

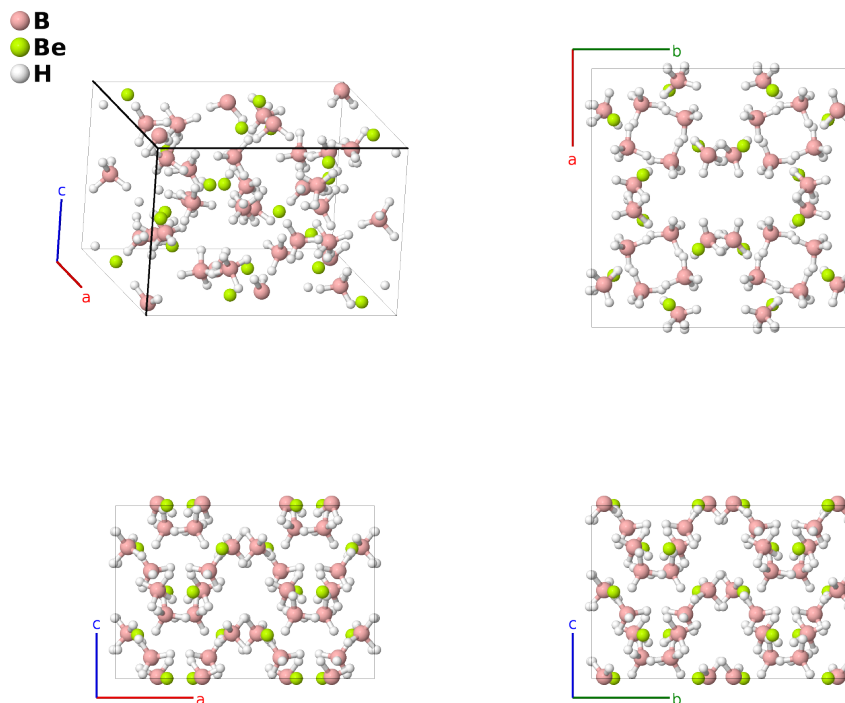
# Be[BH<sub>4</sub>]<sub>2</sub> Structure: A2BC8\_tI176\_110\_2b\_b\_8b-001

This structure originally had the label **A2BC8\_tI176\_110\_2b\_b\_8b**. Calls to that address will be redirected here.

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<https://aflow.org/p/29CG>

[https://aflow.org/p/A2BC8\\_tI176\\_110\\_2b\\_b\\_8b-001](https://aflow.org/p/A2BC8_tI176_110_2b_b_8b-001)



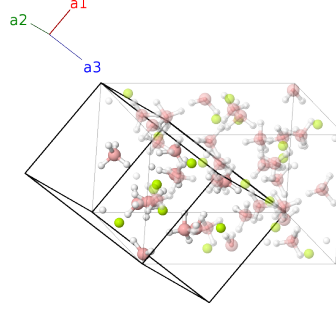
<b>Prototype</b>	B <sub>2</sub> BeH <sub>8</sub>
<b>AFLOW prototype label</b>	A2BC8_tI176_110_2b_b_8b-001
<b>ICSD</b>	10315
<b>Pearson symbol</b>	tI176
<b>Space group number</b>	110
<b>Space group symbol</b>	<i>I</i> 4 <sub>1</sub> <i>cd</i>
<b>AFLOW prototype command</b>	<pre>aflow --proto=A2BC8_tI176_110_2b_b_8b-001       --params=a, c/a, x<sub>1</sub>, y<sub>1</sub>, z<sub>1</sub>, x<sub>2</sub>, y<sub>2</sub>, z<sub>2</sub>, x<sub>3</sub>, y<sub>3</sub>, z<sub>3</sub>, x<sub>4</sub>, y<sub>4</sub>, z<sub>4</sub>, x<sub>5</sub>, y<sub>5</sub>, z<sub>5</sub>, x<sub>6</sub>, y<sub>6</sub>, z<sub>6</sub>, x<sub>7</sub>, y<sub>7</sub>, z<sub>7</sub>,       x<sub>8</sub>, y<sub>8</sub>, z<sub>8</sub>, x<sub>9</sub>, y<sub>9</sub>, z<sub>9</sub>, x<sub>10</sub>, y<sub>10</sub>, z<sub>10</sub>, x<sub>11</sub>, y<sub>11</sub>, z<sub>11</sub></pre>

- Space group *I*4<sub>1</sub>*cd* #110 allows an arbitrary placement of the *z*-axis origin, and we put a beryllium atom there by setting  $z_3 = 0$ .

