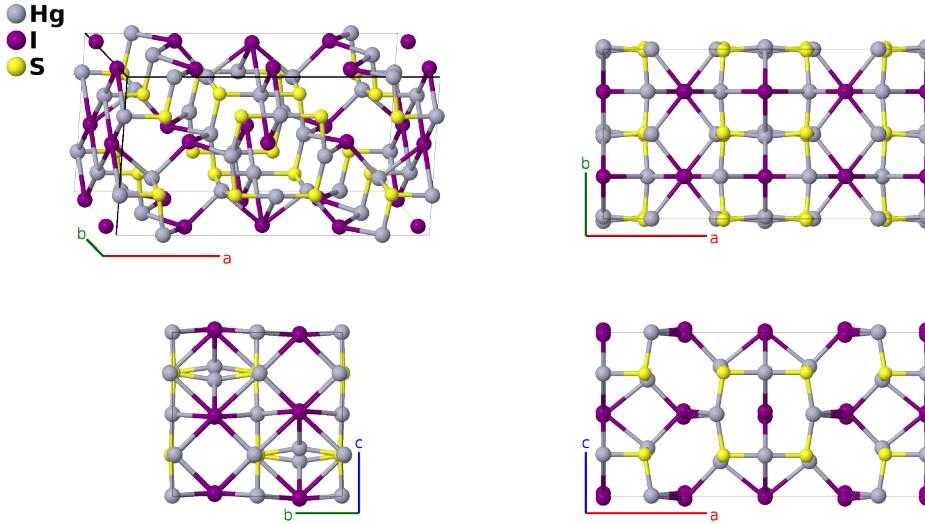


# Hg<sub>3</sub>S<sub>2</sub>I<sub>2</sub> Structure: A3B2C2\_oI56\_74\_fhi\_2ei\_j-001

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<https://aflow.org/p/EXRV>

[https://aflow.org/p/A3B2C2\\_oI56\\_74\\_fhi\\_2ei\\_j-001](https://aflow.org/p/A3B2C2_oI56_74_fhi_2ei_j-001)



Prototype	Hg <sub>3</sub> I <sub>2</sub> S <sub>2</sub>
AFLOW prototype label	A3B2C2_oI56_74_fhi_2ei_j-001
ICSD	411154
Pearson symbol	oI56
Space group number	74
Space group symbol	<i>Imma</i>
AFLOW prototype command	<code>aflow --proto=A3B2C2_oI56_74_fhi_2ei_j-001 --params=a, b/a, c/a, z<sub>1</sub>, z<sub>2</sub>, x<sub>3</sub>, y<sub>4</sub>, z<sub>4</sub>, x<sub>5</sub>, z<sub>5</sub>, x<sub>6</sub>, z<sub>6</sub>, x<sub>7</sub>, y<sub>7</sub>, z<sub>7</sub></code>

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## Other compounds with this structure

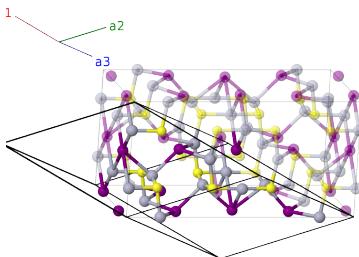
Hg<sub>3</sub>Se<sub>2</sub>I<sub>2</sub>

- FINDSYM rotated this structure by 90° about the *z*-axis and shifted the origin by  $(\mathbf{a}_1 + \mathbf{a}_2 + \mathbf{a}_3)/4$  compared to the structure in (Beck, 2000).

