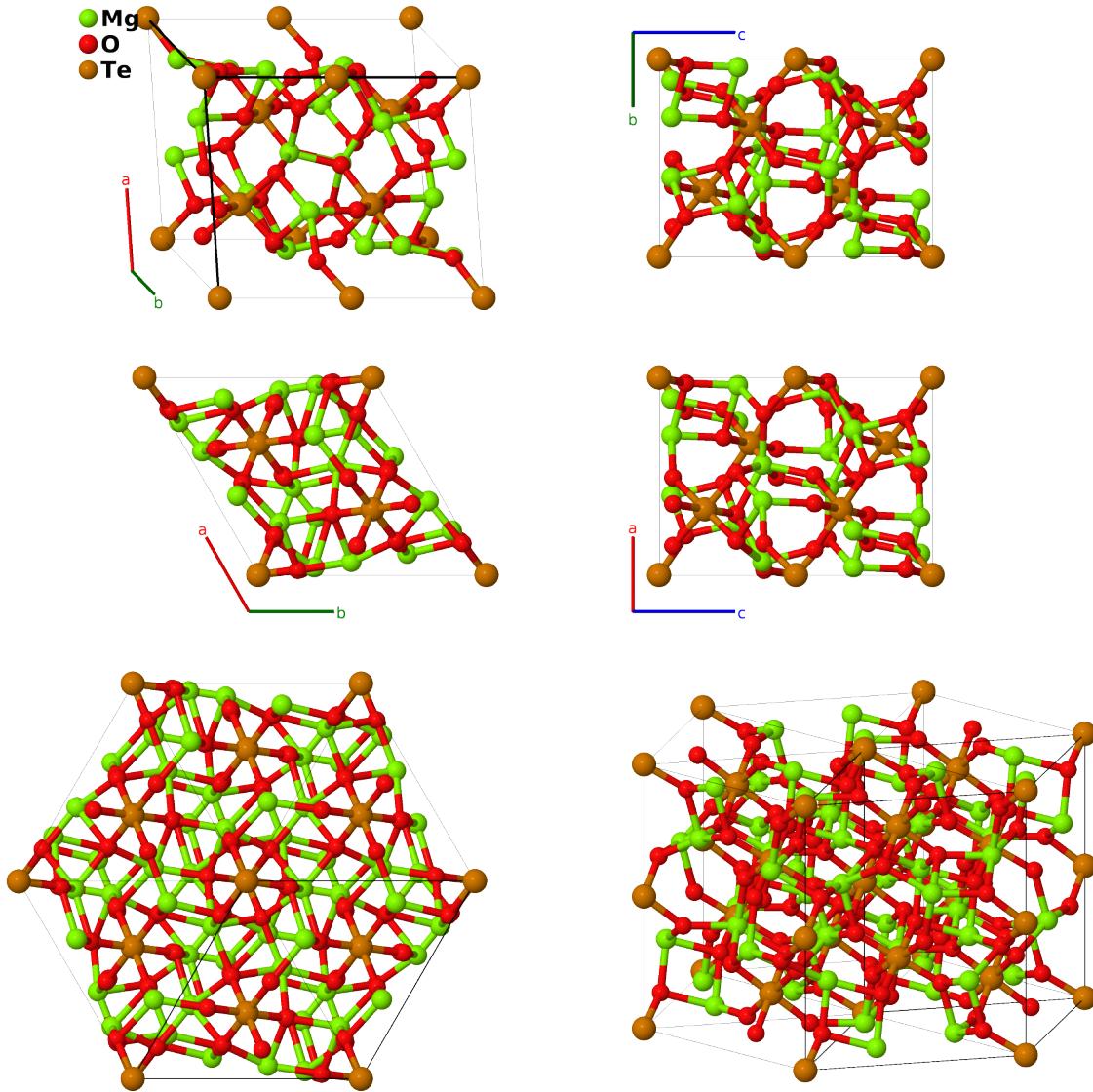


# Mg<sub>3</sub>TeO<sub>6</sub> Structure: A3B6C\_hR20\_148\_f\_2f\_ab-001

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<https://aflow.org/p/K70X>

[https://aflow.org/p/A3B6C\\_hR20\\_148\\_f\\_2f\\_ab-001](https://aflow.org/p/A3B6C_hR20_148_f_2f_ab-001)



|                       |                                   |
|-----------------------|-----------------------------------|
| Prototype             | Mg <sub>3</sub> O <sub>6</sub> Te |
| AFLOW prototype label | A3B6C_hR20_148_f_2f_ab-001        |
| ICSD                  | 23611                             |
| Pearson symbol        | hR20                              |
| Space group number    | 148                               |
| Space group symbol    | $R\bar{3}$                        |

**AFLOW prototype command**    `aflow --proto=A3B6C_hR20_148_f_2f_ab-001  
--params=a, c/a, x3, y3, z3, x4, y4, z4, x5, y5, z5`