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## Body-centered Tetragonal primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= -\frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}a \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}a \hat{\mathbf{y}} - \frac{1}{2}c \hat{\mathbf{z}}\end{aligned}$$




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## Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$(y_1 + z_1) \mathbf{a}_1 + (x_1 + z_1) \mathbf{a}_2 + (x_1 + y_1) \mathbf{a}_3$	=	$ax_1 \hat{\mathbf{x}} + ay_1 \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(16b)	B I
$\mathbf{B}_2$	$-(y_1 - z_1) \mathbf{a}_1 - (x_1 - z_1) \mathbf{a}_2 - (x_1 + y_1) \mathbf{a}_3$	=	$-ax_1 \hat{\mathbf{x}} - ay_1 \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(16b)	B I
$\mathbf{B}_3$	$(x_1 + z_1 + \frac{3}{4}) \mathbf{a}_1 + (-y_1 + z_1 + \frac{1}{4}) \mathbf{a}_2 + (x_1 - y_1 + \frac{1}{2}) \mathbf{a}_3$	=	$-ay_1 \hat{\mathbf{x}} + a(x_1 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{4}) \hat{\mathbf{z}}$	(16b)	B I
$\mathbf{B}_4$	$(-x_1 + z_1 + \frac{3}{4}) \mathbf{a}_1 + (y_1 + z_1 + \frac{1}{4}) \mathbf{a}_2 + (-x_1 + y_1 + \frac{1}{2}) \mathbf{a}_3$	=	$ay_1 \hat{\mathbf{x}} - a(x_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{4}) \hat{\mathbf{z}}$	(16b)	B I
$\mathbf{B}_5$	$(-y_1 + z_1 + \frac{1}{2}) \mathbf{a}_1 + (x_1 + z_1 + \frac{1}{2}) \mathbf{a}_2 + (x_1 - y_1) \mathbf{a}_3$	=	$ax_1 \hat{\mathbf{x}} - ay_1 \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \hat{\mathbf{z}}$	(16b)	B I
$\mathbf{B}_6$	$(y_1 + z_1 + \frac{1}{2}) \mathbf{a}_1 + (-x_1 + z_1 + \frac{1}{2}) \mathbf{a}_2 - (x_1 - y_1) \mathbf{a}_3$	=	$-ax_1 \hat{\mathbf{x}} + ay_1 \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \hat{\mathbf{z}}$	(16b)	B I
$\mathbf{B}_7$	$(-x_1 + z_1 + \frac{1}{4}) \mathbf{a}_1 + (-y_1 + z_1 + \frac{3}{4}) \mathbf{a}_2 - (x_1 + y_1 - \frac{1}{2}) \mathbf{a}_3$	=	$-a(y_1 - \frac{1}{2}) \hat{\mathbf{x}} - ax_1 \hat{\mathbf{y}} + c(z_1 + \frac{1}{4}) \hat{\mathbf{z}}$	(16b)	B I
$\mathbf{B}_8$	$(x_1 + z_1 + \frac{1}{4}) \mathbf{a}_1 + (y_1 + z_1 + \frac{3}{4}) \mathbf{a}_2 + (x_1 + y_1 + \frac{1}{2}) \mathbf{a}_3$	=	$a(y_1 + \frac{1}{2}) \hat{\mathbf{x}} + ax_1 \hat{\mathbf{y}} + c(z_1 + \frac{1}{4}) \hat{\mathbf{z}}$	(16b)	B I
$\mathbf{B}_9$	$(y_2 + z_2) \mathbf{a}_1 + (x_2 + z_2) \mathbf{a}_2 + (x_2 + y_2) \mathbf{a}_3$	=	$ax_2 \hat{\mathbf{x}} + ay_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(16b)	B II
$\mathbf{B}_{10}$	$-(y_2 - z_2) \mathbf{a}_1 - (x_2 - z_2) \mathbf{a}_2 - (x_2 + y_2) \mathbf{a}_3$	=	$-ax_2 \hat{\mathbf{x}} - ay_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(16b)	B II
$\mathbf{B}_{11}$	$(x_2 + z_2 + \frac{3}{4}) \mathbf{a}_1 + (-y_2 + z_2 + \frac{1}{4}) \mathbf{a}_2 + (x_2 - y_2 + \frac{1}{2}) \mathbf{a}_3$	=	$-ay_2 \hat{\mathbf{x}} + a(x_2 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(16b)	B II
$\mathbf{B}_{12}$	$(-x_2 + z_2 + \frac{3}{4}) \mathbf{a}_1 + (y_2 + z_2 + \frac{1}{4}) \mathbf{a}_2 + (-x_2 + y_2 + \frac{1}{2}) \mathbf{a}_3$	=	$ay_2 \hat{\mathbf{x}} - a(x_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{4}) \hat{\mathbf{z}}$	(16b)	B II
$\mathbf{B}_{13}$	$(-y_2 + z_2 + \frac{1}{2}) \mathbf{a}_1 + (x_2 + z_2 + \frac{1}{2}) \mathbf{a}_2 + (x_2 - y_2) \mathbf{a}_3$	=	$ax_2 \hat{\mathbf{x}} - ay_2 \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \hat{\mathbf{z}}$	(16b)	B II

