

α -Li₃PS₄ Structure:

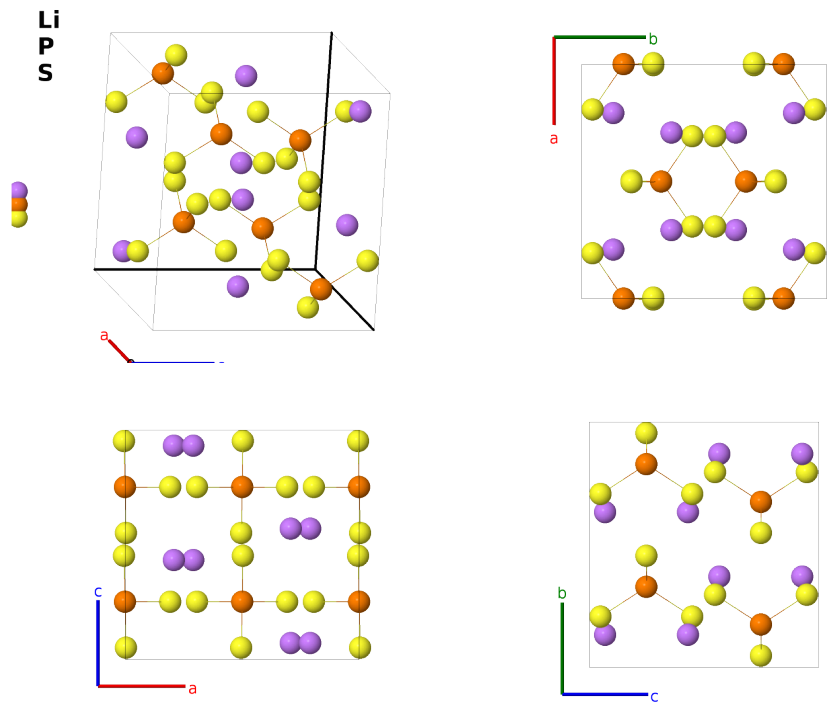
A2BC4_oP28_60_d_c_2d-002

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- D. Hicks, M. J. Mehl, M. Esters, C. Oses, O. Levy, G. L. W. Hart, C. Toher, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 3*, Comput. Mater. Sci. **199**, 110450 (2021), doi: 10.1016/j.commatsci.2021.110450.

<https://aflow.org/prototype-encyclopedia/7NXF>

https://aflow.org/prototype-encyclopedia/A2BC4_oP28_60_d_c_2d-002



Prototype	Li ₃ PS ₄
AFLOW prototype label	A2BC4_oP28_60_d_c_2d-002
Pearson symbol	oP28
Space group number	60
Space group symbol	<i>Pbcn</i>
AFLOW prototype command	<code>aflow --proto=A2BC4_oP28_60_d_c_2d-002</code> <code>--params=a, b/a, c/a, y₁, x₂, y₂, z₂, x₃, y₃, z₃, x₄, y₄, z₄</code>

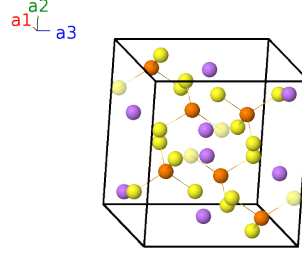
- Li₃PS₄ is known to exist in four forms (Homma, 2011):
 - γ -Li₃PS₄, the ground state, is stable below 573K in the enargite (*H2₅*) structure.
 - β -Li₃PS₄ is stable between 573 and 746K.
 - α -Li₃PS₄ (this structure) is stable above 746K.

– $\delta\text{-Li}_3\text{PS}_4$ is a predicted high-pressure phase.

- The astute reader will note that we have left 1/3 of the lithium atoms unaccounted for. (Homma, 2010) could not find the positions of these atoms. As Li_3PS_4 is a superionic conductor it is possible that these atoms move freely through the structure.
- Data for this structure was taken at 906K.
- CaB_2O_4 I and $\alpha\text{-Li}_3\text{PO}_4$ have the same AFLOW prototype label, A2BC4_oP28.60_d.c.2d. They are generated by the same symmetry operations with different sets of parameters (`--params`) specified in their corresponding CIF files.

Simple Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= y_1 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$by_1 \hat{\mathbf{y}} + \frac{1}{4} c \hat{\mathbf{z}}$	(4c)	P I
$\mathbf{B}_2$	$= \frac{1}{2} \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{1}{2} a \hat{\mathbf{x}} - b (y_1 - \frac{1}{2}) \hat{\mathbf{y}} + \frac{3}{4} c \hat{\mathbf{z}}$	(4c)	P I
$\mathbf{B}_3$	$= -y_1 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$-by_1 \hat{\mathbf{y}} + \frac{3}{4} c \hat{\mathbf{z}}$	(4c)	P I
$\mathbf{B}_4$	$= \frac{1}{2} \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{2} a \hat{\mathbf{x}} + b (y_1 + \frac{1}{2}) \hat{\mathbf{y}} + \frac{1}{4} c \hat{\mathbf{z}}$	(4c)	P I
$\mathbf{B}_5$	$= x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B}_6$	$= -(x_2 - \frac{1}{2}) \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a (x_2 - \frac{1}{2}) \hat{\mathbf{x}} - b (y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c (z_2 + \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B}_7$	$= -x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} - c (z_2 - \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B}_8$	$= (x_2 + \frac{1}{2}) \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$a (x_2 + \frac{1}{2}) \hat{\mathbf{x}} - b (y_2 - \frac{1}{2}) \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B}_9$	$= -x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B}_{10}$	$= (x_2 + \frac{1}{2}) \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$a (x_2 + \frac{1}{2}) \hat{\mathbf{x}} + b (y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c (z_2 - \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B}_{11}$	$= x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + c (z_2 + \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B}_{12}$	$= -(x_2 - \frac{1}{2}) \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$-a (x_2 - \frac{1}{2}) \hat{\mathbf{x}} + b (y_2 + \frac{1}{2}) \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(8d)	Li I
$\mathbf{B}_{13}$	$= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$ax_3 \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8d)	S I
$\mathbf{B}_{14}$	$= -(x_3 - \frac{1}{2}) \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$-a (x_3 - \frac{1}{2}) \hat{\mathbf{x}} - b (y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c (z_3 + \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	S I
$\mathbf{B}_{15}$	$= -x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} - c (z_3 - \frac{1}{2}) \hat{\mathbf{z}}$	(8d)	S I
$\mathbf{B}_{16}$	$= (x_3 + \frac{1}{2}) \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$a (x_3 + \frac{1}{2}) \hat{\mathbf{x}} - b (y_3 - \frac{1}{2}) \hat{\mathbf{y}} - cz_3 \hat{\mathbf{z}}$	(8d)	S I
$\mathbf{B}_{17}$	$= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-ax_3 \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \hat{\mathbf{z}}$	(8d)	S I

