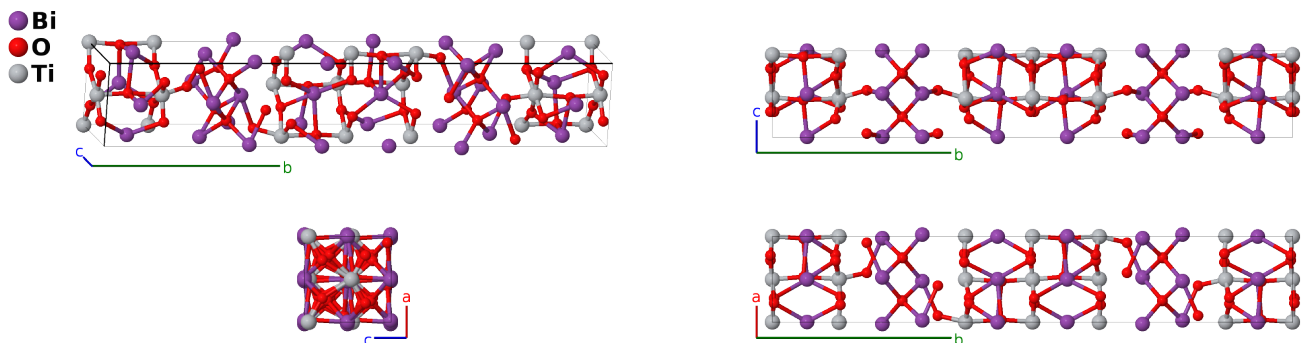


Orthorhombic $\text{Bi}_4\text{Ti}_3\text{O}_{12}$ $m = 3$ Aurivillius Structure (*Obsolete*): A4B12C3_oC76_41_2b_6b_ab-001

Cite this page as: H. Eckert, S. Divilov, A. Zettel, M. J. Mehl, D. Hicks, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*. In preparation.

<https://aflow.org/p/5TXE>

https://aflow.org/p/A4B12C3_oC76_41_2b_6b_ab-001

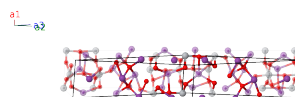


Prototype	$\text{Bi}_4\text{O}_{12}\text{Ti}_3$
AFLOW prototype label	A4B12C3_oC76_41_2b_6b_ab-001
ICSD	16488
Pearson symbol	oC76
Space group number	41
Space group symbol	<i>Aca</i> 2
AFLOW prototype command	aflow --proto=A4B12C3_oC76_41_2b_6b_ab-001 --params=a, b/a, c/a, z ₁ , x ₂ , y ₂ , z ₂ , x ₃ , y ₃ , z ₃ , x ₄ , y ₄ , z ₄ , x ₅ , y ₅ , z ₅ , x ₆ , y ₆ , z ₆ , x ₇ , y ₇ , z ₇ , x ₈ , y ₈ , z ₈ , x ₉ , y ₉ , z ₉ , x ₁₀ , y ₁₀ , z ₁₀

- Aurivillius phases are layered tetragonal materials with composition $(\text{Me}'_2\text{O}_2)^{2+}(\text{Me}_{m-1}\text{R}_m\text{O}_{3m+1})^{2-}$ ($\text{Me}_{m-1}\text{Me}'_2\text{R}_m\text{O}_{3(m+1)}$), where Me and Me' are metals and R is a transition metal with a charge of +4 or +5. (Subbaro, 1962)
- (Dorrian, 1971) give this structure in what they call the *B2cb* (or *B2ab*) setting of space group #41. We used FINDSYM to transform this to the standard *Aca*2 setting.
- (Dorrian, 1971) notes that the physical properties of this structure indicate monoclinic symmetry, but that the structure is consistent with orthorhombic symmetry. Various authors have shown that the structure is actually in monoclinic, with space group *Pc* #7, as described by (Guo, 2019).