$$\begin{aligned}
\mathbf{B}_{14} &= \begin{pmatrix} (y_2 + z_2 + \frac{1}{2}) \mathbf{a}_1 + \\ (-x_2 + z_2 + \frac{1}{2}) \mathbf{a}_2 - (x_2 - y_2) \mathbf{a}_3 \end{pmatrix} = -ax_2 \hat{\mathbf{x}} + ay_2 \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{B II} \\
\mathbf{B}_{15} &= \begin{pmatrix} (-x_2 + z_2 + \frac{1}{4}) \mathbf{a}_1 + \\ (-y_2 + z_2 + \frac{3}{4}) \mathbf{a}_2 - \\ (x_2 + y_2 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(y_2 - \frac{1}{2}) \hat{\mathbf{x}} - ax_2 \hat{\mathbf{y}} + c(z_2 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{B II} \\
\mathbf{B}_{16} &= \begin{pmatrix} (x_2 + z_2 + \frac{1}{4}) \mathbf{a}_1 + \\ (y_2 + z_2 + \frac{3}{4}) \mathbf{a}_2 + \\ (x_2 + y_2 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(y_2 + \frac{1}{2}) \hat{\mathbf{x}} + ax_2 \hat{\mathbf{y}} + c(z_2 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{B II} \\
\mathbf{B}_{17} &= \begin{pmatrix} (y_3 + z_3) \mathbf{a}_1 + (x_3 + z_3) \mathbf{a}_2 + \\ (x_3 + y_3) \mathbf{a}_3 \end{pmatrix} = ax_3 \hat{\mathbf{x}} + ay_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}} & (16b) & \text{Be I} \\
\mathbf{B}_{18} &= \begin{pmatrix} -(y_3 - z_3) \mathbf{a}_1 - (x_3 - z_3) \mathbf{a}_2 - \\ (x_3 + y_3) \mathbf{a}_3 \end{pmatrix} = -ax_3 \hat{\mathbf{x}} - ay_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}} & (16b) & \text{Be I} \\
\mathbf{B}_{19} &= \begin{pmatrix} (x_3 + z_3 + \frac{3}{4}) \mathbf{a}_1 + \\ (-y_3 + z_3 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_3 - y_3 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ay_3 \hat{\mathbf{x}} + a(x_3 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Be I} \\
\mathbf{B}_{20} &= \begin{pmatrix} (-x_3 + z_3 + \frac{3}{4}) \mathbf{a}_1 + \\ (y_3 + z_3 + \frac{1}{4}) \mathbf{a}_2 + \\ (-x_3 + y_3 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ay_3 \hat{\mathbf{x}} - a(x_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Be I} \\
\mathbf{B}_{21} &= \begin{pmatrix} (-y_3 + z_3 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_3 + z_3 + \frac{1}{2}) \mathbf{a}_2 + (x_3 - y_3) \mathbf{a}_3 \end{pmatrix} = ax_3 \hat{\mathbf{x}} - ay_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{Be I} \\
\mathbf{B}_{22} &= \begin{pmatrix} (y_3 + z_3 + \frac{1}{2}) \mathbf{a}_1 + \\ (-x_3 + z_3 + \frac{1}{2}) \mathbf{a}_2 - (x_3 - y_3) \mathbf{a}_3 \end{pmatrix} = -ax_3 \hat{\mathbf{x}} + ay_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{Be I} \\
