

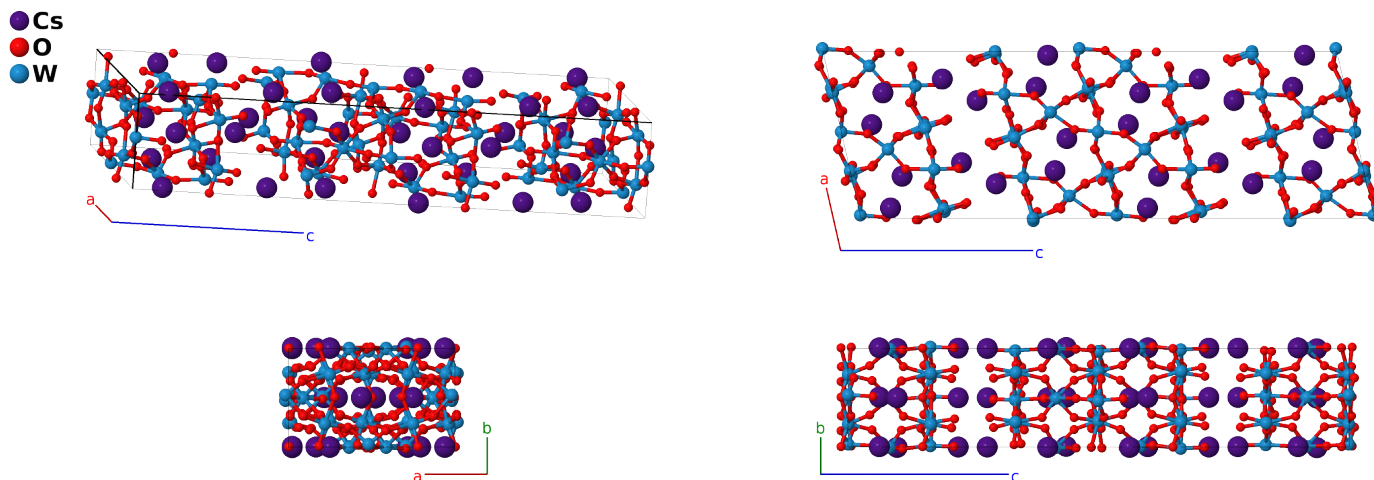
Cs₆W₁₁O₃₆ Structure: A6B36C11_mC212_9_6a_36a_11a-001

This structure originally had the label A6B36C11_mC212_9_6a_36a_11a. Calls to that address will be redirected here.