Base-centered Orthorhombic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= \frac{1}{2}b \hat{\mathbf{y}} - \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$= -z_1 \mathbf{a}_2 + z_1 \mathbf{a}_3 =$		$cz_1 \hat{\mathbf{z}}$	(4a)	Ti I
\mathbf{B}_2	$= \frac{1}{2} \mathbf{a}_1 - (z_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3 =$		$\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(4a)	Ti I
\mathbf{B}_3	$= x_2 \mathbf{a}_1 + (y_2 - z_2) \mathbf{a}_2 + (y_2 + z_2) \mathbf{a}_3 =$		$ax_2 \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8b)	Bi I
\mathbf{B}_4	$= -x_2 \mathbf{a}_1 - (y_2 + z_2) \mathbf{a}_2 -$ $(y_2 - z_2) \mathbf{a}_3 =$		$-ax_2 \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8b)	Bi I
\mathbf{B}_5	$= (x_2 + \frac{1}{2}) \mathbf{a}_1 - (y_2 + z_2 - \frac{1}{2}) \mathbf{a}_2 +$ $(-y_2 + z_2 + \frac{1}{2}) \mathbf{a}_3 =$		$a(x_2 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8b)	Bi I
\mathbf{B}_6	$= -(x_2 - \frac{1}{2}) \mathbf{a}_1 +$ $(y_2 - z_2 + \frac{1}{2}) \mathbf{a}_2 +$ $(y_2 + z_2 + \frac{1}{2}) \mathbf{a}_3 =$		$-a(x_2 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8b)	Bi I
\mathbf{B}_7	$= x_3 \mathbf{a}_1 + (y_3 - z_3) \mathbf{a}_2 + (y_3 + z_3) \mathbf{a}_3 =$		$ax_3 \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8b)	Bi II
\mathbf{B}_8	$= -x_3 \mathbf{a}_1 - (y_3 + z_3) \mathbf{a}_2 -$ $(y_3 - z_3) \mathbf{a}_3 =$		$-ax_3 \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8b)	Bi II
\mathbf{B}_9	$= (x_3 + \frac{1}{2}) \mathbf{a}_1 - (y_3 + z_3 - \frac{1}{2}) \mathbf{a}_2 +$ $(-y_3 + z_3 + \frac{1}{2}) \mathbf{a}_3 =$		$a(x_3 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8b)	Bi II
\mathbf{B}_{10}	$= -(x_3 - \frac{1}{2}) \mathbf{a}_1 +$ $(y_3 - z_3 + \frac{1}{2}) \mathbf{a}_2 +$ $(y_3 + z_3 + \frac{1}{2}) \mathbf{a}_3 =$		$-a(x_3 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8b)	Bi II
\mathbf{B}_{11}	$= x_4 \mathbf{a}_1 + (y_4 - z_4) \mathbf{a}_2 + (y_4 + z_4) \mathbf{a}_3 =$		$ax_4 \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8b)	O I
\mathbf{B}_{12}	$= -x_4 \mathbf{a}_1 - (y_4 + z_4) \mathbf{a}_2 -$ $(y_4 - z_4) \mathbf{a}_3 =$		$-ax_4 \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8b)	O I
\mathbf{B}_{13}	$= (x_4 + \frac{1}{2}) \mathbf{a}_1 - (y_4 + z_4 - \frac{1}{2}) \mathbf{a}_2 +$ $(-y_4 + z_4 + \frac{1}{2}) \mathbf{a}_3 =$		$a(x_4 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8b)	O I
\mathbf{B}_{14}	$= -(x_4 - \frac{1}{2}) \mathbf{a}_1 +$ $(y_4 - z_4 + \frac{1}{2}) \mathbf{a}_2 +$ $(y_4 + z_4 + \frac{1}{2}) \mathbf{a}_3 =$		$-a(x_4 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8b)	O I
\mathbf{B}_{15}	$= x_5 \mathbf{a}_1 + (y_5 - z_5) \mathbf{a}_2 + (y_5 + z_5) \mathbf{a}_3 =$		$ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8b)	O II
\mathbf{B}_{16}	$= -x_5 \mathbf{a}_1 - (y_5 + z_5) \mathbf{a}_2 -$ $(y_5 - z_5) \mathbf{a}_3 =$		$-ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8b)	O II
\mathbf{B}_{17}	$= (x_5 + \frac{1}{2}) \mathbf{a}_1 - (y_5 + z_5 - \frac{1}{2}) \mathbf{a}_2 +$ $(-y_5 + z_5 + \frac{1}{2}) \mathbf{a}_3 =$		$a(x_5 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8b)	O II
\mathbf{B}_{18}	$= -(x_5 - \frac{1}{2}) \mathbf{a}_1 +$ $(y_5 - z_5 + \frac{1}{2}) \mathbf{a}_2 +$ $(y_5 + z_5 + \frac{1}{2}) \mathbf{a}_3 =$		$-a(x_5 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8b)	O II
\mathbf{B}_{19}	$= x_6 \mathbf{a}_1 + (y_6 - z_6) \mathbf{a}_2 + (y_6 + z_6) \mathbf{a}_3 =$		$ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8b)	O III
\mathbf{B}_{20}	$= -x_6 \mathbf{a}_1 - (y_6 + z_6) \mathbf{a}_2 -$ $(y_6 - z_6) \mathbf{a}_3 =$		$-ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8b)	O III
\mathbf{B}_{21}	$= (x_6 + \frac{1}{2}) \mathbf{a}_1 - (y_6 + z_6 - \frac{1}{2}) \mathbf{a}_2 +$ $(-y_6 + z_6 + \frac{1}{2}) \mathbf{a}_3 =$		$a(x_6 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8b)	O III
\mathbf{B}_{22}	$= -(x_6 - \frac{1}{2}) \mathbf{a}_1 +$ $(y_6 - z_6 + \frac{1}{2}) \mathbf{a}_2 +$ $(y_6 + z_6 + \frac{1}{2}) \mathbf{a}_3 =$		$-a(x_6 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8b)	O III
\mathbf{B}_{23}	$= x_7 \mathbf{a}_1 + (y_7 - z_7) \mathbf{a}_2 + (y_7 + z_7) \mathbf{a}_3 =$		$ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}}$	(8b)	O IV
\mathbf{B}_{24}	$= -x_7 \mathbf{a}_1 - (y_7 + z_7) \mathbf{a}_2 -$ $(y_7 - z_7) \mathbf{a}_3 =$		$-ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}}$	(8b)	O IV