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## Body-centered Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= -\frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}b\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a\hat{\mathbf{x}} - \frac{1}{2}b\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}b\hat{\mathbf{y}} - \frac{1}{2}c\hat{\mathbf{z}}\end{aligned}$$



## Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$(z_1 + \frac{1}{4}) \mathbf{a}_1 + z_1 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	=	$\frac{1}{4}b \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(4e)	I I
$\mathbf{B}_2$	$-(z_1 - \frac{3}{4}) \mathbf{a}_1 - z_1 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	=	$\frac{3}{4}b \hat{\mathbf{y}} - cz_1 \hat{\mathbf{z}}$	(4e)	I I
$\mathbf{B}_3$	$(z_2 + \frac{1}{4}) \mathbf{a}_1 + z_2 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	=	$\frac{1}{4}b \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(4e)	I II
$\mathbf{B}_4$	$-(z_2 - \frac{3}{4}) \mathbf{a}_1 - z_2 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	=	$\frac{3}{4}b \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(4e)	I II
$\mathbf{B}_5$	$x_3 \mathbf{a}_2 + x_3 \mathbf{a}_3$	=	$ax_3 \hat{\mathbf{x}}$	(8f)	Hg I
$\mathbf{B}_6$	$\frac{1}{2} \mathbf{a}_1 - x_3 \mathbf{a}_2 - (x_3 - \frac{1}{2}) \mathbf{a}_3$	=	$-ax_3 \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}}$	(8f)	Hg I
$\mathbf{B}_7$	$-x_3 \mathbf{a}_2 - x_3 \mathbf{a}_3$	=	$-ax_3 \hat{\mathbf{x}}$	(8f)	Hg I
$\mathbf{B}_8$	$\frac{1}{2} \mathbf{a}_1 + x_3 \mathbf{a}_2 + (x_3 + \frac{1}{2}) \mathbf{a}_3$	=	$ax_3 \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}}$	(8f)	Hg I
$\mathbf{B}_9$	$(y_4 + z_4) \mathbf{a}_1 + z_4 \mathbf{a}_2 + y_4 \mathbf{a}_3$	=	$by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8h)	Hg II
$\mathbf{B}_{10}$	$(-y_4 + z_4 + \frac{1}{2}) \mathbf{a}_1 + z_4 \mathbf{a}_2 - (y_4 - \frac{1}{2}) \mathbf{a}_3$	=	$-b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8h)	Hg II
$\mathbf{B}_{11}$	$(y_4 - z_4 + \frac{1}{2}) \mathbf{a}_1 - z_4 \mathbf{a}_2 + (y_4 + \frac{1}{2}) \mathbf{a}_3$	=	$b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(8h)	Hg II
$\mathbf{B}_{12}$	$-(y_4 + z_4) \mathbf{a}_1 - z_4 \mathbf{a}_2 - y_4 \mathbf{a}_3$	=	$-by_4 \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$	(8h)	Hg II
$\mathbf{B}_{13}$	$(z_5 + \frac{1}{4}) \mathbf{a}_1 + (x_5 + z_5) \mathbf{a}_2 + (x_5 + \frac{1}{4}) \mathbf{a}_3$	=	$ax_5 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8i)	Hg III
$\mathbf{B}_{14}$	$(z_5 + \frac{1}{4}) \mathbf{a}_1 - (x_5 - z_5) \mathbf{a}_2 - (x_5 - \frac{1}{4}) \mathbf{a}_3$	=	$-ax_5 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8i)	Hg III
$\mathbf{B}_{15}$	$-(z_5 - \frac{3}{4}) \mathbf{a}_1 - (x_5 + z_5) \mathbf{a}_2 - (x_5 - \frac{3}{4}) \mathbf{a}_3$	=	$-ax_5 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$	(8i)	Hg III