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<https://afLOW.org/p/A3V8>

https://afLOW.org/p/A6B36C11_mC212_9_6a_36a_11a-001

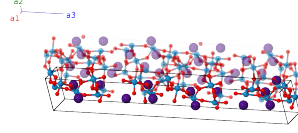


Prototype	Cs ₆ O ₃₆ W ₁₁
AFLOW prototype label	A6B36C11_mC212_9_6a_36a_11a-001
ICSD	80133
Pearson symbol	mC212
Space group number	9
Space group symbol	<i>Cc</i>
AFLOW prototype command	<pre>afLOW --proto=A6B36C11_mC212_9_6a_36a_11a-001 --params=a,b/a,c/a,β,x₁,y₁,z₁,x₂,y₂,z₂,x₃,y₃,z₃,x₄,y₄,z₄,x₅,y₅,z₅,x₆,y₆,z₆,x₇, y₇,z₇,x₈,y₈,z₈,x₉,y₉,z₉,x₁₀,y₁₀,z₁₀,x₁₁,y₁₁,z₁₁,x₁₂,y₁₂,z₁₂,x₁₃,y₁₃,z₁₃,x₁₄,y₁₄,z₁₄,x₁₅, y₁₅,z₁₅,x₁₆,y₁₆,z₁₆,x₁₇,y₁₇,z₁₇,x₁₈,y₁₈,z₁₈,x₁₉,y₁₉,z₁₉,x₂₀,y₂₀,z₂₀,x₂₁,y₂₁,z₂₁,x₂₂,y₂₂, z₂₂,x₂₃,y₂₃,z₂₃,x₂₄,y₂₄,z₂₄,x₂₅,y₂₅,z₂₅,x₂₆,y₂₆,z₂₆,x₂₇,y₂₇,z₂₇,x₂₈,y₂₈,z₂₈,x₂₉,y₂₉,z₂₉, x₃₀,y₃₀,z₃₀,x₃₁,y₃₁,z₃₁,x₃₂,y₃₂,z₃₂,x₃₃,y₃₃,z₃₃,x₃₄,y₃₄,z₃₄,x₃₅,y₃₅,z₃₅,x₃₆,y₃₆,z₃₆,x₃₇, y₃₇,z₃₇,x₃₈,y₃₈,z₃₈,x₃₉,y₃₉,z₃₉,x₄₀,y₄₀,z₄₀,x₄₁,y₄₁,z₄₁,x₄₂,y₄₂,z₄₂,x₄₃,y₄₃,z₄₃,x₄₄,y₄₄, z₄₄,x₄₅,y₄₅,z₄₅,x₄₆,y₄₆,z₄₆,x₄₇,y₄₇,z₄₇,x₄₈,y₄₈,z₄₈,x₄₉,y₄₉,z₄₉,x₅₀,y₅₀,z₅₀,x₅₁,y₅₁,z₅₁, x₅₂,y₅₂,z₅₂,x₅₃,y₅₃,z₅₃</pre>

- (Okada, 1978) placed this in the monoclinic space group *Cc*#9. (Marsh, 1995) determined that their data fit in space group *R* $\bar{3}c$ #167, and we present their analysis here.

Base-centered Monoclinic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}b \hat{\mathbf{y}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$(x_1 - y_1) \mathbf{a}_1 + (x_1 + y_1) \mathbf{a}_2 + z_1 \mathbf{a}_3$	=	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4a)	Cs I
\mathbf{B}_2	$(x_1 + y_1) \mathbf{a}_1 + (x_1 - y_1) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	Cs I
\mathbf{B}_3	$(x_2 - y_2) \mathbf{a}_1 + (x_2 + y_2) \mathbf{a}_2 + z_2 \mathbf{a}_3$	=	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4a)	Cs II
\mathbf{B}_4	$(x_2 + y_2) \mathbf{a}_1 + (x_2 - y_2) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	Cs II
\mathbf{B}_5	$(x_3 - y_3) \mathbf{a}_1 + (x_3 + y_3) \mathbf{a}_2 + z_3 \mathbf{a}_3$	=	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4a)	Cs III
\mathbf{B}_6	$(x_3 + y_3) \mathbf{a}_1 + (x_3 - y_3) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	Cs III
\mathbf{B}_7	$(x_4 - y_4) \mathbf{a}_1 + (x_4 + y_4) \mathbf{a}_2 + z_4 \mathbf{a}_3$	=	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4a)	Cs IV
\mathbf{B}_8	$(x_4 + y_4) \mathbf{a}_1 + (x_4 - y_4) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	Cs IV
\mathbf{B}_9	$(x_5 - y_5) \mathbf{a}_1 + (x_5 + y_5) \mathbf{a}_2 + z_5 \mathbf{a}_3$	=	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4a)	Cs V
\mathbf{B}_{10}	$(x_5 + y_5) \mathbf{a}_1 + (x_5 - y_5) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	Cs V
\mathbf{B}_{11}	$(x_6 - y_6) \mathbf{a}_1 + (x_6 + y_6) \mathbf{a}_2 + z_6 \mathbf{a}_3$	=	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(4a)	Cs VI
\mathbf{B}_{12}	$(x_6 + y_6) \mathbf{a}_1 + (x_6 - y_6) \mathbf{a}_2 + (z_6 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	Cs VI
\mathbf{B}_{13}	$(x_7 - y_7) \mathbf{a}_1 + (x_7 + y_7) \mathbf{a}_2 + z_7 \mathbf{a}_3$	=	$(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}}$	(4a)	O I
\mathbf{B}_{14}	$(x_7 + y_7) \mathbf{a}_1 + (x_7 - y_7) \mathbf{a}_2 + (z_7 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O I
\mathbf{B}_{15}	$(x_8 - y_8) \mathbf{a}_1 + (x_8 + y_8) \mathbf{a}_2 + z_8 \mathbf{a}_3$	=	$(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}}$	(4a)	O II
\mathbf{B}_{16}	$(x_8 + y_8) \mathbf{a}_1 + (x_8 - y_8) \mathbf{a}_2 + (z_8 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_8 + c(z_8 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O II
\mathbf{B}_{17}	$(x_9 - y_9) \mathbf{a}_1 + (x_9 + y_9) \mathbf{a}_2 + z_9 \mathbf{a}_3$	=	$(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}}$	(4a)	O III
\mathbf{B}_{18}	$(x_9 + y_9) \mathbf{a}_1 + (x_9 - y_9) \mathbf{a}_2 + (z_9 + \frac{1}{2}) \mathbf{a}_3$	=	$(ax_9 + c(z_9 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} + c(z_9 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O III

