

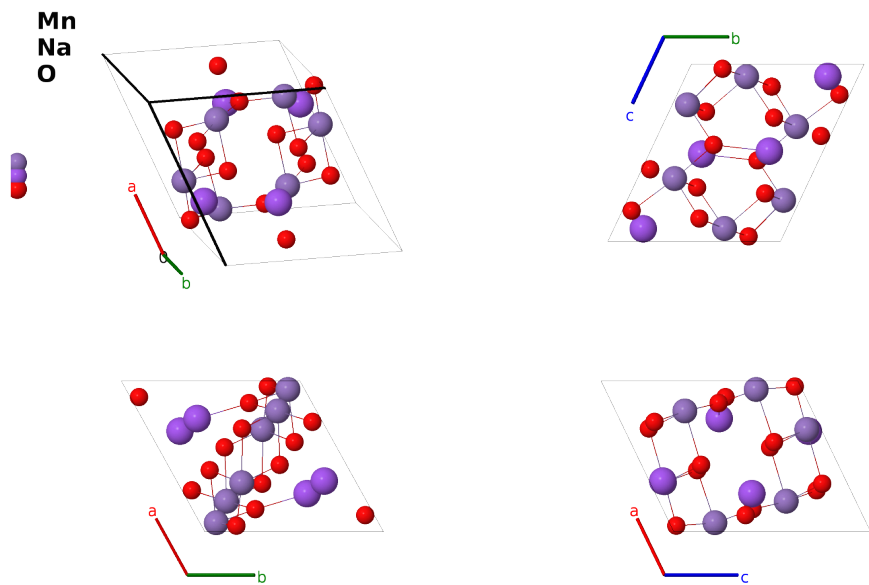
Na₂Mn₃O₇ “Maple Leaf” Structure: A3B2C7_aP24_2_3i_2i_7i-001

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<https://aflow.org/prototype-encyclopedia/62D7>

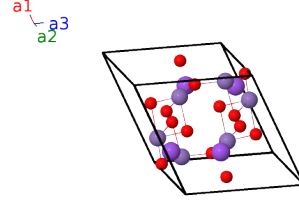
https://aflow.org/prototype-encyclopedia/A3B2C7_aP24_2_3i_2i_7i-001



Prototype	Mn ₃ Na ₂ O ₇
AFLOW prototype label	A3B2C7_aP24_2_3i_2i_7i-001
ICSD	92858
CCDC	1652339
Pearson symbol	aP24
Space group number	2
Space group symbol	$P\bar{1}$
AFLOW prototype command	<pre>aflow --proto=A3B2C7_aP24_2_3i_2i_7i-001 --params=a,b/a,c/a,α,β,γ,x₁,y₁,z₁,x₂,y₂,z₂,x₃,y₃,z₃,x₄,y₄,z₄,x₅,y₅,z₅,x₆,y₆, z₆,x₇,y₇,z₇,x₈,y₈,z₈,x₉,y₉,z₉,x₁₀,y₁₀,z₁₀,x₁₁,y₁₁,z₁₁,x₁₂,y₁₂,z₁₂</pre>

