

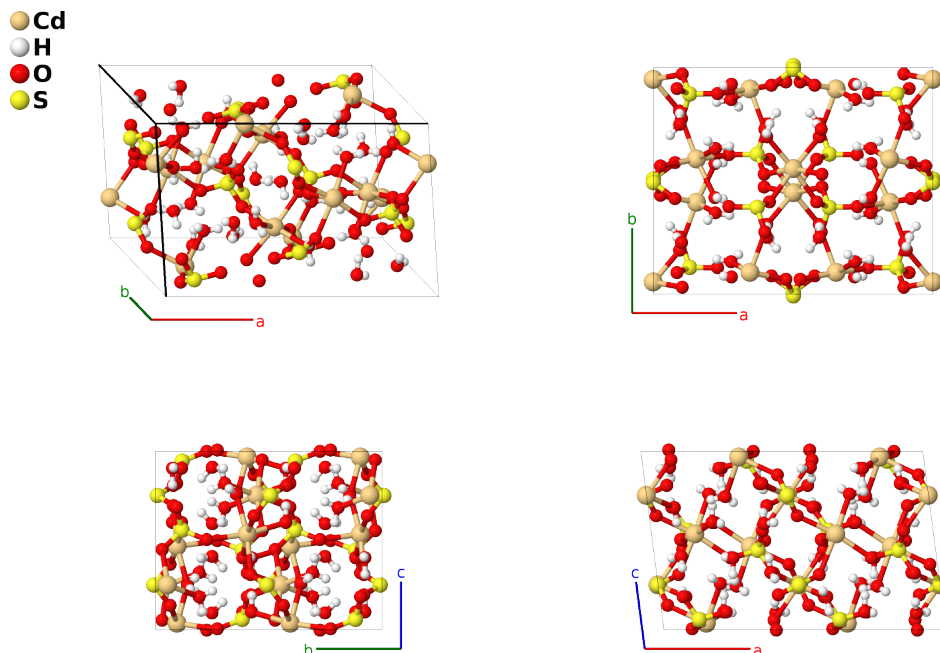
# (CdSO<sub>4</sub>)<sub>3</sub>·8H<sub>2</sub>O (*H*4<sub>20</sub>) Structure: A3B16C20D3\_mC168\_15\_ef\_8f\_10f\_ef-001

This structure originally had the label A3B16C20D3\_mC168\_15\_ef\_8f\_10f\_ef. Calls to that address will be redirected here.

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<https://aflow.org/p/VXAE>

[https://aflow.org/p/A3B16C20D3\\_mC168\\_15\\_ef\\_8f\\_10f\\_ef-001](https://aflow.org/p/A3B16C20D3_mC168_15_ef_8f_10f_ef-001)



Prototype	Cd <sub>3</sub> H <sub>16</sub> O <sub>20</sub> S <sub>3</sub>
AFLOW prototype label	A3B16C20D3_mC168_15_ef_8f_10f_ef-001
<i>Strukturbericht</i> designation	<i>H</i> 4 <sub>20</sub>
ICSD	24400
Pearson symbol	mC168
Space group number	15
Space group symbol	<i>C</i> 2/ <i>c</i>
AFLOW prototype command	<pre>aflow --proto=A3B16C20D3_mC168_15_ef_8f_10f_ef-001 --params=a, b/a, c/a, β, y1, y2, x3, y3, z3, x4, y4, z4, x5, y5, z5, x6, y6, z6, x7, y7, z7, x8, y8, z8, x9, y9, z9, x10, y10, z10, x11, y11, z11, x12, y12, z12, x13, y13, z13, x14, y14, z14, x15, y15, z15, x16, y16, z16, x17, y17, z17, x18, y18, z18, x19, y19, z19, x20, y20, z20, x21, y21, z21, x22, y22, z22</pre>

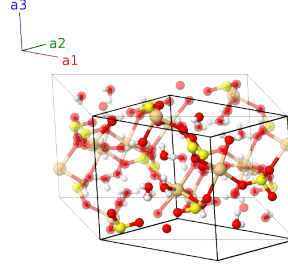
- (Lipson, 1938) originally found this structure and (Gottfried, 1938) gave it the *Strukturbericht* designation *H*4<sub>20</sub>. Later (Caminiti, 1981) located the hydrogen atoms. As this does not change the rest of the structure we use their results.

