

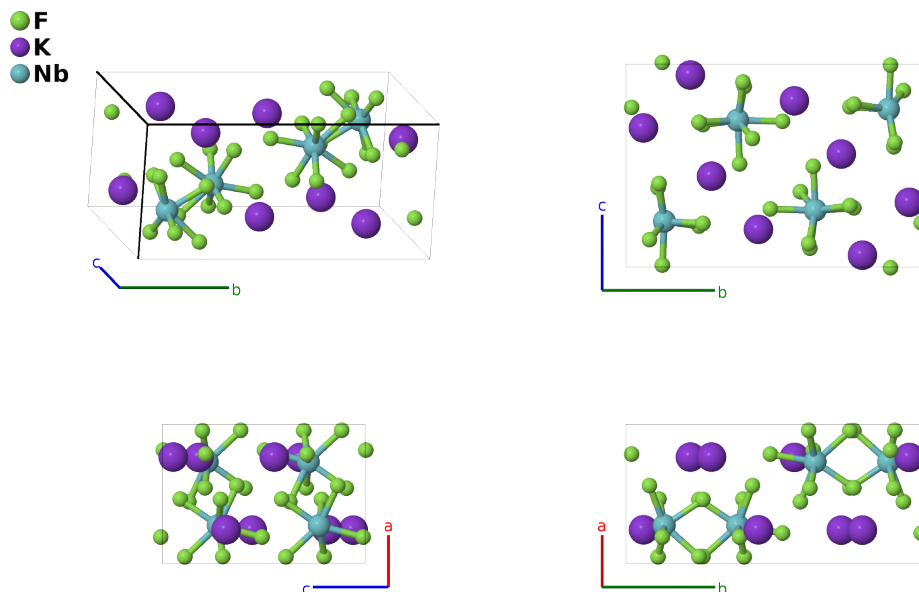
K₂NbF₇ (*K6*₂) Structure: A7B2C_mP40_14_7e_2e_e-001

This structure originally had the label A7B2C_mP40_14_7e_2e_e. Calls to that address will be redirected here.

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<https://afLOW.org/p/TF3J>

https://afLOW.org/p/A7B2C_mP40_14_7e_2e_e-001

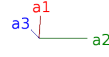


Prototype	F ₇ K ₂ Nb
AFLOW prototype label	A7B2C_mP40_14_7e_2e_e-001
<i>Strukturbericht</i> designation	<i>K6</i> ₂
ICSD	14132
Pearson symbol	mP40
Space group number	14
Space group symbol	<i>P2</i> ₁ / <i>c</i>
AFLOW prototype command	afLOW --proto=A7B2C_mP40_14_7e_2e_e-001 --params= <i>a</i> , <i>b/a</i> , <i>c/a</i> , β , <i>x</i> ₁ , <i>y</i> ₁ , <i>z</i> ₁ , <i>x</i> ₂ , <i>y</i> ₂ , <i>z</i> ₂ , <i>x</i> ₃ , <i>y</i> ₃ , <i>z</i> ₃ , <i>x</i> ₄ , <i>y</i> ₄ , <i>z</i> ₄ , <i>x</i> ₅ , <i>y</i> ₅ , <i>z</i> ₅ , <i>x</i> ₆ , <i>y</i> ₆ , <i>z</i> ₆ , <i>x</i> ₇ , <i>y</i> ₇ , <i>z</i> ₇ , <i>x</i> ₈ , <i>y</i> ₈ , <i>z</i> ₈ , <i>x</i> ₉ , <i>y</i> ₉ , <i>z</i> ₉ , <i>x</i> ₁₀ , <i>y</i> ₁₀ , <i>z</i> ₁₀

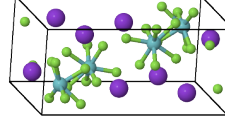
Other compounds with this structure

K₂TaF₇

Simple Monoclinic primitive vectors



$$\begin{aligned}
 \mathbf{a}_1 &= a \hat{\mathbf{x}} \\
 \mathbf{a}_2 &= b \hat{\mathbf{y}} \\
 \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}
 \end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	=	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	F I
\mathbf{B}_2	$-x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F I
\mathbf{B}_3	$-x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	=	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	F I
\mathbf{B}_4	$x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F I
\mathbf{B}_5	$x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	=	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	F II
\mathbf{B}_6	$-x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F II
\mathbf{B}_7	$-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	=	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	F II
\mathbf{B}_8	$x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F II
\mathbf{B}_9	$x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	=	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	F III
\mathbf{B}_{10}	$-x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F III
\mathbf{B}_{11}	$-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	=	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	F III
\mathbf{B}_{12}	$x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F III
\mathbf{B}_{13}	$x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	=	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	F IV
\mathbf{B}_{14}	$-x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F IV
\mathbf{B}_{15}	$-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	=	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	F IV
\mathbf{B}_{16}	$x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F IV
\mathbf{B}_{17}	$x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	=	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	F V
\mathbf{B}_{18}	$-x_5 \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F V
\mathbf{B}_{19}	$-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	=	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	F V
\mathbf{B}_{20}	$x_5 \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F V
\mathbf{B}_{21}	$x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	=	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	F VI
\mathbf{B}_{22}	$-x_6 \mathbf{a}_1 + (y_6 + \frac{1}{2}) \mathbf{a}_2 - (z_6 - \frac{1}{2}) \mathbf{a}_3$	=	$-(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	F VI
\mathbf{B}_{23}	$-x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	=	$-(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	F VI