$$\begin{aligned}
\mathbf{B}_{18} &= \begin{pmatrix} (x_3 + \frac{1}{2}) \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - \\ (z_3 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a \left(x_3 + \frac{1}{2} \right) \hat{\mathbf{x}} + b \left(y_3 + \frac{1}{2} \right) \hat{\mathbf{y}} - c \left(z_3 - \frac{1}{2} \right) \hat{\mathbf{z}} & (8d) & \text{S I} \\
\mathbf{B}_{19} &= x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 + \left(z_3 + \frac{1}{2} \right) \mathbf{a}_3 = ax_3 \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + c \left(z_3 + \frac{1}{2} \right) \hat{\mathbf{z}} & (8d) & \text{S I} \\
\mathbf{B}_{20} &= - \left(x_3 - \frac{1}{2} \right) \mathbf{a}_1 + \left(y_3 + \frac{1}{2} \right) \mathbf{a}_2 + z_3 \mathbf{a}_3 = -a \left(x_3 - \frac{1}{2} \right) \hat{\mathbf{x}} + b \left(y_3 + \frac{1}{2} \right) \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}} & (8d) & \text{S I} \\
\mathbf{B}_{21} &= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3 = ax_4 \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}} & (8d) & \text{S II} \\
\mathbf{B}_{22} &= - \left(x_4 - \frac{1}{2} \right) \mathbf{a}_1 - \left(y_4 - \frac{1}{2} \right) \mathbf{a}_2 + \left(z_4 + \frac{1}{2} \right) \mathbf{a}_3 = -a \left(x_4 - \frac{1}{2} \right) \hat{\mathbf{x}} - b \left(y_4 - \frac{1}{2} \right) \hat{\mathbf{y}} + c \left(z_4 + \frac{1}{2} \right) \hat{\mathbf{z}} & (8d) & \text{S II} \\
\mathbf{B}_{23} &= -x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 - \left(z_4 - \frac{1}{2} \right) \mathbf{a}_3 = -ax_4 \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} - c \left(z_4 - \frac{1}{2} \right) \hat{\mathbf{z}} & (8d) & \text{S II} \\
\mathbf{B}_{24} &= \left(x_4 + \frac{1}{2} \right) \mathbf{a}_1 - \left(y_4 - \frac{1}{2} \right) \mathbf{a}_2 - z_4 \mathbf{a}_3 = a \left(x_4 + \frac{1}{2} \right) \hat{\mathbf{x}} - b \left(y_4 - \frac{1}{2} \right) \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}} & (8d) & \text{S II} \\
\mathbf{B}_{25} &= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3 = -ax_4 \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}} & (8d) & \text{S II} \\
\mathbf{B}_{26} &= \begin{pmatrix} (x_4 + \frac{1}{2}) \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - \\ (z_4 - \frac{1}{2}) \mathbf{a}_3 \end{pmatrix} = a \left(x_4 + \frac{1}{2} \right) \hat{\mathbf{x}} + b \left(y_4 + \frac{1}{2} \right) \hat{\mathbf{y}} - c \left(z_4 - \frac{1}{2} \right) \hat{\mathbf{z}} & (8d) & \text{S II} \\
\mathbf{B}_{27} &= x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 + \left(z_4 + \frac{1}{2} \right) \mathbf{a}_3 = ax_4 \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c \left(z_4 + \frac{1}{2} \right) \hat{\mathbf{z}} & (8d) & \text{S II} \\
\mathbf{B}_{28} &= - \left(x_4 - \frac{1}{2} \right) \mathbf{a}_1 + \left(y_4 + \frac{1}{2} \right) \mathbf{a}_2 + z_4 \mathbf{a}_3 = -a \left(x_4 - \frac{1}{2} \right) \hat{\mathbf{x}} + b \left(y_4 + \frac{1}{2} \right) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}} & (8d) & \text{S II}
\end{aligned}$$

References

- [1] K. Homma, M. Yonemura, M. Nagao, M. Hirayama, and R. Kanno, *Crystal Structure of High-Temperature Phase of Lithium Ionic Conductor, Li_3PS_4* , J. Phys. Soc. Jpn. **79**, 90–93 (2010), doi:10.1143/JPSJS.79SA.90.

Found in

- [1] K. Homma, M. Yonemura, T. Kobayashi, M. Nagao, M. Hirayama, and R. Kanno, *Crystal structure and phase transitions of the lithium ionic conductor Li_3PS_4* , Solid State Ionics **182**, 53–58 (2011), doi:10.1016/j.ssi.2010.10.001.

First cited in

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