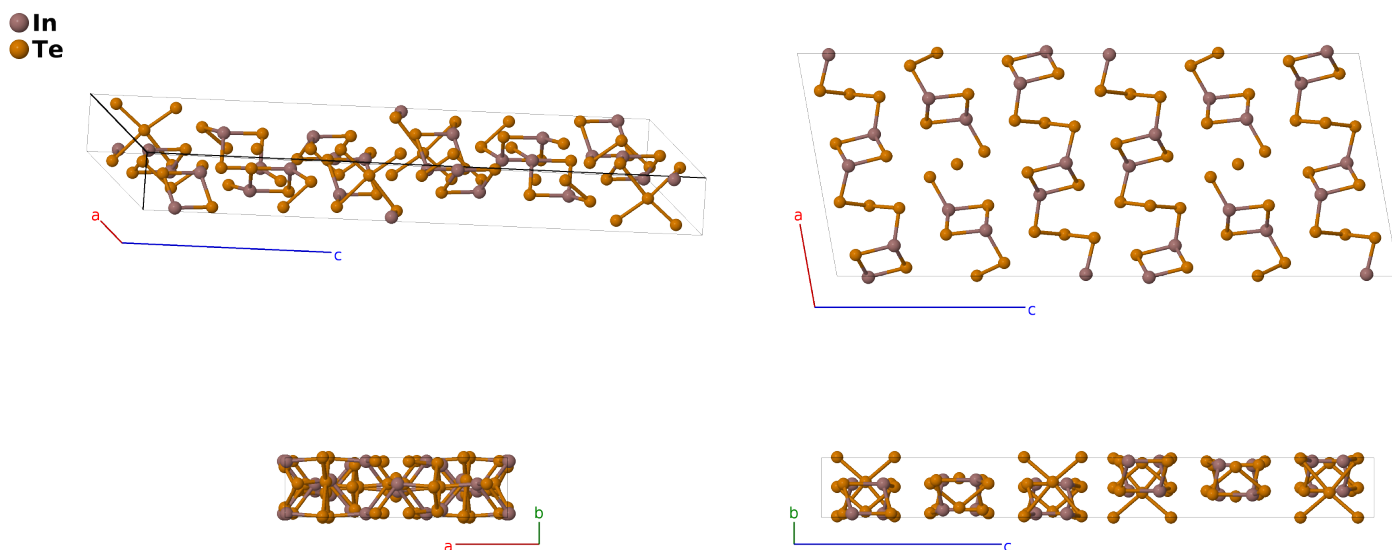


In₂Te₅ (II) Structure: A2B5_mC84_15_3f_e7f-001

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<https://afLOW.org/p/A3RY>

https://afLOW.org/p/A2B5_mC84_15_3f_e7f-001

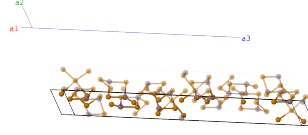


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ICSD	1385
Pearson symbol	mC84
Space group number	15
Space group symbol	<i>C</i> 2/ <i>c</i>
AFLOW prototype command	afLOW --proto=A2B5_mC84_15_3f_e7f-001 --params= <i>a</i> , <i>b/a</i> , <i>c/a</i> , β , <i>y</i> ₁ , <i>x</i> ₂ , <i>y</i> ₂ , <i>z</i> ₂ , <i>x</i> ₃ , <i>y</i> ₃ , <i>z</i> ₃ , <i>x</i> ₄ , <i>y</i> ₄ , <i>z</i> ₄ , <i>x</i> ₅ , <i>y</i> ₅ , <i>z</i> ₅ , <i>x</i> ₆ , <i>y</i> ₆ , <i>z</i> ₆ , <i>x</i> ₇ , <i>y</i> ₇ , <i>z</i> ₇ , <i>x</i> ₈ , <i>y</i> ₈ , <i>z</i> ₈ , <i>x</i> ₉ , <i>y</i> ₉ , <i>z</i> ₉ , <i>x</i> ₁₀ , <i>y</i> ₁₀ , <i>z</i> ₁₀ , <i>x</i> ₁₁ , <i>y</i> ₁₁ , <i>z</i> ₁₁

- (Sutherland, 1976) found the structure which we call In₂Te₅ (I), but later also found evidence of another tetragonal structure in the same sample. (Walton, 1978) investigated this new structure, which they called In₂Te₅ (II). (Villars, 2018) and others list In₂Te₅ (I) as the room temperature structure.

