

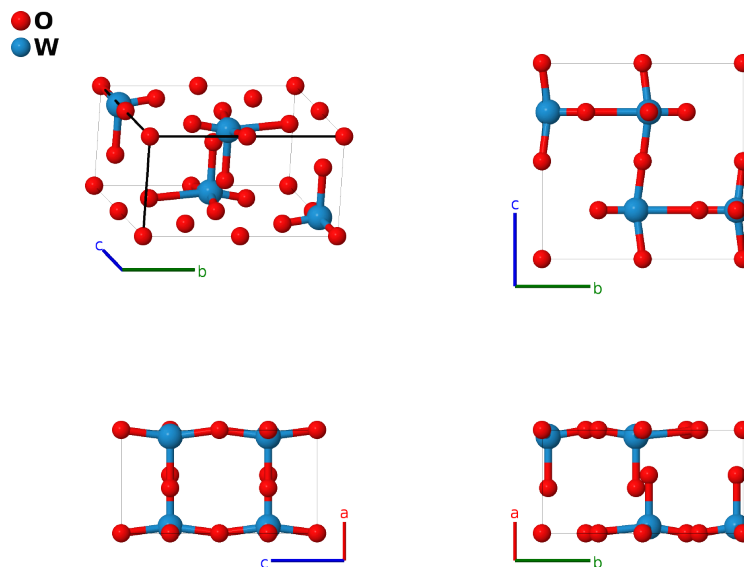
D_{010} (WO_3) Structure (*Obsolete*): A3B_oP16_57_a2d_d-001

This structure originally had the label A3B_oP16_57_a2d_d. Calls to that address will be redirected here.

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<https://afLOW.org/p/5B3E>

https://afLOW.org/p/A3B_oP16_57_a2d_d-001



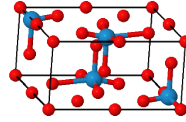
Prototype	O_3W
AFLOW prototype label	A3B_oP16_57_a2d_d-001
<i>Strukturbericht</i> designation	D_{010}
ICSD	none
Pearson symbol	oP16
Space group number	57
Space group symbol	$Pbcm$
AFLOW prototype command	<code>afLOW --proto=A3B_oP16_57_a2d_d-001 --params=a, b/a, c/a, x2, y2, x3, y3, x4, y4</code>

- All stable phases of WO_3 are distortions of the cubic $\alpha\text{-ReO}_3$ (D_{09}) phase. Based on (Woodward, 1997 and Vogt, 1999), the known stable phases and their approximate temperature ranges are:
 - $\alpha\text{-WO}_3$ (1010-1170 K) (Vogt, 1999)
 - $\beta\text{-WO}_3$ (600-1170 K) (Vogt, 1999)
 - $\gamma\text{-WO}_3$ (290-600 K) (Vogt, 1999)

- δ -WO₃ (230-290 K) (Diehl, 1978)
- ϵ -WO₃ (below 23 K) (Woodward, 1997)
- Woodward notes that “The transition temperatures display large hysteresis effects and universal agreement is not found in the literature.”
- In addition, several other structures have been proposed and/or found:
 - The original $D0_{10}$ structure (Bräkken, 1931), (Hermann, 1937) (this structure), superseded by δ -WO₃
 - The original β -WO₃ (Salje, 1977)
 - Hexagonal WO₃, presumably metastable, found by (Gerand, 1979) while dehydrating WO₃·H₂O
- (Bräkken, 1931) found a triclinic unit cell for WO₃ (this structure). As it was nearly orthorhombic, (Hermann, 1937) approximated it with the structure shown here and gave it the *Strukturbericht* symbol $D0_{10}$. Later (Diehl, 1978) showed that the near-room-temperature phase of WO₃ was indeed a triclinic crystal, but the unit cell was double that of Bräkken and is in fact a pseudo-cubic distorted perovskite.
- We retain this original structure for its historical interest.

Simple Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	0	$=$	0	(4a)	O I
\mathbf{B}_2	$\frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2} c \hat{\mathbf{z}}$	(4a)	O I
\mathbf{B}_3	$\frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2} b \hat{\mathbf{y}} + \frac{1}{2} c \hat{\mathbf{z}}$	(4a)	O I
\mathbf{B}_4	$\frac{1}{2} \mathbf{a}_2$	$=$	$\frac{1}{2} b \hat{\mathbf{y}}$	(4a)	O I
\mathbf{B}_5	$x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + \frac{1}{4} c \hat{\mathbf{z}}$	(4d)	O II
\mathbf{B}_6	$-x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + \frac{3}{4} c \hat{\mathbf{z}}$	(4d)	O II
\mathbf{B}_7	$-x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} + \frac{1}{4} c \hat{\mathbf{z}}$	(4d)	O II
\mathbf{B}_8	$x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + \frac{3}{4} c \hat{\mathbf{z}}$	(4d)	O II
\mathbf{B}_9	$x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + \frac{1}{4} c \hat{\mathbf{z}}$	(4d)	O III
\mathbf{B}_{10}	$-x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + \frac{3}{4} c \hat{\mathbf{z}}$	(4d)	O III
\mathbf{B}_{11}	$-x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} + \frac{1}{4} c \hat{\mathbf{z}}$	(4d)	O III
\mathbf{B}_{12}	$x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + \frac{3}{4} c \hat{\mathbf{z}}$	(4d)	O III
\mathbf{B}_{13}	$x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$ax_4 \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + \frac{1}{4} c \hat{\mathbf{z}}$	(4d)	W I
\mathbf{B}_{14}	$-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$-ax_4 \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + \frac{3}{4} c \hat{\mathbf{z}}$	(4d)	W I
\mathbf{B}_{15}	$-x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$-ax_4 \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} + \frac{1}{4} c \hat{\mathbf{z}}$	(4d)	W I
\mathbf{B}_{16}	$x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$ax_4 \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + \frac{3}{4} c \hat{\mathbf{z}}$	(4d)	W I

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