- Some of the H-O distances appear to be very small. For example, the O-VIII – H-III distance is only 0.43Å. We have checked our inputs compared to (Caminiti, 1981) and found no error. Unfortunately they do not provide H-O distances for comparison.

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### Base-centered Monoclinic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}b \hat{\mathbf{y}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}\end{aligned}$$




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### Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= -y_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}c \cos \beta \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + \frac{1}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	Cd I
$\mathbf{B}_2$	$= y_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}c \cos \beta \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} + \frac{3}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	Cd I
$\mathbf{B}_3$	$= -y_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}c \cos \beta \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + \frac{1}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	S I
$\mathbf{B}_4$	$= y_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}c \cos \beta \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + \frac{3}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	S I
$\mathbf{B}_5$	$= (x_3 - y_3) \mathbf{a}_1 + (x_3 + y_3) \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(8f)	Cd II
$\mathbf{B}_6$	$= -(x_3 + y_3) \mathbf{a}_1 - (x_3 - y_3) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	Cd II
$\mathbf{B}_7$	$= -(x_3 - y_3) \mathbf{a}_1 - (x_3 + y_3) \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(8f)	Cd II
$\mathbf{B}_8$	$= (x_3 + y_3) \mathbf{a}_1 + (x_3 - y_3) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	Cd II
$\mathbf{B}_9$	$= (x_4 - y_4) \mathbf{a}_1 + (x_4 + y_4) \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(8f)	H I
$\mathbf{B}_{10}$	$= -(x_4 + y_4) \mathbf{a}_1 - (x_4 - y_4) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	H I
$\mathbf{B}_{11}$	$= -(x_4 - y_4) \mathbf{a}_1 - (x_4 + y_4) \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(8f)	H I
$\mathbf{B}_{12}$	$= (x_4 + y_4) \mathbf{a}_1 + (x_4 - y_4) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	H I
$\mathbf{B}_{13}$	$= (x_5 - y_5) \mathbf{a}_1 + (x_5 + y_5) \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(8f)	H II
$\mathbf{B}_{14}$	$= -(x_5 + y_5) \mathbf{a}_1 - (x_5 - y_5) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	H II
$\mathbf{B}_{15}$	$= -(x_5 - y_5) \mathbf{a}_1 - (x_5 + y_5) \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(8f)	H II
$\mathbf{B}_{16}$	$= (x_5 + y_5) \mathbf{a}_1 + (x_5 - y_5) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	H II
$\mathbf{B}_{17}$	$= (x_6 - y_6) \mathbf{a}_1 + (x_6 + y_6) \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(8f)	H III