$$\begin{aligned}
\mathbf{B}_{25} &= \begin{pmatrix} (x_7 + \frac{1}{2}) \mathbf{a}_1 - (y_7 + z_7 - \frac{1}{2}) \mathbf{a}_2 + \\ (-y_7 + z_7 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(x_7 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (8b) & \text{O IV} \\
\mathbf{B}_{26} &= \begin{pmatrix} -(x_7 - \frac{1}{2}) \mathbf{a}_1 + \\ (y_7 - z_7 + \frac{1}{2}) \mathbf{a}_2 + \\ (y_7 + z_7 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(x_7 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (8b) & \text{O IV} \\
\mathbf{B}_{27} &= x_8 \mathbf{a}_1 + (y_8 - z_8) \mathbf{a}_2 + (y_8 + z_8) \mathbf{a}_3 = ax_8 \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (8b) & \text{O V} \\
\mathbf{B}_{28} &= -x_8 \mathbf{a}_1 - (y_8 + z_8) \mathbf{a}_2 - (y_8 - z_8) \mathbf{a}_3 = -ax_8 \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (8b) & \text{O V} \\
\mathbf{B}_{29} &= \begin{pmatrix} (x_8 + \frac{1}{2}) \mathbf{a}_1 - (y_8 + z_8 - \frac{1}{2}) \mathbf{a}_2 + \\ (-y_8 + z_8 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(x_8 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_8 - \frac{1}{2}) \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (8b) & \text{O V} \\
\mathbf{B}_{30} &= \begin{pmatrix} -(x_8 - \frac{1}{2}) \mathbf{a}_1 + \\ (y_8 - z_8 + \frac{1}{2}) \mathbf{a}_2 + \\ (y_8 + z_8 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(x_8 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_8 + \frac{1}{2}) \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (8b) & \text{O V} \\
\mathbf{B}_{31} &= x_9 \mathbf{a}_1 + (y_9 - z_9) \mathbf{a}_2 + (y_9 + z_9) \mathbf{a}_3 = ax_9 \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \hat{\mathbf{z}} & (8b) & \text{O VI} \\
\mathbf{B}_{32} &= -x_9 \mathbf{a}_1 - (y_9 + z_9) \mathbf{a}_2 - (y_9 - z_9) \mathbf{a}_3 = -ax_9 \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} + cz_9 \hat{\mathbf{z}} & (8b) & \text{O VI} \\
\mathbf{B}_{33} &= \begin{pmatrix} (x_9 + \frac{1}{2}) \mathbf{a}_1 - (y_9 + z_9 - \frac{1}{2}) \mathbf{a}_2 + \\ (-y_9 + z_9 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(x_9 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_9 - \frac{1}{2}) \hat{\mathbf{y}} + cz_9 \hat{\mathbf{z}} & (8b) & \text{O VI} \\
\mathbf{B}_{34} &= \begin{pmatrix} -(x_9 - \frac{1}{2}) \mathbf{a}_1 + \\ (y_9 - z_9 + \frac{1}{2}) \mathbf{a}_2 + \\ (y_9 + z_9 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(x_9 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_9 + \frac{1}{2}) \hat{\mathbf{y}} + cz_9 \hat{\mathbf{z}} & (8b) & \text{O VI} \\
\mathbf{B}_{35} &= x_{10} \mathbf{a}_1 + (y_{10} - z_{10}) \mathbf{a}_2 + (y_{10} + z_{10}) \mathbf{a}_3 = ax_{10} \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \hat{\mathbf{z}} & (8b) & \text{Ti II} \\
\mathbf{B}_{36} &= -x_{10} \mathbf{a}_1 - (y_{10} + z_{10}) \mathbf{a}_2 - (y_{10} - z_{10}) \mathbf{a}_3 = -ax_{10} \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} + cz_{10} \hat{\mathbf{z}} & (8b) & \text{Ti II} \\
\mathbf{B}_{37} &= \begin{pmatrix} (x_{10} + \frac{1}{2}) \mathbf{a}_1 - \\ (y_{10} + z_{10} - \frac{1}{2}) \mathbf{a}_2 + \\ (-y_{10} + z_{10} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(x_{10} + \frac{1}{2}) \hat{\mathbf{x}} - b(y_{10} - \frac{1}{2}) \hat{\mathbf{y}} + cz_{10} \hat{\mathbf{z}} & (8b) & \text{Ti II} \\
\mathbf{B}_{38} &= \begin{pmatrix} -(x_{10} - \frac{1}{2}) \mathbf{a}_1 + \\ (y_{10} - z_{10} + \frac{1}{2}) \mathbf{a}_2 + \\ (y_{10} + z_{10} + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(x_{10} - \frac{1}{2}) \hat{\mathbf{x}} + b(y_{10} + \frac{1}{2}) \hat{\mathbf{y}} + cz_{10} \hat{\mathbf{z}} & (8b) & \text{Ti II}
\end{aligned}$$

References

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