\mathbf{B}_{23} &= \begin{pmatrix} (-x_3 + z_3 + \frac{1}{4}) \mathbf{a}_1 + \\ (-y_3 + z_3 + \frac{3}{4}) \mathbf{a}_2 - \\ (x_3 + y_3 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(y_3 - \frac{1}{2}) \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Be I} \\
\mathbf{B}_{24} &= \begin{pmatrix} (x_3 + z_3 + \frac{1}{4}) \mathbf{a}_1 + \\ (y_3 + z_3 + \frac{3}{4}) \mathbf{a}_2 + \\ (x_3 + y_3 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(y_3 + \frac{1}{2}) \hat{\mathbf{x}} + ax_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Be I} \\
\mathbf{B}_{25} &= \begin{pmatrix} (y_4 + z_4) \mathbf{a}_1 + (x_4 + z_4) \mathbf{a}_2 + \\ (x_4 + y_4) \mathbf{a}_3 \end{pmatrix} = ax_4 \hat{\mathbf{x}} + ay_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}} & (16b) & \text{H I} \\
\mathbf{B}_{26} &= \begin{pmatrix} -(y_4 - z_4) \mathbf{a}_1 - (x_4 - z_4) \mathbf{a}_2 - \\ (x_4 + y_4) \mathbf{a}_3 \end{pmatrix} = -ax_4 \hat{\mathbf{x}} - ay_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}} & (16b) & \text{H I} \\
\mathbf{B}_{27} &= \begin{pmatrix} (x_4 + z_4 + \frac{3}{4}) \mathbf{a}_1 + \\ (-y_4 + z_4 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_4 - y_4 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ay_4 \hat{\mathbf{x}} + a(x_4 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H I} \\
\mathbf{B}_{28} &= \begin{pmatrix} (-x_4 + z_4 + \frac{3}{4}) \mathbf{a}_1 + \\ (y_4 + z_4 + \frac{1}{4}) \mathbf{a}_2 + \\ (-x_4 + y_4 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ay_4 \hat{\mathbf{x}} - a(x_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H I} \\
\mathbf{B}_{29} &= \begin{pmatrix} (-y_4 + z_4 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_4 + z_4 + \frac{1}{2}) \mathbf{a}_2 + (x_4 - y_4) \mathbf{a}_3 \end{pmatrix} = ax_4 \hat{\mathbf{x}} - ay_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{H I} \\
\mathbf{B}_{30} &= \begin{pmatrix} (y_4 + z_4 + \frac{1}{2}) \mathbf{a}_1 + \\ (-x_4 + z_4 + \frac{1}{2}) \mathbf{a}_2 - (x_4 - y_4) \mathbf{a}_3 \end{pmatrix} = -ax_4 \hat{\mathbf{x}} + ay_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{H I} \\
\mathbf{B}_{31} &= \begin{pmatrix} (-x_4 + z_4 + \frac{1}{4}) \mathbf{a}_1 + \\ (-y_4 + z_4 + \frac{3}{4}) \mathbf{a}_2 - \\ (x_4 + y_4 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(y_4 - \frac{1}{2}) \hat{\mathbf{x}} - ax_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H I} \\
\mathbf{B}_{32} &= \begin{pmatrix} (x_4 + z_4 + \frac{1}{4}) \mathbf{a}_1 + \\ (y_4 + z_4 + \frac{3}{4}) \mathbf{a}_2 + \\ (x_4 + y_4 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(y_4 + \frac{1}{2}) \hat{\mathbf{x}} + ax_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H I}
\end{aligned}$$

