

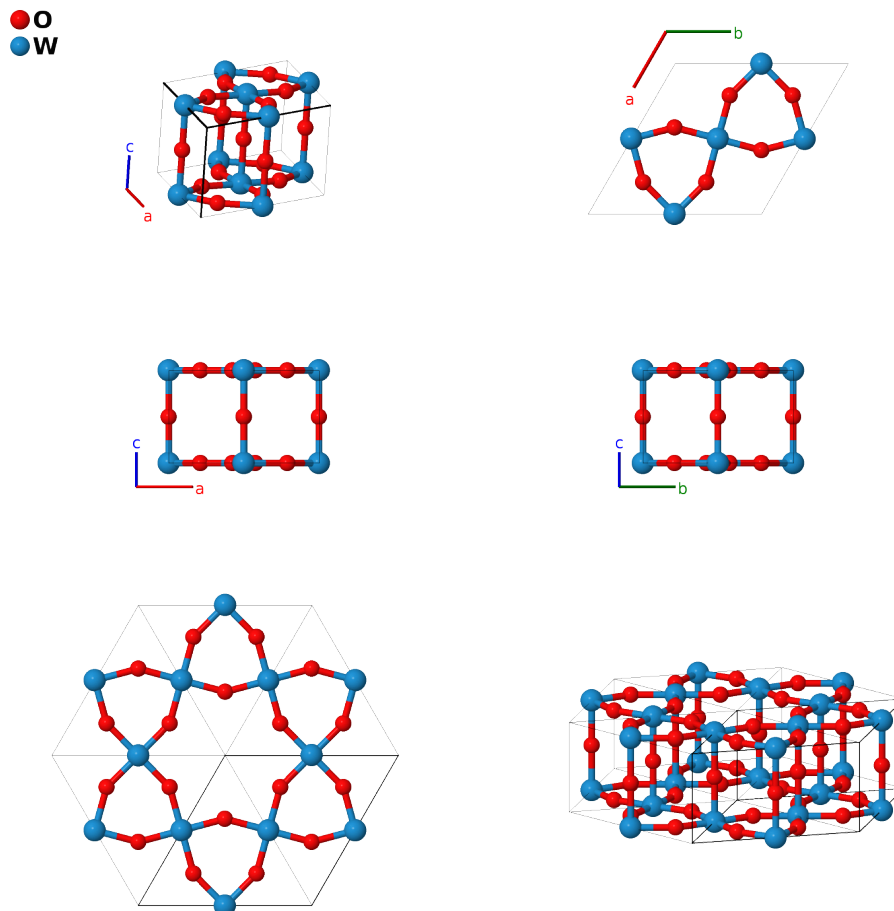
# Hexagonal $\text{WO}_3$ Structure: A3B\_hP12\_191\_gl\_f-001

This structure originally had the label `A3B_hP12_191_gl_f`. Calls to that address will be redirected here.

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<https://aflow.org/p/SQAX>

[https://aflow.org/p/A3B\\_hP12\\_191\\_gl\\_f-001](https://aflow.org/p/A3B_hP12_191_gl_f-001)



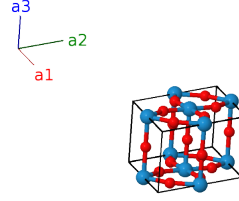
Prototype	$\text{O}_3\text{W}$
AFLOW prototype label	A3B_hP12_191_gl_f-001
ICSD	32001
Pearson symbol	hP12
Space group number	191
Space group symbol	$P6/mmm$
AFLOW prototype command	<code>aflow --proto=A3B_hP12_191_gl_f-001 --params=a, c/a, x3</code>