$$\begin{aligned}
\mathbf{B}_{18} &= -(x_6 + y_6) \mathbf{a}_1 - (x_6 - y_6) \mathbf{a}_2 - (z_6 - \frac{1}{2}) \mathbf{a}_3 = -(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H III} \\
\mathbf{B}_{19} &= -(x_6 - y_6) \mathbf{a}_1 - (x_6 + y_6) \mathbf{a}_2 - z_6 \mathbf{a}_3 = -(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}} & (8f) & \text{H III} \\
\mathbf{B}_{20} &= (x_6 + y_6) \mathbf{a}_1 + (x_6 - y_6) \mathbf{a}_2 + (z_6 + \frac{1}{2}) \mathbf{a}_3 = (ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H III} \\
\mathbf{B}_{21} &= (x_7 - y_7) \mathbf{a}_1 + (x_7 + y_7) \mathbf{a}_2 + z_7 \mathbf{a}_3 = (ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}} & (8f) & \text{H IV} \\
\mathbf{B}_{22} &= -(x_7 + y_7) \mathbf{a}_1 - (x_7 - y_7) \mathbf{a}_2 - (z_7 - \frac{1}{2}) \mathbf{a}_3 = -(ax_7 + c(z_7 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H IV} \\
\mathbf{B}_{23} &= -(x_7 - y_7) \mathbf{a}_1 - (x_7 + y_7) \mathbf{a}_2 - z_7 \mathbf{a}_3 = -(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}} & (8f) & \text{H IV} \\
\mathbf{B}_{24} &= (x_7 + y_7) \mathbf{a}_1 + (x_7 - y_7) \mathbf{a}_2 + (z_7 + \frac{1}{2}) \mathbf{a}_3 = (ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H IV} \\
\mathbf{B}_{25} &= (x_8 - y_8) \mathbf{a}_1 + (x_8 + y_8) \mathbf{a}_2 + z_8 \mathbf{a}_3 = (ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}} & (8f) & \text{H V} \\
\mathbf{B}_{26} &= -(x_8 + y_8) \mathbf{a}_1 - (x_8 - y_8) \mathbf{a}_2 - (z_8 - \frac{1}{2}) \mathbf{a}_3 = -(ax_8 + c(z_8 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H V} \\
\mathbf{B}_{27} &= -(x_8 - y_8) \mathbf{a}_1 - (x_8 + y_8) \mathbf{a}_2 - z_8 \mathbf{a}_3 = -(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}} & (8f) & \text{H V} \\
\mathbf{B}_{28} &= (x_8 + y_8) \mathbf{a}_1 + (x_8 - y_8) \mathbf{a}_2 + (z_8 + \frac{1}{2}) \mathbf{a}_3 = (ax_8 + c(z_8 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H V} \\
\mathbf{B}_{29} &= (x_9 - y_9) \mathbf{a}_1 + (x_9 + y_9) \mathbf{a}_2 + z_9 \mathbf{a}_3 = (ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VI} \\
\mathbf{B}_{30} &= -(x_9 + y_9) \mathbf{a}_1 - (x_9 - y_9) \mathbf{a}_2 - (z_9 - \frac{1}{2}) \mathbf{a}_3 = -(ax_9 + c(z_9 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} - c(z_9 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VI} \\
\mathbf{B}_{31} &= -(x_9 - y_9) \mathbf{a}_1 - (x_9 + y_9) \mathbf{a}_2 - z_9 \mathbf{a}_3 = -(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VI} \\
\mathbf{B}_{32} &= (x_9 + y_9) \mathbf{a}_1 + (x_9 - y_9) \mathbf{a}_2 + (z_9 + \frac{1}{2}) \mathbf{a}_3 = (ax_9 + c(z_9 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} + c(z_9 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VI} \\
\mathbf{B}_{33} &= (x_{10} - y_{10}) \mathbf{a}_1 + (x_{10} + y_{10}) \mathbf{a}_2 + z_{10} \mathbf{a}_3 = (ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VII} \\
\mathbf{B}_{34} &= -(x_{10} + y_{10}) \mathbf{a}_1 - (x_{10} - y_{10}) \mathbf{a}_2 - (z_{10} - \frac{1}{2}) \mathbf{a}_3 = -(ax_{10} + c(z_{10} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} - c(z_{10} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VII} \\
\mathbf{B}_{35} &= -(x_{10} - y_{10}) \mathbf{a}_1 - (x_{10} + y_{10}) \mathbf{a}_2 - z_{10} \mathbf{a}_3 = -(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} - cz_{10} \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VII} \\
\mathbf{B}_{36} &= (x_{10} + y_{10}) \mathbf{a}_1 + (x_{10} - y_{10}) \mathbf{a}_2 + (z_{10} + \frac{1}{2}) \mathbf{a}_3 = (ax_{10} + c(z_{10} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} + c(z_{10} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VII} \\
\mathbf{B}_{37} &= (x_{11} - y_{11}) \mathbf{a}_1 + (x_{11} + y_{11}) \mathbf{a}_2 + z_{11} \mathbf{a}_3 = (ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} + cz_{11} \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VIII} \\
\mathbf{B}_{38} &= -(x_{11} + y_{11}) \mathbf{a}_1 - (x_{11} - y_{11}) \mathbf{a}_2 - (z_{11} - \frac{1}{2}) \mathbf{a}_3 = -(ax_{11} + c(z_{11} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} - c(z_{11} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VIII} \\
\mathbf{B}_{39} &= -(x_{11} - y_{11}) \mathbf{a}_1 - (x_{11} + y_{11}) \mathbf{a}_2 - z_{11} \mathbf{a}_3 = -(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} - cz_{11} \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VIII} \\
\mathbf{B}_{40} &= (x_{11} + y_{11}) \mathbf{a}_1 + (x_{11} - y_{11}) \mathbf{a}_2 + (z_{11} + \frac{1}{2}) \mathbf{a}_3 = (ax_{11} + c(z_{11} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} + c(z_{11} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{H VIII}
\end{aligned}$$