$$\begin{aligned}
\mathbf{B}_{33} &= \begin{pmatrix} (y_5 + z_5) \mathbf{a}_1 + (x_5 + z_5) \mathbf{a}_2 + \\ (x_5 + y_5) \mathbf{a}_3 \end{pmatrix} = ax_5 \hat{\mathbf{x}} + ay_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}} & (16b) & \text{H II} \\
\mathbf{B}_{34} &= \begin{pmatrix} -(y_5 - z_5) \mathbf{a}_1 - (x_5 - z_5) \mathbf{a}_2 - \\ (x_5 + y_5) \mathbf{a}_3 \end{pmatrix} = -ax_5 \hat{\mathbf{x}} - ay_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}} & (16b) & \text{H II} \\
\mathbf{B}_{35} &= \begin{pmatrix} (x_5 + z_5 + \frac{3}{4}) \mathbf{a}_1 + \\ (-y_5 + z_5 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_5 - y_5 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ay_5 \hat{\mathbf{x}} + a(x_5 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H II} \\
\mathbf{B}_{36} &= \begin{pmatrix} (-x_5 + z_5 + \frac{3}{4}) \mathbf{a}_1 + \\ (y_5 + z_5 + \frac{1}{4}) \mathbf{a}_2 + \\ (-x_5 + y_5 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ay_5 \hat{\mathbf{x}} - a(x_5 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H II} \\
\mathbf{B}_{37} &= \begin{pmatrix} (-y_5 + z_5 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_5 + z_5 + \frac{1}{2}) \mathbf{a}_2 + (x_5 - y_5) \mathbf{a}_3 \end{pmatrix} = ax_5 \hat{\mathbf{x}} - ay_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{H II} \\
\mathbf{B}_{38} &= \begin{pmatrix} (y_5 + z_5 + \frac{1}{2}) \mathbf{a}_1 + \\ (-x_5 + z_5 + \frac{1}{2}) \mathbf{a}_2 - (x_5 - y_5) \mathbf{a}_3 \end{pmatrix} = -ax_5 \hat{\mathbf{x}} + ay_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{H II} \\
\mathbf{B}_{39} &= \begin{pmatrix} (-x_5 + z_5 + \frac{1}{4}) \mathbf{a}_1 + \\ (-y_5 + z_5 + \frac{3}{4}) \mathbf{a}_2 - \\ (x_5 + y_5 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(y_5 - \frac{1}{2}) \hat{\mathbf{x}} - ax_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H II} \\
\mathbf{B}_{40} &= \begin{pmatrix} (x_5 + z_5 + \frac{1}{4}) \mathbf{a}_1 + \\ (y_5 + z_5 + \frac{3}{4}) \mathbf{a}_2 + \\ (x_5 + y_5 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(y_5 + \frac{1}{2}) \hat{\mathbf{x}} + ax_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H II} \\
\mathbf{B}_{41} &= \begin{pmatrix} (y_6 + z_6) \mathbf{a}_1 + (x_6 + z_6) \mathbf{a}_2 + \\ (x_6 + y_6) \mathbf{a}_3 \end{pmatrix} = ax_6 \hat{\mathbf{x}} + ay_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16b) & \text{H III} \\
\mathbf{B}_{42} &= \begin{pmatrix} -(y_6 - z_6) \mathbf{a}_1 - (x_6 - z_6) \mathbf{a}_2 - \\ (x_6 + y_6) \mathbf{a}_3 \end{pmatrix} = -ax_6 \hat{\mathbf{x}} - ay_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16b) & \text{H III} \\
\mathbf{B}_{43} &= \begin{pmatrix} (x_6 + z_6 + \frac{3}{4}) \mathbf{a}_1 + \\ (-y_6 + z_6 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_6 - y_6 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ay_6 \hat{\mathbf{x}} + a(x_6 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H III} \\
