype label   | A8B2C13_aP23_2_4i_i_a6i-001                                                                                                                                                                                       |
| ICSD                    | 72976                                                                                                                                                                                                             |
| CCDC                    | 1633801                                                                                                                                                                                                           |
| Pearson symbol          | aP23                                                                                                                                                                                                              |
| Space group number      | 2                                                                                                                                                                                                                 |
| Space group symbol      | $P\bar{1}$                                                                                                                                                                                                        |
| AFLOW prototype command | <pre>aflow --proto=A8B2C13_aP23_2_4i_i_a6i-001       --params=a,b/a,c/a,alpha,beta,gamma,x2,y2,z2,x3,y3,z3,x4,y4,z4,x5,y5,z5,x6,y6,z6,x7,y7,       z7,x8,y8,z8,x9,y9,z9,x10,y10,z10,x11,y11,z11,x12,y12,z12</pre> |

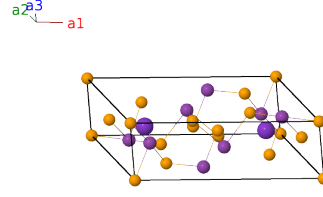
- We have shifted the Se I atom from the (1c) site to the origin at the (1a) site.

- $\text{K}_2\text{Bi}_8\text{Se}_{13}$  can also be found in the monoclinic  $\beta$  phase.

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### Triclinic primitive vectors

$$\begin{aligned}
\mathbf{a}_1 &= a \hat{\mathbf{x}} \\
\mathbf{a}_2 &= b \cos \gamma \hat{\mathbf{x}} + b \sin \gamma \hat{\mathbf{y}} \\
\mathbf{a}_3 &= c_x \hat{\mathbf{x}} + c_y \hat{\mathbf{y}} + c_z \hat{\mathbf{z}} \\
c_x &= c \cos \beta \\
c_y &= c(\cos \alpha - \cos \beta \cos \gamma) / \sin \gamma \\
c_z &= \sqrt{c^2 - c_x^2 - c_y^2}
\end{aligned}$$




