α-WO_3 Structure: A3B_tP16_130_cf_c-001

This structure originally had the label `A3B_tP16_130_cf_c`. Calls to that address will be redirected here.

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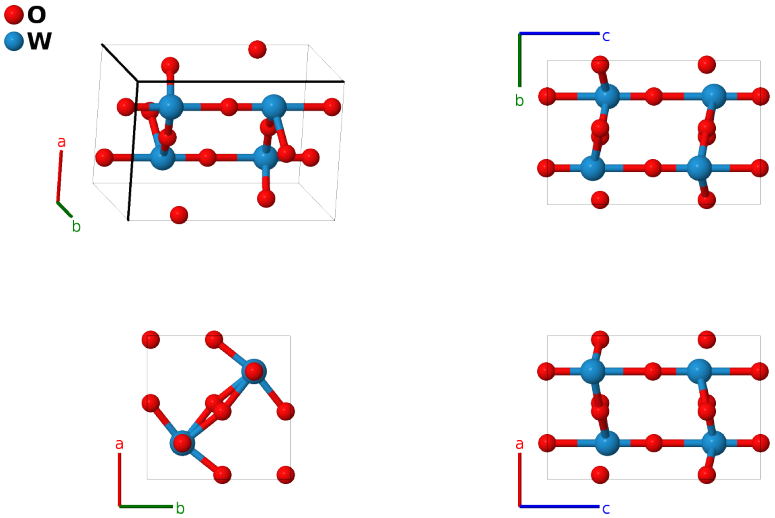
https://aflow.org/p/HPJW

https://aflow.org/p/A3B_tP16_130_cf_c-001



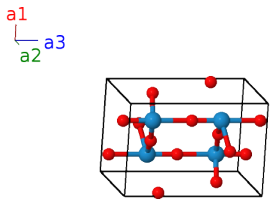
Prototype	O_3W
AFLOW prototype label	A3B_tP16_130_cf_c-001
ICSD	50732
Pearson symbol	tP16
Space group number	130
Space group symbol	$P4/ncc$
AFLOW prototype command	`aflow --proto=A3B_tP16_130_cf_c-001 --params=`$a, c/a, z_1, z_2, x_3$

- All stable phases of WO_3 are distortions of the cubic α-ReO_3 ($D0_9$) phase. Based on (Woodward, 1997 and Vogt, 1999), the known stable phases and their approximate temperature ranges are:
  - α-WO_3 (1010-1170 K) (Vogt, 1999) (this structure)
  - β-WO_3 (600-1170 K) (Vogt, 1999)
  - γ-WO_3 (290-600 K) (Vogt, 1999)
  - δ-WO_3 (230-290 K) (Diehl, 1978)
  - ϵ-WO_3 (below 23 K) (Woodward, 1997)
- Woodward notes that "The transition temperatures display large hysteresis effects and universal agreement is not found in the literature."

- In addition, several other structures have been proposed and/or found:
  - The original $D0_{10}$ structure (Bräkken, 1931; Hermann, 1937), superseded by δ-WO_3
  - The original β-WO_3 (Salje, 1977),
  - Hexagonal WO_3, presumably metastable, found by (Gerand, 1979) while dehydrating $WO_3{\cdot}H_2O$.
- We use the α-WO_3 data taken by (Vogt, 1999) at 800°C (1073K).
- (Kehl, 1952) originally put this structure in space group $P4/nmm$ #129, with a c-lattice constant set to half of the current value. This structure was corrected by (Vogh, 1999).

Simple Tetragonal primitive vectors

$$\mathbf{a_1} = a\,\hat{\mathbf{x}}$$
$$\mathbf{a_2} = a\,\hat{\mathbf{y}}$$
$$\mathbf{a_3} = c\,\hat{\mathbf{z}}$$