\mathbf{B}_{44} &= \begin{pmatrix} (-x_6 + z_6 + \frac{3}{4}) \mathbf{a}_1 + \\ (y_6 + z_6 + \frac{1}{4}) \mathbf{a}_2 + \\ (-x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = ay_6 \hat{\mathbf{x}} - a(x_6 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H III} \\
\mathbf{B}_{45} &= \begin{pmatrix} (-y_6 + z_6 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_6 + z_6 + \frac{1}{2}) \mathbf{a}_2 + (x_6 - y_6) \mathbf{a}_3 \end{pmatrix} = ax_6 \hat{\mathbf{x}} - ay_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{H III} \\
\mathbf{B}_{46} &= \begin{pmatrix} (y_6 + z_6 + \frac{1}{2}) \mathbf{a}_1 + \\ (-x_6 + z_6 + \frac{1}{2}) \mathbf{a}_2 - (x_6 - y_6) \mathbf{a}_3 \end{pmatrix} = -ax_6 \hat{\mathbf{x}} + ay_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \hat{\mathbf{z}} & (16b) & \text{H III} \\
\mathbf{B}_{47} &= \begin{pmatrix} (-x_6 + z_6 + \frac{1}{4}) \mathbf{a}_1 + \\ (-y_6 + z_6 + \frac{3}{4}) \mathbf{a}_2 - \\ (x_6 + y_6 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -a(y_6 - \frac{1}{2}) \hat{\mathbf{x}} - ax_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H III} \\
\mathbf{B}_{48} &= \begin{pmatrix} (x_6 + z_6 + \frac{1}{4}) \mathbf{a}_1 + \\ (y_6 + z_6 + \frac{3}{4}) \mathbf{a}_2 + \\ (x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a(y_6 + \frac{1}{2}) \hat{\mathbf{x}} + ax_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H III} \\
\mathbf{B}_{49} &= \begin{pmatrix} (y_7 + z_7) \mathbf{a}_1 + (x_7 + z_7) \mathbf{a}_2 + \\ (x_7 + y_7) \mathbf{a}_3 \end{pmatrix} = ax_7 \hat{\mathbf{x}} + ay_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16b) & \text{H IV} \\
\mathbf{B}_{50} &= \begin{pmatrix} -(y_7 - z_7) \mathbf{a}_1 - (x_7 - z_7) \mathbf{a}_2 - \\ (x_7 + y_7) \mathbf{a}_3 \end{pmatrix} = -ax_7 \hat{\mathbf{x}} - ay_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16b) & \text{H IV} \\
\mathbf{B}_{51} &= \begin{pmatrix} (x_7 + z_7 + \frac{3}{4}) \mathbf{a}_1 + \\ (-y_7 + z_7 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_7 - y_7 + \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = -ay_7 \hat{\mathbf{x}} + a(x_7 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_7 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{H IV}
\end{aligned}$$





$$\mathbf{B}_{88} = \begin{pmatrix} x_{11} + z_{11} + \frac{1}{4} \\ y_{11} + z_{11} + \frac{3}{4} \\ x_{11} + y_{11} + \frac{1}{2} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_{11} + z_{11} + \frac{1}{4} \\ y_{11} + z_{11} + \frac{3}{4} \\ x_{11} + y_{11} + \frac{1}{2} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_{11} + z_{11} + \frac{1}{4} \\ y_{11} + z_{11} + \frac{3}{4} \\ x_{11} + y_{11} + \frac{1}{2} \end{pmatrix} \mathbf{a}_3 = a \left( y_{11} + \frac{1}{2} \right) \hat{\mathbf{x}} + ax_{11} \hat{\mathbf{y}} + c \left( z_{11} + \frac{1}{4} \right) \hat{\mathbf{z}} \quad (16b) \quad \text{H VIII}$$

## References

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