$$\begin{aligned}
\mathbf{B}_{64} &= (x_{17} + y_{17}) \mathbf{a}_1 + (x_{17} - y_{17}) \mathbf{a}_2 + (z_{17} + \frac{1}{2}) \mathbf{a}_3 &= (ax_{17} + c(z_{17} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{17} \hat{\mathbf{y}} + c(z_{17} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VI} \\
\mathbf{B}_{65} &= (x_{18} - y_{18}) \mathbf{a}_1 + (x_{18} + y_{18}) \mathbf{a}_2 + z_{18} \mathbf{a}_3 &= (ax_{18} + cz_{18} \cos \beta) \hat{\mathbf{x}} + by_{18} \hat{\mathbf{y}} + cz_{18} \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VII} \\
\mathbf{B}_{66} &= -(x_{18} + y_{18}) \mathbf{a}_1 - (x_{18} - y_{18}) \mathbf{a}_2 - (z_{18} - \frac{1}{2}) \mathbf{a}_3 &= -(ax_{18} + c(z_{18} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{18} \hat{\mathbf{y}} - c(z_{18} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VII} \\
\mathbf{B}_{67} &= -(x_{18} - y_{18}) \mathbf{a}_1 - (x_{18} + y_{18}) \mathbf{a}_2 - z_{18} \mathbf{a}_3 &= -(ax_{18} + cz_{18} \cos \beta) \hat{\mathbf{x}} - by_{18} \hat{\mathbf{y}} - cz_{18} \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VII} \\
\mathbf{B}_{68} &= (x_{18} + y_{18}) \mathbf{a}_1 + (x_{18} - y_{18}) \mathbf{a}_2 + (z_{18} + \frac{1}{2}) \mathbf{a}_3 &= (ax_{18} + c(z_{18} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{18} \hat{\mathbf{y}} + c(z_{18} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VII} \\
\mathbf{B}_{69} &= (x_{19} - y_{19}) \mathbf{a}_1 + (x_{19} + y_{19}) \mathbf{a}_2 + z_{19} \mathbf{a}_3 &= (ax_{19} + cz_{19} \cos \beta) \hat{\mathbf{x}} + by_{19} \hat{\mathbf{y}} + cz_{19} \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VIII} \\
\mathbf{B}_{70} &= -(x_{19} + y_{19}) \mathbf{a}_1 - (x_{19} - y_{19}) \mathbf{a}_2 - (z_{19} - \frac{1}{2}) \mathbf{a}_3 &= -(ax_{19} + c(z_{19} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{19} \hat{\mathbf{y}} - c(z_{19} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VIII} \\
\mathbf{B}_{71} &= -(x_{19} - y_{19}) \mathbf{a}_1 - (x_{19} + y_{19}) \mathbf{a}_2 - z_{19} \mathbf{a}_3 &= -(ax_{19} + cz_{19} \cos \beta) \hat{\mathbf{x}} - by_{19} \hat{\mathbf{y}} - cz_{19} \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VIII} \\
\mathbf{B}_{72} &= (x_{19} + y_{19}) \mathbf{a}_1 + (x_{19} - y_{19}) \mathbf{a}_2 + (z_{19} + \frac{1}{2}) \mathbf{a}_3 &= (ax_{19} + c(z_{19} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{19} \hat{\mathbf{y}} + c(z_{19} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O VIII} \\
\mathbf{B}_{73} &= (x_{20} - y_{20}) \mathbf{a}_1 + (x_{20} + y_{20}) \mathbf{a}_2 + z_{20} \mathbf{a}_3 &= (ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} + by_{20} \hat{\mathbf{y}} + cz_{20} \sin \beta \hat{\mathbf{z}} &(8f) & \text{O IX} \\
\mathbf{B}_{74} &= -(x_{20} + y_{20}) \mathbf{a}_1 - (x_{20} - y_{20}) \mathbf{a}_2 - (z_{20} - \frac{1}{2}) \mathbf{a}_3 &= -(ax_{20} + c(z_{20} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{20} \hat{\mathbf{y}} - c(z_{20} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O IX} \\