Basis vectors

		Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B_1}$	=	$\frac{1}{4}\,\mathbf{a}_1 + \frac{1}{4}\,\mathbf{a}_2 + z_1\,\mathbf{a}_3$	=	$\frac{1}{4}a\,\hat{\mathbf{x}} + \frac{1}{4}a\,\hat{\mathbf{y}} + cz_1\,\hat{\mathbf{z}}$	(4c)	O I
$\mathbf{B_2}$	=	$\frac{3}{4}\,\mathbf{a}_1 + \frac{3}{4}\,\mathbf{a}_2 - \left(z_1 - \frac{1}{2}\right)\,\mathbf{a}_3$	=	$\frac{3}{4}a\,\hat{\mathbf{x}} + \frac{3}{4}a\,\hat{\mathbf{y}} - c\left(z_1 - \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4c)	O I
$\mathbf{B_3}$	=	$\frac{3}{4}\,\mathbf{a}_1 + \frac{3}{4}\,\mathbf{a}_2 - z_1\,\mathbf{a}_3$	=	$\frac{3}{4}a\,\hat{\mathbf{x}} + \frac{3}{4}a\,\hat{\mathbf{y}} - cz_1\,\hat{\mathbf{z}}$	(4c)	O I
$\mathbf{B_4}$	=	$\frac{1}{4}\,\mathbf{a}_1 + \frac{1}{4}\,\mathbf{a}_2 + \left(z_1 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$\frac{1}{4}a\,\hat{\mathbf{x}} + \frac{1}{4}a\,\hat{\mathbf{y}} + c\left(z_1 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4c)	O I
$\mathbf{B_5}$	=	$\frac{1}{4}\,\mathbf{a}_1 + \frac{1}{4}\,\mathbf{a}_2 + z_2\,\mathbf{a}_3$	=	$\frac{1}{4}a\,\hat{\mathbf{x}} + \frac{1}{4}a\,\hat{\mathbf{y}} + cz_2\,\hat{\mathbf{z}}$	(4c)	W I
$\mathbf{B_6}$	=	$\frac{3}{4}\,\mathbf{a}_1 + \frac{3}{4}\,\mathbf{a}_2 - \left(z_2 - \frac{1}{2}\right)\,\mathbf{a}_3$	=	$\frac{3}{4}a\,\hat{\mathbf{x}} + \frac{3}{4}a\,\hat{\mathbf{y}} - c\left(z_2 - \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4c)	W I
$\mathbf{B_7}$	=	$\frac{3}{4}\,\mathbf{a}_1 + \frac{3}{4}\,\mathbf{a}_2 - z_2\,\mathbf{a}_3$	=	$\frac{3}{4}a\,\hat{\mathbf{x}} + \frac{3}{4}a\,\hat{\mathbf{y}} - cz_2\,\hat{\mathbf{z}}$	(4c)	W I
$\mathbf{B_8}$	=	$\frac{1}{4}\,\mathbf{a}_1 + \frac{1}{4}\,\mathbf{a}_2 + \left(z_2 + \frac{1}{2}\right)\,\mathbf{a}_3$	=	$\frac{1}{4}a\,\hat{\mathbf{x}} + \frac{1}{4}a\,\hat{\mathbf{y}} + c\left(z_2 + \frac{1}{2}\right)\,\hat{\mathbf{z}}$	(4c)	W I
$\mathbf{B_9}$	=	$x_3\,\mathbf{a}_1 - x_3\,\mathbf{a}_2 + \frac{1}{4}\,\mathbf{a}_3$	=	$ax_3\,\hat{\mathbf{x}} - ax_3\,\hat{\mathbf{y}} + \frac{1}{4}c\,\hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B_{10}}$	=	$-\left(x_3 - \frac{1}{2}\right)\,\mathbf{a}_1 + \left(x_3 + \frac{1}{2}\right)\,\mathbf{a}_2 + \frac{1}{4}\,\mathbf{a}_3$	=	$-a\left(x_3 - \frac{1}{2}\right)\,\hat{\mathbf{x}} + a\left(x_3 + \frac{1}{2}\right)\,\hat{\mathbf{y}} + \frac{1}{4}c\,\hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B_{11}}$	=	$\left(x_3 + \frac{1}{2}\right)\,\mathbf{a}_1 + x_3\,\mathbf{a}_2 + \frac{1}{4}\,\mathbf{a}_3$	=	$a\left(x_3 + \frac{1}{2}\right)\,\hat{\mathbf{x}} + ax_3\,\hat{\mathbf{y}} + \frac{1}{4}c\,\hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B_{12}}$	=	$-x_3\,\mathbf{a}_1 - \left(x_3 - \frac{1}{2}\right)\,\mathbf{a}_2 + \frac{1}{4}\,\mathbf{a}_3$	=	$-ax_3\,\hat{\mathbf{x}} - a\left(x_3 - \frac{1}{2}\right)\,\hat{\mathbf{y}} + \frac{1}{4}c\,\hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B_{13}}$	=	$-x_3\,\mathbf{a}_1 + x_3\,\mathbf{a}_2 + \frac{3}{4}\,\mathbf{a}_3$	=	$-ax_3\,\hat{\mathbf{x}} + ax_3\,\hat{\mathbf{y}} + \frac{3}{4}c\,\hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B_{14}}$	=	$\left(x_3 + \frac{1}{2}\right)\,\mathbf{a}_1 - \left(x_3 - \frac{1}{2}\right)\,\mathbf{a}_2 + \frac{3}{4}\,\mathbf{a}_3$	=	$a\left(x_3 + \frac{1}{2}\right)\,\hat{\mathbf{x}} - a\left(x_3 - \frac{1}{2}\right)\,\hat{\mathbf{y}} + \frac{3}{4}c\,\hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B_{15}}$	=	$-\left(x_3 - \frac{1}{2}\right)\,\mathbf{a}_1 - x_3\,\mathbf{a}_2 + \frac{3}{4}\,\mathbf{a}_3$	=	$-a\left(x_3 - \frac{1}{2}\right)\,\hat{\mathbf{x}} - ax_3\,\hat{\mathbf{y}} + \frac{3}{4}c\,\hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B_{16}}$	=	$x_3\,\mathbf{a}_1 + \left(x_3 + \frac{1}{2}\right)\,\mathbf{a}_2 + \frac{3}{4}\,\mathbf{a}_3$	=	$ax_3\,\hat{\mathbf{x}} + a\left(x_3 + \frac{1}{2}\right)\,\hat{\mathbf{y}} + \frac{3}{4}c\,\hat{\mathbf{z}}$	(8f)	O II

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