Triclinic primitive vectors

$$\begin{aligned}
\mathbf{a}_1 &= a \hat{\mathbf{x}} \\
\mathbf{a}_2 &= b \cos \gamma \hat{\mathbf{x}} + b \sin \gamma \hat{\mathbf{y}} \\
\mathbf{a}_3 &= c_x \hat{\mathbf{x}} + c_y \hat{\mathbf{y}} + c_z \hat{\mathbf{z}} \\
c_x &= c \cos \beta \\
c_y &= c(\cos \alpha - \cos \beta \cos \gamma) / \sin \gamma \\
c_z &= \sqrt{c^2 - c_x^2 - c_y^2}
\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$(ax_1 + by_1 \cos \gamma + c_x z_1) \hat{\mathbf{x}} + (by_1 \sin \gamma + c_y z_1) \hat{\mathbf{y}} + c_z z_1 \hat{\mathbf{z}}$	(2i)	Mn I
$\mathbf{B}_2$	$= -x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$-(ax_1 + by_1 \cos \gamma + c_x z_1) \hat{\mathbf{x}} - (by_1 \sin \gamma + c_y z_1) \hat{\mathbf{y}} - c_z z_1 \hat{\mathbf{z}}$	(2i)	Mn I
$\mathbf{B}_3$	$= x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$(ax_2 + by_2 \cos \gamma + c_x z_2) \hat{\mathbf{x}} + (by_2 \sin \gamma + c_y z_2) \hat{\mathbf{y}} + c_z z_2 \hat{\mathbf{z}}$	(2i)	Mn II
$\mathbf{B}_4$	$= -x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-(ax_2 + by_2 \cos \gamma + c_x z_2) \hat{\mathbf{x}} - (by_2 \sin \gamma + c_y z_2) \hat{\mathbf{y}} - c_z z_2 \hat{\mathbf{z}}$	(2i)	Mn II
$\mathbf{B}_5$	$= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + by_3 \cos \gamma + c_x z_3) \hat{\mathbf{x}} + (by_3 \sin \gamma + c_y z_3) \hat{\mathbf{y}} + c_z z_3 \hat{\mathbf{z}}$	(2i)	Mn III
$\mathbf{B}_6$	$= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + by_3 \cos \gamma + c_x z_3) \hat{\mathbf{x}} - (by_3 \sin \gamma + c_y z_3) \hat{\mathbf{y}} - c_z z_3 \hat{\mathbf{z}}$	(2i)	Mn III
$\mathbf{B}_7$	$= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + by_4 \cos \gamma + c_x z_4) \hat{\mathbf{x}} + (by_4 \sin \gamma + c_y z_4) \hat{\mathbf{y}} + c_z z_4 \hat{\mathbf{z}}$	(2i)	Na I
$\mathbf{B}_8$	$= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + by_4 \cos \gamma + c_x z_4) \hat{\mathbf{x}} - (by_4 \sin \gamma + c_y z_4) \hat{\mathbf{y}} - c_z z_4 \hat{\mathbf{z}}$	(2i)	Na I
$\mathbf{B}_9$	$= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + by_5 \cos \gamma + c_x z_5) \hat{\mathbf{x}} + (by_5 \sin \gamma + c_y z_5) \hat{\mathbf{y}} + c_z z_5 \hat{\mathbf{z}}$	(2i)	Na II
$\mathbf{B}_{10}$	$= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-(ax_5 + by_5 \cos \gamma + c_x z_5) \hat{\mathbf{x}} - (by_5 \sin \gamma + c_y z_5) \hat{\mathbf{y}} - c_z z_5 \hat{\mathbf{z}}$	(2i)	Na II
$\mathbf{B}_{11}$	$= x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$(ax_6 + by_6 \cos \gamma + c_x z_6) \hat{\mathbf{x}} + (by_6 \sin \gamma + c_y z_6) \hat{\mathbf{y}} + c_z z_6 \hat{\mathbf{z}}$	(2i)	O I
$\mathbf{B}_{12}$	$= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	$=$	$-(ax_6 + by_6 \cos \gamma + c_x z_6) \hat{\mathbf{x}} - (by_6 \sin \gamma + c_y z_6) \hat{\mathbf{y}} - c_z z_6 \hat{\mathbf{z}}$	(2i)	O I
$\mathbf{B}_{13}$	$= x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3$	$=$	$(ax_7 + by_7 \cos \gamma + c_x z_7) \hat{\mathbf{x}} + (by_7 \sin \gamma + c_y z_7) \hat{\mathbf{y}} + c_z z_7 \hat{\mathbf{z}}$	(2i)	O II
$\mathbf{B}_{14}$	$= -x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3$	$=$	$-(ax_7 + by_7 \cos \gamma + c_x z_7) \hat{\mathbf{x}} - (by_7 \sin \gamma + c_y z_7) \hat{\mathbf{y}} - c_z z_7 \hat{\mathbf{z}}$	(2i)	O II
$\mathbf{B}_{15}$	$= x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3$	$=$	$(ax_8 + by_8 \cos \gamma + c_x z_8) \hat{\mathbf{x}} + (by_8 \sin \gamma + c_y z_8) \hat{\mathbf{y}} + c_z z_8 \hat{\mathbf{z}}$	(2i)	O III
$\mathbf{B}_{16}$	$= -x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3$	$=$	$-(ax_8 + by_8 \cos \gamma + c_x z_8) \hat{\mathbf{x}} - (by_8 \sin \gamma + c_y z_8) \hat{\mathbf{y}} - c_z z_8 \hat{\mathbf{z}}$	(2i)	O III
$\mathbf{B}_{17}$	$= x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3$	$=$	$(ax_9 + by_9 \cos \gamma + c_x z_9) \hat{\mathbf{x}} + (by_9 \sin \gamma + c_y z_9) \hat{\mathbf{y}} + c_z z_9 \hat{\mathbf{z}}$	(2i)	O IV
$\mathbf{B}_{18}$	$= -x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3$	$=$	$-(ax_9 + by_9 \cos \gamma + c_x z_9) \hat{\mathbf{x}} - (by_9 \sin \gamma + c_y z_9) \hat{\mathbf{y}} - c_z z_9 \hat{\mathbf{z}}$	(2i)	O IV