\mathbf{B}_{75} &= -(x_{20} - y_{20}) \mathbf{a}_1 - (x_{20} + y_{20}) \mathbf{a}_2 - z_{20} \mathbf{a}_3 &= -(ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} - by_{20} \hat{\mathbf{y}} - cz_{20} \sin \beta \hat{\mathbf{z}} &(8f) & \text{O IX} \\
\mathbf{B}_{76} &= (x_{20} + y_{20}) \mathbf{a}_1 + (x_{20} - y_{20}) \mathbf{a}_2 + (z_{20} + \frac{1}{2}) \mathbf{a}_3 &= (ax_{20} + c(z_{20} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{20} \hat{\mathbf{y}} + c(z_{20} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O IX} \\
\mathbf{B}_{77} &= (x_{21} - y_{21}) \mathbf{a}_1 + (x_{21} + y_{21}) \mathbf{a}_2 + z_{21} \mathbf{a}_3 &= (ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} + by_{21} \hat{\mathbf{y}} + cz_{21} \sin \beta \hat{\mathbf{z}} &(8f) & \text{O X} \\
\mathbf{B}_{78} &= -(x_{21} + y_{21}) \mathbf{a}_1 - (x_{21} - y_{21}) \mathbf{a}_2 - (z_{21} - \frac{1}{2}) \mathbf{a}_3 &= -(ax_{21} + c(z_{21} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{21} \hat{\mathbf{y}} - c(z_{21} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O X} \\
\mathbf{B}_{79} &= -(x_{21} - y_{21}) \mathbf{a}_1 - (x_{21} + y_{21}) \mathbf{a}_2 - z_{21} \mathbf{a}_3 &= -(ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} - by_{21} \hat{\mathbf{y}} - cz_{21} \sin \beta \hat{\mathbf{z}} &(8f) & \text{O X} \\
\mathbf{B}_{80} &= (x_{21} + y_{21}) \mathbf{a}_1 + (x_{21} - y_{21}) \mathbf{a}_2 + (z_{21} + \frac{1}{2}) \mathbf{a}_3 &= (ax_{21} + c(z_{21} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{21} \hat{\mathbf{y}} + c(z_{21} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{O X} \\
\mathbf{B}_{81} &= (x_{22} - y_{22}) \mathbf{a}_1 + (x_{22} + y_{22}) \mathbf{a}_2 + z_{22} \mathbf{a}_3 &= (ax_{22} + cz_{22} \cos \beta) \hat{\mathbf{x}} + by_{22} \hat{\mathbf{y}} + cz_{22} \sin \beta \hat{\mathbf{z}} &(8f) & \text{S II} \\
\mathbf{B}_{82} &= -(x_{22} + y_{22}) \mathbf{a}_1 - (x_{22} - y_{22}) \mathbf{a}_2 - (z_{22} - \frac{1}{2}) \mathbf{a}_3 &= -(ax_{22} + c(z_{22} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{22} \hat{\mathbf{y}} - c(z_{22} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{S II} \\
\mathbf{B}_{83} &= -(x_{22} - y_{22}) \mathbf{a}_1 - (x_{22} + y_{22}) \mathbf{a}_2 - z_{22} \mathbf{a}_3 &= -(ax_{22} + cz_{22} \cos \beta) \hat{\mathbf{x}} - by_{22} \hat{\mathbf{y}} - cz_{22} \sin \beta \hat{\mathbf{z}} &(8f) & \text{S II} \\
\mathbf{B}_{84} &= (x_{22} + y_{22}) \mathbf{a}_1 + (x_{22} - y_{22}) \mathbf{a}_2 + (z_{22} + \frac{1}{2}) \mathbf{a}_3 &= (ax_{22} + c(z_{22} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{22} \hat{\mathbf{y}} + c(z_{22} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} &(8f) & \text{S II}
\end{aligned}$$

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