$\mathbf{B}_{65} =$	$(x_{33} - y_{33}) \mathbf{a}_1 +$ $(x_{33} + y_{33}) \mathbf{a}_2 + z_{33} \mathbf{a}_3$	$=$	$(ax_{33} + cz_{33} \cos \beta) \hat{\mathbf{x}} + by_{33} \hat{\mathbf{y}} + cz_{33} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXVII
$\mathbf{B}_{66} =$	$(x_{33} + y_{33}) \mathbf{a}_1 +$ $(x_{33} - y_{33}) \mathbf{a}_2 + (z_{33} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{33} + c(z_{33} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{33} \hat{\mathbf{y}} +$ $c(z_{33} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXVII
$\mathbf{B}_{67} =$	$(x_{34} - y_{34}) \mathbf{a}_1 +$ $(x_{34} + y_{34}) \mathbf{a}_2 + z_{34} \mathbf{a}_3$	$=$	$(ax_{34} + cz_{34} \cos \beta) \hat{\mathbf{x}} + by_{34} \hat{\mathbf{y}} + cz_{34} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXVIII
$\mathbf{B}_{68} =$	$(x_{34} + y_{34}) \mathbf{a}_1 +$ $(x_{34} - y_{34}) \mathbf{a}_2 + (z_{34} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{34} + c(z_{34} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{34} \hat{\mathbf{y}} +$ $c(z_{34} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXVIII
$\mathbf{B}_{69} =$	$(x_{35} - y_{35}) \mathbf{a}_1 +$ $(x_{35} + y_{35}) \mathbf{a}_2 + z_{35} \mathbf{a}_3$	$=$	$(ax_{35} + cz_{35} \cos \beta) \hat{\mathbf{x}} + by_{35} \hat{\mathbf{y}} + cz_{35} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXIX
$\mathbf{B}_{70} =$	$(x_{35} + y_{35}) \mathbf{a}_1 +$ $(x_{35} - y_{35}) \mathbf{a}_2 + (z_{35} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{35} + c(z_{35} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{35} \hat{\mathbf{y}} +$ $c(z_{35} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXIX
$\mathbf{B}_{71} =$	$(x_{36} - y_{36}) \mathbf{a}_1 +$ $(x_{36} + y_{36}) \mathbf{a}_2 + z_{36} \mathbf{a}_3$	$=$	$(ax_{36} + cz_{36} \cos \beta) \hat{\mathbf{x}} + by_{36} \hat{\mathbf{y}} + cz_{36} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXX
$\mathbf{B}_{72} =$	$(x_{36} + y_{36}) \mathbf{a}_1 +$ $(x_{36} - y_{36}) \mathbf{a}_2 + (z_{36} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{36} + c(z_{36} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{36} \hat{\mathbf{y}} +$ $c(z_{36} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXX
$\mathbf{B}_{73} =$	$(x_{37} - y_{37}) \mathbf{a}_1 +$ $(x_{37} + y_{37}) \mathbf{a}_2 + z_{37} \mathbf{a}_3$	$=$	$(ax_{37} + cz_{37} \cos \beta) \hat{\mathbf{x}} + by_{37} \hat{\mathbf{y}} + cz_{37} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXI
$\mathbf{B}_{74} =$	$(x_{37} + y_{37}) \mathbf{a}_1 +$ $(x_{37} - y_{37}) \mathbf{a}_2 + (z_{37} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{37} + c(z_{37} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{37} \hat{\mathbf{y}} +$ $c(z_{37} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXI
$\mathbf{B}_{75} =$	$(x_{38} - y_{38}) \mathbf{a}_1 +$ $(x_{38} + y_{38}) \mathbf{a}_2 + z_{38} \mathbf{a}_3$	$=$	$(ax_{38} + cz_{38} \cos \beta) \hat{\mathbf{x}} + by_{38} \hat{\mathbf{y}} + cz_{38} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXII