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### Basis vectors

|                   | Lattice<br>coordinates |                                                           | Cartesian<br>coordinates | Wyckoff<br>position                                                                                                                | Atom<br>type |
|-------------------|------------------------|-----------------------------------------------------------|--------------------------|------------------------------------------------------------------------------------------------------------------------------------|--------------|
| $\mathbf{B}_1$    | $=$                    | $0$                                                       | $=$                      | $0$                                                                                                                                | (1a) Se I    |
| $\mathbf{B}_2$    | $=$                    | $x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$  | $=$                      | $(ax_2 + by_2 \cos \gamma + c_x z_2) \hat{\mathbf{x}} + (by_2 \sin \gamma + c_y z_2) \hat{\mathbf{y}} + c_z z_2 \hat{\mathbf{z}}$  | (2i) Bi I    |
| $\mathbf{B}_3$    | $=$                    | $-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$ | $=$                      | $-(ax_2 + by_2 \cos \gamma + c_x z_2) \hat{\mathbf{x}} - (by_2 \sin \gamma + c_y z_2) \hat{\mathbf{y}} - c_z z_2 \hat{\mathbf{z}}$ | (2i) Bi I    |
| $\mathbf{B}_4$    | $=$                    | $x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$  | $=$                      | $(ax_3 + by_3 \cos \gamma + c_x z_3) \hat{\mathbf{x}} + (by_3 \sin \gamma + c_y z_3) \hat{\mathbf{y}} + c_z z_3 \hat{\mathbf{z}}$  | (2i) Bi II   |
| $\mathbf{B}_5$    | $=$                    | $-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$ | $=$                      | $-(ax_3 + by_3 \cos \gamma + c_x z_3) \hat{\mathbf{x}} - (by_3 \sin \gamma + c_y z_3) \hat{\mathbf{y}} - c_z z_3 \hat{\mathbf{z}}$ | (2i) Bi II   |
| $\mathbf{B}_6$    | $=$                    | $x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$  | $=$                      | $(ax_4 + by_4 \cos \gamma + c_x z_4) \hat{\mathbf{x}} + (by_4 \sin \gamma + c_y z_4) \hat{\mathbf{y}} + c_z z_4 \hat{\mathbf{z}}$  | (2i) Bi III  |
| $\mathbf{B}_7$    | $=$                    | $-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$ | $=$                      | $-(ax_4 + by_4 \cos \gamma + c_x z_4) \hat{\mathbf{x}} - (by_4 \sin \gamma + c_y z_4) \hat{\mathbf{y}} - c_z z_4 \hat{\mathbf{z}}$ | (2i) Bi III  |
| $\mathbf{B}_8$    | $=$                    | $x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$  | $=$                      | $(ax_5 + by_5 \cos \gamma + c_x z_5) \hat{\mathbf{x}} + (by_5 \sin \gamma + c_y z_5) \hat{\mathbf{y}} + c_z z_5 \hat{\mathbf{z}}$  | (2i) Bi IV   |
| $\mathbf{B}_9$    | $=$                    | $-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$ | $=$                      | $-(ax_5 + by_5 \cos \gamma + c_x z_5) \hat{\mathbf{x}} - (by_5 \sin \gamma + c_y z_5) \hat{\mathbf{y}} - c_z z_5 \hat{\mathbf{z}}$ | (2i) Bi IV   |
| $\mathbf{B}_{10}$ | $=$                    | $x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$  | $=$                      | $(ax_6 + by_6 \cos \gamma + c_x z_6) \hat{\mathbf{x}} + (by_6 \sin \gamma + c_y z_6) \hat{\mathbf{y}} + c_z z_6 \hat{\mathbf{z}}$  | (2i) K I     |
| $\mathbf{B}_{11}$ | $=$                    | $-x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$ | $=$                      | $-(ax_6 + by_6 \cos \gamma + c_x z_6) \hat{\mathbf{x}} - (by_6 \sin \gamma + c_y z_6) \hat{\mathbf{y}} - c_z z_6 \hat{\mathbf{z}}$ | (2i) K I     |
| $\mathbf{B}_{12}$ | $=$                    | $x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3$  | $=$                      | $(ax_7 + by_7 \cos \gamma + c_x z_7) \hat{\mathbf{x}} + (by_7 \sin \gamma + c_y z_7) \hat{\mathbf{y}} + c_z z_7 \hat{\mathbf{z}}$  | (2i) Se II   |
| $\mathbf{B}_{13}$ | $=$                    | $-x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3$ | $=$                      | $-(ax_7 + by_7 \cos \gamma + c_x z_7) \hat{\mathbf{x}} - (by_7 \sin \gamma + c_y z_7) \hat{\mathbf{y}} - c_z z_7 \hat{\mathbf{z}}$ | (2i) Se II   |
| $\mathbf{B}_{14}$ | $=$                    | $x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3$  | $=$                      | $(ax_8 + by_8 \cos \gamma + c_x z_8) \hat{\mathbf{x}} + (by_8 \sin \gamma + c_y z_8) \hat{\mathbf{y}} + c_z z_8 \hat{\mathbf{z}}$  | (2i) Se III  |
| $\mathbf{B}_{15}$ | $=$                    | $-x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3$ | $=$                      | $-(ax_8 + by_8 \cos \gamma + c_x z_8) \hat{\mathbf{x}} - (by_8 \sin \gamma + c_y z_8) \hat{\mathbf{y}} - c_z z_8 \hat{\mathbf{z}}$ | (2i) Se III  |
| $\mathbf{B}_{16}$ | $=$                    | $x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3$  | $=$                      | $(ax_9 + by_9 \cos \gamma + c_x z_9) \hat{\mathbf{x}} + (by_9 \sin \gamma + c_y z_9) \hat{\mathbf{y}} + c_z z_9 \hat{\mathbf{z}}$  | (2i) Se IV   |