- All stable phases of  $\text{WO}_3$  are distortions of the cubic  $\alpha\text{-ReO}_3$  ( $D0_9$ ) phase. Based on (Woodward, 1997 and Vogt, 1999), the known stable phases and their approximate temperature ranges are:
  - $\alpha\text{-WO}_3$  (1010-1170 K) (Vogt, 1999)
  - $\beta\text{-WO}_3$  (600-1170 K) (Vogt, 1999)
  - $\gamma\text{-WO}_3$  (290-600 K) (Vogt, 1999)
  - $\delta\text{-WO}_3$  (230-290 K) (Diehl, 1978)
  - $\epsilon\text{-WO}_3$  (below 23 K) (Woodward, 1997)
- Woodward notes that “The transition temperatures display large hysteresis effects and universal agreement is not found in the literature.”
- In addition, several other structures have been proposed and/or found:
  - The original  $D0_{10}$  structure (Brækken, 1931; Hermann, 1937), superseded by  $\delta\text{-WO}_3$
  - The original  $\beta\text{-WO}_3$  (Salje, 1977)
  - Hexagonal  $\text{WO}_3$ , presumably metastable, found by (Gerand, 1979) while dehydrating  $\text{WO}_3\cdot\text{H}_2\text{O}$  (this structure)
- (Gerand, 1979) determined the structure of hexagonal  $\text{WO}_3$  by X-ray diffraction of powdered samples. They found evidence of super-reflection, indicating that the unit cell should be doubled along the  $c$ -axis, but were unable to determine the shift in atomic positions for the double unit cell. We report what they called the “half-cell” structure.

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### Hexagonal primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{2}a \hat{\mathbf{y}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{\sqrt{3}}{2}a \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \hat{\mathbf{z}}\end{aligned}$$




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### Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= \frac{1}{2} \mathbf{a}_1$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{4}a \hat{\mathbf{y}}$	(3f)	W I
$\mathbf{B}_2$	$= \frac{1}{2} \mathbf{a}_2$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + \frac{\sqrt{3}}{4}a \hat{\mathbf{y}}$	(3f)	W I
$\mathbf{B}_3$	$= \frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2$	$=$	$\frac{1}{2}a \hat{\mathbf{x}}$	(3f)	W I
$\mathbf{B}_4$	$= \frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} - \frac{\sqrt{3}}{4}a \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$	(3g)	O I
$\mathbf{B}_5$	$= \frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{4}a \hat{\mathbf{x}} + \frac{\sqrt{3}}{4}a \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}$	(3g)	O I
$\mathbf{B}_6$	$= \frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$	$=$	$\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}c \hat{\mathbf{z}}$	(3g)	O I
$\mathbf{B}_7$	$= x_3 \mathbf{a}_1 + 2x_3 \mathbf{a}_2$	$=$	$\frac{3}{2}ax_3 \hat{\mathbf{x}} + \frac{\sqrt{3}}{2}ax_3 \hat{\mathbf{y}}$	(6l)	O II
$\mathbf{B}_8$	$= -2x_3 \mathbf{a}_1 - x_3 \mathbf{a}_2$	$=$	$-\frac{3}{2}ax_3 \hat{\mathbf{x}} + \frac{\sqrt{3}}{2}ax_3 \hat{\mathbf{y}}$	(6l)	O II
$\mathbf{B}_9$	$= x_3 \mathbf{a}_1 - x_3 \mathbf{a}_2$	$=$	$-\sqrt{3}ax_3 \hat{\mathbf{y}}$	(6l)	O II
$\mathbf{B}_{10}$	$= -x_3 \mathbf{a}_1 - 2x_3 \mathbf{a}_2$	$=$	$-\frac{3}{2}ax_3 \hat{\mathbf{x}} - \frac{\sqrt{3}}{2}ax_3 \hat{\mathbf{y}}$	(6l)	O II
$\mathbf{B}_{11}$	$= 2x_3 \mathbf{a}_1 + x_3 \mathbf{a}_2$	$=$	$\frac{3}{2}ax_3 \hat{\mathbf{x}} - \frac{\sqrt{3}}{2}ax_3 \hat{\mathbf{y}}$	(6l)	O II
$\mathbf{B}_{12}$	$= -x_3 \mathbf{a}_1 + x_3 \mathbf{a}_2$	$=$	$\sqrt{3}ax_3 \hat{\mathbf{y}}$	(6l)	O II

## References

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## Found in

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