$\mathbf{B}_{76} =$	$(x_{38} + y_{38}) \mathbf{a}_1 +$ $(x_{38} - y_{38}) \mathbf{a}_2 + (z_{38} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{38} + c(z_{38} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{38} \hat{\mathbf{y}} +$ $c(z_{38} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXII
$\mathbf{B}_{77} =$	$(x_{39} - y_{39}) \mathbf{a}_1 +$ $(x_{39} + y_{39}) \mathbf{a}_2 + z_{39} \mathbf{a}_3$	$=$	$(ax_{39} + cz_{39} \cos \beta) \hat{\mathbf{x}} + by_{39} \hat{\mathbf{y}} + cz_{39} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXIII
$\mathbf{B}_{78} =$	$(x_{39} + y_{39}) \mathbf{a}_1 +$ $(x_{39} - y_{39}) \mathbf{a}_2 + (z_{39} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{39} + c(z_{39} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{39} \hat{\mathbf{y}} +$ $c(z_{39} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXIII
$\mathbf{B}_{79} =$	$(x_{40} - y_{40}) \mathbf{a}_1 +$ $(x_{40} + y_{40}) \mathbf{a}_2 + z_{40} \mathbf{a}_3$	$=$	$(ax_{40} + cz_{40} \cos \beta) \hat{\mathbf{x}} + by_{40} \hat{\mathbf{y}} + cz_{40} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXIV
$\mathbf{B}_{80} =$	$(x_{40} + y_{40}) \mathbf{a}_1 +$ $(x_{40} - y_{40}) \mathbf{a}_2 + (z_{40} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{40} + c(z_{40} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{40} \hat{\mathbf{y}} +$ $c(z_{40} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXIV
$\mathbf{B}_{81} =$	$(x_{41} - y_{41}) \mathbf{a}_1 +$ $(x_{41} + y_{41}) \mathbf{a}_2 + z_{41} \mathbf{a}_3$	$=$	$(ax_{41} + cz_{41} \cos \beta) \hat{\mathbf{x}} + by_{41} \hat{\mathbf{y}} + cz_{41} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXV
$\mathbf{B}_{82} =$	$(x_{41} + y_{41}) \mathbf{a}_1 +$ $(x_{41} - y_{41}) \mathbf{a}_2 + (z_{41} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{41} + c(z_{41} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{41} \hat{\mathbf{y}} +$ $c(z_{41} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXV
$\mathbf{B}_{83} =$	$(x_{42} - y_{42}) \mathbf{a}_1 +$ $(x_{42} + y_{42}) \mathbf{a}_2 + z_{42} \mathbf{a}_3$	$=$	$(ax_{42} + cz_{42} \cos \beta) \hat{\mathbf{x}} + by_{42} \hat{\mathbf{y}} + cz_{42} \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXVI
$\mathbf{B}_{84} =$	$(x_{42} + y_{42}) \mathbf{a}_1 +$ $(x_{42} - y_{42}) \mathbf{a}_2 + (z_{42} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{42} + c(z_{42} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{42} \hat{\mathbf{y}} +$ $c(z_{42} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	O XXXVI
$\mathbf{B}_{85} =$	$(x_{43} - y_{43}) \mathbf{a}_1 +$ $(x_{43} + y_{43}) \mathbf{a}_2 + z_{43} \mathbf{a}_3$	$=$	$(ax_{43} + cz_{43} \cos \beta) \hat{\mathbf{x}} + by_{43} \hat{\mathbf{y}} + cz_{43} \sin \beta \hat{\mathbf{z}}$	(4a)	W I
$\mathbf{B}_{86} =$	$(x_{43} + y_{43}) \mathbf{a}_1 +$ $(x_{43} - y_{43}) \mathbf{a}_2 + (z_{43} + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_{43} + c(z_{43} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{43} \hat{\mathbf{y}} +$ $c(z_{43} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4a)	W I
$\mathbf{B}_{87} =$	$(x_{44} - y_{44}) \mathbf{a}_1 +$ $(x_{44} + y_{44}) \mathbf{a}_2 + z_{44} \mathbf{a}_3$	$=$	$(ax_{44} + cz_{44} \cos \beta) \hat{\mathbf{x}} + by_{44} \hat{\mathbf{y}} + cz_{44} \sin \beta \hat{\mathbf{z}}$	(4a)	W II