$\mathbf{B}_{16}$	$-(z_5 - \frac{3}{4}) \mathbf{a}_1 + (x_5 - z_5) \mathbf{a}_2 + (x_5 + \frac{3}{4}) \mathbf{a}_3$	=	$ax_5 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$	(8i)	Hg III
$\mathbf{B}_{17}$	$(z_6 + \frac{1}{4}) \mathbf{a}_1 + (x_6 + z_6) \mathbf{a}_2 + (x_6 + \frac{1}{4}) \mathbf{a}_3$	=	$ax_6 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8i)	I III
$\mathbf{B}_{18}$	$(z_6 + \frac{1}{4}) \mathbf{a}_1 - (x_6 - z_6) \mathbf{a}_2 - (x_6 - \frac{1}{4}) \mathbf{a}_3$	=	$-ax_6 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8i)	I III
$\mathbf{B}_{19}$	$-(z_6 - \frac{3}{4}) \mathbf{a}_1 - (x_6 + z_6) \mathbf{a}_2 - (x_6 - \frac{3}{4}) \mathbf{a}_3$	=	$-ax_6 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}}$	(8i)	I III
$\mathbf{B}_{20}$	$-(z_6 - \frac{3}{4}) \mathbf{a}_1 + (x_6 - z_6) \mathbf{a}_2 + (x_6 + \frac{3}{4}) \mathbf{a}_3$	=	$ax_6 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}}$	(8i)	I III
$\mathbf{B}_{21}$	$(y_7 + z_7) \mathbf{a}_1 + (x_7 + z_7) \mathbf{a}_2 + (x_7 + y_7) \mathbf{a}_3$	=	$ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}}$	(16j)	S I
$\mathbf{B}_{22}$	$(-y_7 + z_7 + \frac{1}{2}) \mathbf{a}_1 - (x_7 - z_7) \mathbf{a}_2 - (x_7 + y_7 - \frac{1}{2}) \mathbf{a}_3$	=	$-ax_7 \hat{\mathbf{x}} - b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}}$	(16j)	S I
$\mathbf{B}_{23}$	$(y_7 - z_7 + \frac{1}{2}) \mathbf{a}_1 - (x_7 + z_7) \mathbf{a}_2 + (-x_7 + y_7 + \frac{1}{2}) \mathbf{a}_3$	=	$-ax_7 \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}}$	(16j)	S I
$\mathbf{B}_{24}$	$-(y_7 + z_7) \mathbf{a}_1 + (x_7 - z_7) \mathbf{a}_2 + (x_7 - y_7) \mathbf{a}_3$	=	$ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}}$	(16j)	S I
$\mathbf{B}_{25}$	$-(y_7 + z_7) \mathbf{a}_1 - (x_7 + z_7) \mathbf{a}_2 - (x_7 + y_7) \mathbf{a}_3$	=	$-ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}}$	(16j)	S I
$\mathbf{B}_{26}$	$(y_7 - z_7 + \frac{1}{2}) \mathbf{a}_1 + (x_7 - z_7) \mathbf{a}_2 + (x_7 + y_7 + \frac{1}{2}) \mathbf{a}_3$	=	$ax_7 \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - cz_7 \hat{\mathbf{z}}$	(16j)	S I

$$\mathbf{B}_{27} = \begin{pmatrix} (-y_7 + z_7 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_7 + z_7) \mathbf{a}_2 + (x_7 - y_7 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ax_7 \hat{\mathbf{x}} - b \left( y_7 - \frac{1}{2} \right) \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} \quad (16j) \quad \text{S I}$$

$$\mathbf{B}_{28} = \begin{pmatrix} (y_7 + z_7) \mathbf{a}_1 - (x_7 - z_7) \mathbf{a}_2 - \\ (x_7 - y_7) \mathbf{a}_3 \end{pmatrix} = -ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} \quad (16j) \quad \text{S I}$$

## References

- [1] J. Beck and S. Hedderich, *Synthesis and Crystal Structure of Hg<sub>3</sub>S<sub>2</sub>I<sub>2</sub> and Hg<sub>3</sub>Se<sub>2</sub>I<sub>2</sub>, New Members of the Hg<sub>3</sub>E<sub>2</sub>X<sub>2</sub> Family*, Journal of Solid State Chemistry **151**, 73–76 (2000), doi:10.1006/jssc.1999.8624.