$$\begin{aligned}
\mathbf{B}_{24} &= x_6 \mathbf{a}_1 - \left(y_6 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_6 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} &(ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ &b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{F VI} \\
\mathbf{B}_{25} &= x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3 = (ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VII} \\
\mathbf{B}_{26} &= -x_7 \mathbf{a}_1 + \left(y_7 + \frac{1}{2}\right) \mathbf{a}_2 - \begin{aligned} &(z_7 - \frac{1}{2}) \mathbf{a}_3 \end{aligned} = \begin{aligned} &-(ax_7 + c(z_7 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + \\ &b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{F VII} \\
\mathbf{B}_{27} &= -x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3 = -(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}} & (4e) & \text{F VII} \\
\mathbf{B}_{28} &= x_7 \mathbf{a}_1 - \left(y_7 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_7 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} &(ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ &b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{F VII} \\
\mathbf{B}_{29} &= x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3 = (ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}} & (4e) & \text{K I} \\
\mathbf{B}_{30} &= -x_8 \mathbf{a}_1 + \left(y_8 + \frac{1}{2}\right) \mathbf{a}_2 - \begin{aligned} &(z_8 - \frac{1}{2}) \mathbf{a}_3 \end{aligned} = \begin{aligned} &-(ax_8 + c(z_8 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + \\ &b(y_8 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{K I} \\
\mathbf{B}_{31} &= -x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3 = -(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}} & (4e) & \text{K I} \\
\mathbf{B}_{32} &= x_8 \mathbf{a}_1 - \left(y_8 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_8 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} &(ax_8 + c(z_8 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ &b(y_8 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{K I} \\
\mathbf{B}_{33} &= x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3 = (ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}} & (4e) & \text{K II} \\
\mathbf{B}_{34} &= -x_9 \mathbf{a}_1 + \left(y_9 + \frac{1}{2}\right) \mathbf{a}_2 - \begin{aligned} &(z_9 - \frac{1}{2}) \mathbf{a}_3 \end{aligned} = \begin{aligned} &-(ax_9 + c(z_9 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + \\ &b(y_9 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_9 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{K II} \\
\mathbf{B}_{35} &= -x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3 = -(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}} & (4e) & \text{K II} \\
\mathbf{B}_{36} &= x_9 \mathbf{a}_1 - \left(y_9 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_9 + \frac{1}{2}\right) \mathbf{a}_3 = \begin{aligned} &(ax_9 + c(z_9 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ &b(y_9 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_9 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{K II} \\
\mathbf{B}_{37} &= x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3 = (ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}} & (4e) & \text{Nb I} \\
\mathbf{B}_{38} &= -x_{10} \mathbf{a}_1 + \left(y_{10} + \frac{1}{2}\right) \mathbf{a}_2 - \begin{aligned} &(z_{10} - \frac{1}{2}) \mathbf{a}_3 \end{aligned} = \begin{aligned} &-(ax_{10} + c(z_{10} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + \\ &b(y_{10} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{10} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{Nb I} \\
\mathbf{B}_{39} &= -x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3 = \begin{aligned} &-(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} - \\ &cz_{10} \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{Nb I} \\
\mathbf{B}_{40} &= x_{10} \mathbf{a}_1 - \left(y_{10} - \frac{1}{2}\right) \mathbf{a}_2 + \begin{aligned} &(z_{10} + \frac{1}{2}) \mathbf{a}_3 \end{aligned} = \begin{aligned} &(ax_{10} + c(z_{10} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - \\ &b(y_{10} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{10} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{aligned} & (4e) & \text{Nb I}
\end{aligned}$$

References

- [1] G. M. Brown and L. A. Walker, *Refinement of the structure of potassium heptafluoronioate, $K_2\text{NbF}_7$, from neutron-diffraction data*, Acta Cryst. **20**, 220–229 (1966), doi:10.1107/S0365110X66000458.

Found in

- [1] C. C. Torardi, L. H. Brixner, and G. Blasse, *Structure and luminescence of $K_2\text{TaF}_7$ and $K_2\text{NbF}_7$* , J. Solid State Chem. **67**, 21–25 (1987), doi:10.1016/0022-4596(87)90333-1.