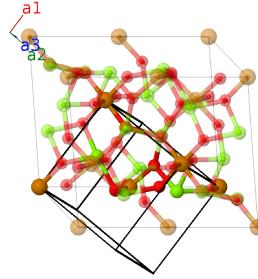
### Other compounds with this structure

Bi<sub>3</sub>DyO<sub>6</sub>, Bi<sub>3</sub>ErO<sub>6</sub>, Bi<sub>3</sub>LuO<sub>6</sub>, Bi<sub>3</sub>YO<sub>6</sub>, Ca<sub>3</sub>UO<sub>6</sub>, La<sub>3</sub>ScO<sub>6</sub>, Li<sub>3</sub>AlH<sub>6</sub>, Li<sub>3</sub>AlO<sub>6</sub>, Li<sub>3</sub>CuF<sub>6</sub>, Li<sub>3</sub>FeF<sub>6</sub>, Li<sub>3</sub>VF<sub>6</sub>, Mg<sub>3</sub>SbO<sub>6</sub>, Mn<sub>3</sub>TeO<sub>6</sub>, Mn<sub>3</sub>WO<sub>6</sub>

- Hexagonal settings of this structure can be obtained with the option `--hex`.

### Rhombohedral primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a\hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a\hat{\mathbf{y}} + \frac{1}{3}c\hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{\sqrt{3}}a\hat{\mathbf{y}} + \frac{1}{3}c\hat{\mathbf{z}} \\ \mathbf{a}_3 &= -\frac{1}{2}a\hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a\hat{\mathbf{y}} + \frac{1}{3}c\hat{\mathbf{z}}\end{aligned}$$



### Basis vectors

|                   | Lattice coordinates                                                             | Cartesian coordinates                                                                                                                                | Wyckoff position | Atom type |
|-------------------|---------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------|------------------|-----------|
| $\mathbf{B}_1$    | = 0                                                                             | = 0                                                                                                                                                  | (1a)             | Te I      |
| $\mathbf{B}_2$    | = $\frac{1}{2}\mathbf{a}_1 + \frac{1}{2}\mathbf{a}_2 + \frac{1}{2}\mathbf{a}_3$ | = $\frac{1}{2}c\hat{\mathbf{z}}$                                                                                                                     | (1b)             | Te II     |
| $\mathbf{B}_3$    | = $x_3\mathbf{a}_1 + y_3\mathbf{a}_2 + z_3\mathbf{a}_3$                         | = $\frac{1}{2}a(x_3 - z_3)\hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_3 - 2y_3 + z_3)\hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3)\hat{\mathbf{z}}$  | (6f)             | Mg I      |
| $\mathbf{B}_4$    | = $z_3\mathbf{a}_1 + x_3\mathbf{a}_2 + y_3\mathbf{a}_3$                         | = $-\frac{1}{2}a(y_3 - z_3)\hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(2x_3 - y_3 - z_3)\hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3)\hat{\mathbf{z}}$ | (6f)             | Mg I      |
| $\mathbf{B}_5$    | = $y_3\mathbf{a}_1 + z_3\mathbf{a}_2 + x_3\mathbf{a}_3$                         | = $-\frac{1}{2}a(x_3 - y_3)\hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_3 + y_3 - 2z_3)\hat{\mathbf{y}} + \frac{1}{3}c(x_3 + y_3 + z_3)\hat{\mathbf{z}}$ | (6f)             | Mg I      |
| $\mathbf{B}_6$    | = $-x_3\mathbf{a}_1 - y_3\mathbf{a}_2 - z_3\mathbf{a}_3$                        | = $-\frac{1}{2}a(x_3 - z_3)\hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 - 2y_3 + z_3)\hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3)\hat{\mathbf{z}}$ | (6f)             | Mg I      |
| $\mathbf{B}_7$    | = $-z_3\mathbf{a}_1 - x_3\mathbf{a}_2 - y_3\mathbf{a}_3$                        | = $\frac{1}{2}a(y_3 - z_3)\hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(2x_3 - y_3 - z_3)\hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3)\hat{\mathbf{z}}$  | (6f)             | Mg I      |
| $\mathbf{B}_8$    | = $-y_3\mathbf{a}_1 - z_3\mathbf{a}_2 - x_3\mathbf{a}_3$                        | = $\frac{1}{2}a(x_3 - y_3)\hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_3 + y_3 - 2z_3)\hat{\mathbf{y}} - \frac{1}{3}c(x_3 + y_3 + z_3)\hat{\mathbf{z}}$  | (6f)             | Mg I      |
| $\mathbf{B}_9$    | = $x_4\mathbf{a}_1 + y_4\mathbf{a}_2 + z_4\mathbf{a}_3$                         | = $\frac{1}{2}a(x_4 - z_4)\hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_4 - 2y_4 + z_4)\hat{\mathbf{y}} + \frac{1}{3}c(x_4 + y_4 + z_4)\hat{\mathbf{z}}$  | (6f)             | O I       |
| $\mathbf{B}_{10}$ | = $z_4\mathbf{a}_1 + x_4\mathbf{a}_2 + y_4\mathbf{a}_3$                         | = $-\frac{1}{2}a(y_4 - z_4)\hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(2x_4 - y_4 - z_4)\hat{\mathbf{y}} + \frac{1}{3}c(x_4 + y_4 + z_4)\hat{\mathbf{z}}$ | (6f)             | O I       |
| $\mathbf{B}_{11}$ | = $y_4\mathbf{a}_1 + z_4\mathbf{a}_2 + x_4\mathbf{a}_3$                         | = $-\frac{1}{2}a(x_4 - y_4)\hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_4 + y_4 - 2z_4)\hat{\mathbf{y}} + \frac{1}{3}c(x_4 + y_4 + z_4)\hat{\mathbf{z}}$ | (6f)             | O I       |
| $\mathbf{B}_{12}$ | = $-x_4\mathbf{a}_1 - y_4\mathbf{a}_2 - z_4\mathbf{a}_3$                        | = $-\frac{1}{2}a(x_4 - z_4)\hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_4 - 2y_4 + z_4)\hat{\mathbf{y}} - \frac{1}{3}c(x_4 + y_4 + z_4)\hat{\mathbf{z}}$ | (6f)             | O I       |
| $\mathbf{B}_{13}$ | = $-z_4\mathbf{a}_1 - x_4\mathbf{a}_2 - y_4\mathbf{a}_3$                        | = $\frac{1}{2}a(y_4 - z_4)\hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(2x_4 - y_4 - z_4)\hat{\mathbf{y}} - \frac{1}{3}c(x_4 + y_4 + z_4)\hat{\mathbf{z}}$  | (6f)             | O I       |
| $\mathbf{B}_{14}$ | = $-y_4\mathbf{a}_1 - z_4\mathbf{a}_2 - x_4\mathbf{a}_3$                        | = $\frac{1}{2}a(x_4 - y_4)\hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_4 + y_4 - 2z_4)\hat{\mathbf{y}} - \frac{1}{3}c(x_4 + y_4 + z_4)\hat{\mathbf{z}}$  | (6f)             | O I       |