$$\begin{aligned}
\mathbf{B}_{17} &= -x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3 &= - (ax_9 + by_9 \cos \gamma + c_x z_9) \hat{\mathbf{x}} - & (2i) & \text{Se IV} \\
&&& (by_9 \sin \gamma + c_y z_9) \hat{\mathbf{y}} - c_z z_9 \hat{\mathbf{z}} \\
\mathbf{B}_{18} &= x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3 &= (ax_{10} + by_{10} \cos \gamma + c_x z_{10}) \hat{\mathbf{x}} + & (2i) & \text{Se V} \\
&&& (by_{10} \sin \gamma + c_y z_{10}) \hat{\mathbf{y}} + c_z z_{10} \hat{\mathbf{z}} \\
\mathbf{B}_{19} &= -x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3 &= - (ax_{10} + by_{10} \cos \gamma + c_x z_{10}) \hat{\mathbf{x}} - & (2i) & \text{Se V} \\
&&& (by_{10} \sin \gamma + c_y z_{10}) \hat{\mathbf{y}} - c_z z_{10} \hat{\mathbf{z}} \\
\mathbf{B}_{20} &= x_{11} \mathbf{a}_1 + y_{11} \mathbf{a}_2 + z_{11} \mathbf{a}_3 &= (ax_{11} + by_{11} \cos \gamma + c_x z_{11}) \hat{\mathbf{x}} + & (2i) & \text{Se VI} \\
&&& (by_{11} \sin \gamma + c_y z_{11}) \hat{\mathbf{y}} + c_z z_{11} \hat{\mathbf{z}} \\
\mathbf{B}_{21} &= -x_{11} \mathbf{a}_1 - y_{11} \mathbf{a}_2 - z_{11} \mathbf{a}_3 &= - (ax_{11} + by_{11} \cos \gamma + c_x z_{11}) \hat{\mathbf{x}} - & (2i) & \text{Se VI} \\
&&& (by_{11} \sin \gamma + c_y z_{11}) \hat{\mathbf{y}} - c_z z_{11} \hat{\mathbf{z}} \\
\mathbf{B}_{22} &= x_{12} \mathbf{a}_1 + y_{12} \mathbf{a}_2 + z_{12} \mathbf{a}_3 &= (ax_{12} + by_{12} \cos \gamma + c_x z_{12}) \hat{\mathbf{x}} + & (2i) & \text{Se VII} \\
&&& (by_{12} \sin \gamma + c_y z_{12}) \hat{\mathbf{y}} + c_z z_{12} \hat{\mathbf{z}} \\
\mathbf{B}_{23} &= -x_{12} \mathbf{a}_1 - y_{12} \mathbf{a}_2 - z_{12} \mathbf{a}_3 &= - (ax_{12} + by_{12} \cos \gamma + c_x z_{12}) \hat{\mathbf{x}} - & (2i) & \text{Se VII} \\
&&& (by_{12} \sin \gamma + c_y z_{12}) \hat{\mathbf{y}} - c_z z_{12} \hat{\mathbf{z}}
\end{aligned}$$

## References

- [1] T. J. McCarthy, S. P. Ngeyi, J. H. Liao, D. C. DeGroot, T. Hogan, C. R. Kannewurf, and M. G. Kanatzidis, *Molten salt synthesis and properties of three new solid-state ternary bismuth chalcogenides,  $\beta$ -CsBiS<sub>2</sub>,  $\gamma$ -CsBiS<sub>2</sub>, and K<sub>2</sub>Bi<sub>8</sub>Se<sub>13</sub>*, Chem. Mater. **5**, 331–340 (1993), doi:10.1021/cm00027a016.

## Found in

- [1] D. I. Bilc, S. D. Mahanti, T. Kyratsi, D. Y. Chung, M. G. Kanatzidis, , and P. Larson, *Electronic structure of K<sub>2</sub>Bi<sub>8</sub>Se<sub>13</sub>*, Phys. Rev. B **71**, 085116 (2005), doi:10.1103/PhysRevB.71.085116.

## First cited in

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