$$\begin{aligned}
\mathbf{B}_{19} &= x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3 &= (ax_{10} + by_{10} \cos \gamma + c_x z_{10}) \hat{\mathbf{x}} + (by_{10} \sin \gamma + c_y z_{10}) \hat{\mathbf{y}} + c_z z_{10} \hat{\mathbf{z}} &(2i) & \text{O V} \\
\mathbf{B}_{20} &= -x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3 &= -(ax_{10} + by_{10} \cos \gamma + c_x z_{10}) \hat{\mathbf{x}} - (by_{10} \sin \gamma + c_y z_{10}) \hat{\mathbf{y}} - c_z z_{10} \hat{\mathbf{z}} &(2i) & \text{O V} \\
\mathbf{B}_{21} &= x_{11} \mathbf{a}_1 + y_{11} \mathbf{a}_2 + z_{11} \mathbf{a}_3 &= (ax_{11} + by_{11} \cos \gamma + c_x z_{11}) \hat{\mathbf{x}} + (by_{11} \sin \gamma + c_y z_{11}) \hat{\mathbf{y}} + c_z z_{11} \hat{\mathbf{z}} &(2i) & \text{O VI} \\
\mathbf{B}_{22} &= -x_{11} \mathbf{a}_1 - y_{11} \mathbf{a}_2 - z_{11} \mathbf{a}_3 &= -(ax_{11} + by_{11} \cos \gamma + c_x z_{11}) \hat{\mathbf{x}} - (by_{11} \sin \gamma + c_y z_{11}) \hat{\mathbf{y}} - c_z z_{11} \hat{\mathbf{z}} &(2i) & \text{O VI} \\
\mathbf{B}_{23} &= x_{12} \mathbf{a}_1 + y_{12} \mathbf{a}_2 + z_{12} \mathbf{a}_3 &= (ax_{12} + by_{12} \cos \gamma + c_x z_{12}) \hat{\mathbf{x}} + (by_{12} \sin \gamma + c_y z_{12}) \hat{\mathbf{y}} + c_z z_{12} \hat{\mathbf{z}} &(2i) & \text{O VII} \\
\mathbf{B}_{24} &= -x_{12} \mathbf{a}_1 - y_{12} \mathbf{a}_2 - z_{12} \mathbf{a}_3 &= -(ax_{12} + by_{12} \cos \gamma + c_x z_{12}) \hat{\mathbf{x}} - (by_{12} \sin \gamma + c_y z_{12}) \hat{\mathbf{y}} - c_z z_{12} \hat{\mathbf{z}} &(2i) & \text{O VII}
\end{aligned}$$

References

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