|                       |                                                           |                                                                                                                                                         |      |      |
|-----------------------|-----------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------|------|------|
| <b>B<sub>15</sub></b> | $x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$  | $= \frac{1}{2}a(x_5 - z_5) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_5 - 2y_5 + z_5) \hat{\mathbf{y}} + \frac{1}{3}c(x_5 + y_5 + z_5) \hat{\mathbf{z}}$  | (6f) | O II |
| <b>B<sub>16</sub></b> | $z_5 \mathbf{a}_1 + x_5 \mathbf{a}_2 + y_5 \mathbf{a}_3$  | $= -\frac{1}{2}a(y_5 - z_5) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(2x_5 - y_5 - z_5) \hat{\mathbf{y}} + \frac{1}{3}c(x_5 + y_5 + z_5) \hat{\mathbf{z}}$ | (6f) | O II |
| <b>B<sub>17</sub></b> | $y_5 \mathbf{a}_1 + z_5 \mathbf{a}_2 + x_5 \mathbf{a}_3$  | $= -\frac{1}{2}a(x_5 - y_5) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(x_5 + y_5 - 2z_5) \hat{\mathbf{y}} + \frac{1}{3}c(x_5 + y_5 + z_5) \hat{\mathbf{z}}$ | (6f) | O II |
| <b>B<sub>18</sub></b> | $-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$ | $= -\frac{1}{2}a(x_5 - z_5) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_5 - 2y_5 + z_5) \hat{\mathbf{y}} - \frac{1}{3}c(x_5 + y_5 + z_5) \hat{\mathbf{z}}$ | (6f) | O II |
| <b>B<sub>19</sub></b> | $-z_5 \mathbf{a}_1 - x_5 \mathbf{a}_2 - y_5 \mathbf{a}_3$ | $= \frac{1}{2}a(y_5 - z_5) \hat{\mathbf{x}} - \frac{\sqrt{3}}{6}a(2x_5 - y_5 - z_5) \hat{\mathbf{y}} - \frac{1}{3}c(x_5 + y_5 + z_5) \hat{\mathbf{z}}$  | (6f) | O II |
| <b>B<sub>20</sub></b> | $-y_5 \mathbf{a}_1 - z_5 \mathbf{a}_2 - x_5 \mathbf{a}_3$ | $= \frac{1}{2}a(x_5 - y_5) \hat{\mathbf{x}} + \frac{\sqrt{3}}{6}a(x_5 + y_5 - 2z_5) \hat{\mathbf{y}} - \frac{1}{3}c(x_5 + y_5 + z_5) \hat{\mathbf{z}}$  | (6f) | O II |

## References

- [1] H. Schulz and G. Bayer, *A New Structure Type Mg<sub>3</sub>TeO<sub>6</sub>*, Naturwissenschaften **57**, 393 (1970), doi:10.1007/BF00599979.