$$\begin{aligned}
\mathbf{B}_{88} &= \begin{pmatrix} (x_{44} + y_{44}) \mathbf{a}_1 + \\ (x_{44} - y_{44}) \mathbf{a}_2 + (z_{44} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{44} + c(z_{44} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{44} \hat{\mathbf{y}} + \\ c(z_{44} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W II} \\
\mathbf{B}_{89} &= \begin{pmatrix} (x_{45} - y_{45}) \mathbf{a}_1 + \\ (x_{45} + y_{45}) \mathbf{a}_2 + z_{45} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{45} + cz_{45} \cos \beta) \hat{\mathbf{x}} + by_{45} \hat{\mathbf{y}} + cz_{45} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W III} \\
\mathbf{B}_{90} &= \begin{pmatrix} (x_{45} + y_{45}) \mathbf{a}_1 + \\ (x_{45} - y_{45}) \mathbf{a}_2 + (z_{45} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{45} + c(z_{45} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{45} \hat{\mathbf{y}} + \\ c(z_{45} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W III} \\
\mathbf{B}_{91} &= \begin{pmatrix} (x_{46} - y_{46}) \mathbf{a}_1 + \\ (x_{46} + y_{46}) \mathbf{a}_2 + z_{46} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{46} + cz_{46} \cos \beta) \hat{\mathbf{x}} + by_{46} \hat{\mathbf{y}} + cz_{46} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W IV} \\
\mathbf{B}_{92} &= \begin{pmatrix} (x_{46} + y_{46}) \mathbf{a}_1 + \\ (x_{46} - y_{46}) \mathbf{a}_2 + (z_{46} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{46} + c(z_{46} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{46} \hat{\mathbf{y}} + \\ c(z_{46} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W IV} \\
\mathbf{B}_{93} &= \begin{pmatrix} (x_{47} - y_{47}) \mathbf{a}_1 + \\ (x_{47} + y_{47}) \mathbf{a}_2 + z_{47} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{47} + cz_{47} \cos \beta) \hat{\mathbf{x}} + by_{47} \hat{\mathbf{y}} + cz_{47} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W V} \\
\mathbf{B}_{94} &= \begin{pmatrix} (x_{47} + y_{47}) \mathbf{a}_1 + \\ (x_{47} - y_{47}) \mathbf{a}_2 + (z_{47} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{47} + c(z_{47} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{47} \hat{\mathbf{y}} + \\ c(z_{47} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W V} \\
\mathbf{B}_{95} &= \begin{pmatrix} (x_{48} - y_{48}) \mathbf{a}_1 + \\ (x_{48} + y_{48}) \mathbf{a}_2 + z_{48} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{48} + cz_{48} \cos \beta) \hat{\mathbf{x}} + by_{48} \hat{\mathbf{y}} + cz_{48} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W VI} \\
\mathbf{B}_{96} &= \begin{pmatrix} (x_{48} + y_{48}) \mathbf{a}_1 + \\ (x_{48} - y_{48}) \mathbf{a}_2 + (z_{48} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{48} + c(z_{48} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{48} \hat{\mathbf{y}} + \\ c(z_{48} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W VI} \\
\mathbf{B}_{97} &= \begin{pmatrix} (x_{49} - y_{49}) \mathbf{a}_1 + \\ (x_{49} + y_{49}) \mathbf{a}_2 + z_{49} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{49} + cz_{49} \cos \beta) \hat{\mathbf{x}} + by_{49} \hat{\mathbf{y}} + cz_{49} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W VII} \\
\mathbf{B}_{98} &= \begin{pmatrix} (x_{49} + y_{49}) \mathbf{a}_1 + \\ (x_{49} - y_{49}) \mathbf{a}_2 + (z_{49} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{49} + c(z_{49} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{49} \hat{\mathbf{y}} + \\ c(z_{49} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W VII} \\
\mathbf{B}_{99} &= \begin{pmatrix} (x_{50} - y_{50}) \mathbf{a}_1 + \\ (x_{50} + y_{50}) \mathbf{a}_2 + z_{50} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{50} + cz_{50} \cos \beta) \hat{\mathbf{x}} + by_{50} \hat{\mathbf{y}} + cz_{50} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W VIII} \\
\mathbf{B}_{100} &= \begin{pmatrix} (x_{50} + y_{50}) \mathbf{a}_1 + \\ (x_{50} - y_{50}) \mathbf{a}_2 + (z_{50} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{50} + c(z_{50} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{50} \hat{\mathbf{y}} + \\ c(z_{50} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W VIII} \\
\mathbf{B}_{101} &= \begin{pmatrix} (x_{51} - y_{51}) \mathbf{a}_1 + \\ (x_{51} + y_{51}) \mathbf{a}_2 + z_{51} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{51} + cz_{51} \cos \beta) \hat{\mathbf{x}} + by_{51} \hat{\mathbf{y}} + cz_{51} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W IX} \\
\mathbf{B}_{102} &= \begin{pmatrix} (x_{51} + y_{51}) \mathbf{a}_1 + \\ (x_{51} - y_{51}) \mathbf{a}_2 + (z_{51} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{51} + c(z_{51} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{51} \hat{\mathbf{y}} + \\ c(z_{51} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W IX} \\
\mathbf{B}_{103} &= \begin{pmatrix} (x_{52} - y_{52}) \mathbf{a}_1 + \\ (x_{52} + y_{52}) \mathbf{a}_2 + z_{52} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{52} + cz_{52} \cos \beta) \hat{\mathbf{x}} + by_{52} \hat{\mathbf{y}} + cz_{52} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W X} \\
\mathbf{B}_{104} &= \begin{pmatrix} (x_{52} + y_{52}) \mathbf{a}_1 + \\ (x_{52} - y_{52}) \mathbf{a}_2 + (z_{52} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{52} + c(z_{52} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{52} \hat{\mathbf{y}} + \\ c(z_{52} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W X} \\
\mathbf{B}_{105} &= \begin{pmatrix} (x_{53} - y_{53}) \mathbf{a}_1 + \\ (x_{53} + y_{53}) \mathbf{a}_2 + z_{53} \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{53} + cz_{53} \cos \beta) \hat{\mathbf{x}} + by_{53} \hat{\mathbf{y}} + cz_{53} \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W XI} \\
\mathbf{B}_{106} &= \begin{pmatrix} (x_{53} + y_{53}) \mathbf{a}_1 + \\ (x_{53} - y_{53}) \mathbf{a}_2 + (z_{53} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = \begin{pmatrix} (ax_{53} + c(z_{53} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{53} \hat{\mathbf{y}} + \\ c(z_{53} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \end{pmatrix} & (4a) & \text{W XI}
\end{aligned}$$

References

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