Base-centered Monoclinic primitive vectors

$$\begin{aligned}
\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}b \hat{\mathbf{y}} \\
\mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} \\
\mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}
\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$= -y_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}c \cos \beta \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + \frac{1}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	Te I
\mathbf{B}_2	$= y_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}c \cos \beta \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} + \frac{3}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	Te I
\mathbf{B}_3	$= (x_2 - y_2) \mathbf{a}_1 + (x_2 + y_2) \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(8f)	In I
\mathbf{B}_4	$= -(x_2 + y_2) \mathbf{a}_1 - (x_2 - y_2) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	In I
\mathbf{B}_5	$= -(x_2 - y_2) \mathbf{a}_1 - (x_2 + y_2) \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(8f)	In I
\mathbf{B}_6	$= (x_2 + y_2) \mathbf{a}_1 + (x_2 - y_2) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	In I
\mathbf{B}_7	$= (x_3 - y_3) \mathbf{a}_1 + (x_3 + y_3) \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(8f)	In II
\mathbf{B}_8	$= -(x_3 + y_3) \mathbf{a}_1 - (x_3 - y_3) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	In II
\mathbf{B}_9	$= -(x_3 - y_3) \mathbf{a}_1 - (x_3 + y_3) \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(8f)	In II
\mathbf{B}_{10}	$= (x_3 + y_3) \mathbf{a}_1 + (x_3 - y_3) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	In II
\mathbf{B}_{11}	$= (x_4 - y_4) \mathbf{a}_1 + (x_4 + y_4) \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(8f)	In III
\mathbf{B}_{12}	$= -(x_4 + y_4) \mathbf{a}_1 - (x_4 - y_4) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	In III
\mathbf{B}_{13}	$= -(x_4 - y_4) \mathbf{a}_1 - (x_4 + y_4) \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(8f)	In III
\mathbf{B}_{14}	$= (x_4 + y_4) \mathbf{a}_1 + (x_4 - y_4) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	In III
\mathbf{B}_{15}	$= (x_5 - y_5) \mathbf{a}_1 + (x_5 + y_5) \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(8f)	Te II
\mathbf{B}_{16}	$= -(x_5 + y_5) \mathbf{a}_1 - (x_5 - y_5) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	Te II
\mathbf{B}_{17}	$= -(x_5 - y_5) \mathbf{a}_1 - (x_5 + y_5) \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(8f)	Te II
\mathbf{B}_{18}	$= (x_5 + y_5) \mathbf{a}_1 + (x_5 - y_5) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	Te II
\mathbf{B}_{19}	$= (x_6 - y_6) \mathbf{a}_1 + (x_6 + y_6) \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(8f)	Te III
\mathbf{B}_{20}	$= -(x_6 + y_6) \mathbf{a}_1 - (x_6 - y_6) \mathbf{a}_2 - (z_6 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	Te III

$$\begin{aligned}
\mathbf{B}_{21} &= -(x_6 - y_6) \mathbf{a}_1 - (x_6 + y_6) \mathbf{a}_2 - z_6 \mathbf{a}_3 = -(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te III} \\
\mathbf{B}_{22} &= (x_6 + y_6) \mathbf{a}_1 + (x_6 - y_6) \mathbf{a}_2 + (z_6 + \frac{1}{2}) \mathbf{a}_3 = (ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te III} \\
\mathbf{B}_{23} &= (x_7 - y_7) \mathbf{a}_1 + (x_7 + y_7) \mathbf{a}_2 + z_7 \mathbf{a}_3 = (ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te IV} \\
\mathbf{B}_{24} &= -(x_7 + y_7) \mathbf{a}_1 - (x_7 - y_7) \mathbf{a}_2 - (z_7 - \frac{1}{2}) \mathbf{a}_3 = -(ax_7 + c(z_7 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te IV} \\
\mathbf{B}_{25} &= -(x_7 - y_7) \mathbf{a}_1 - (x_7 + y_7) \mathbf{a}_2 - z_7 \mathbf{a}_3 = -(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te IV} \\
\mathbf{B}_{26} &= (x_7 + y_7) \mathbf{a}_1 + (x_7 - y_7) \mathbf{a}_2 + (z_7 + \frac{1}{2}) \mathbf{a}_3 = (ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te IV} \\
\mathbf{B}_{27} &= (x_8 - y_8) \mathbf{a}_1 + (x_8 + y_8) \mathbf{a}_2 + z_8 \mathbf{a}_3 = (ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te V} \\
\mathbf{B}_{28} &= -(x_8 + y_8) \mathbf{a}_1 - (x_8 - y_8) \mathbf{a}_2 - (z_8 - \frac{1}{2}) \mathbf{a}_3 = -(ax_8 + c(z_8 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te V} \\
\mathbf{B}_{29} &= -(x_8 - y_8) \mathbf{a}_1 - (x_8 + y_8) \mathbf{a}_2 - z_8 \mathbf{a}_3 = -(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te V} \\
\mathbf{B}_{30} &= (x_8 + y_8) \mathbf{a}_1 + (x_8 - y_8) \mathbf{a}_2 + (z_8 + \frac{1}{2}) \mathbf{a}_3 = (ax_8 + c(z_8 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te V} \\
\mathbf{B}_{31} &= (x_9 - y_9) \mathbf{a}_1 + (x_9 + y_9) \mathbf{a}_2 + z_9 \mathbf{a}_3 = (ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VI} \\
\mathbf{B}_{32} &= -(x_9 + y_9) \mathbf{a}_1 - (x_9 - y_9) \mathbf{a}_2 - (z_9 - \frac{1}{2}) \mathbf{a}_3 = -(ax_9 + c(z_9 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} - c(z_9 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VI} \\
\mathbf{B}_{33} &= -(x_9 - y_9) \mathbf{a}_1 - (x_9 + y_9) \mathbf{a}_2 - z_9 \mathbf{a}_3 = -(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VI} \\
\mathbf{B}_{34} &= (x_9 + y_9) \mathbf{a}_1 + (x_9 - y_9) \mathbf{a}_2 + (z_9 + \frac{1}{2}) \mathbf{a}_3 = (ax_9 + c(z_9 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} + c(z_9 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VI} \\
\mathbf{B}_{35} &= (x_{10} - y_{10}) \mathbf{a}_1 + (x_{10} + y_{10}) \mathbf{a}_2 + z_{10} \mathbf{a}_3 = (ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VII} \\
\mathbf{B}_{36} &= -(x_{10} + y_{10}) \mathbf{a}_1 - (x_{10} - y_{10}) \mathbf{a}_2 - (z_{10} - \frac{1}{2}) \mathbf{a}_3 = -(ax_{10} + c(z_{10} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} - c(z_{10} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VII} \\
\mathbf{B}_{37} &= -(x_{10} - y_{10}) \mathbf{a}_1 - (x_{10} + y_{10}) \mathbf{a}_2 - z_{10} \mathbf{a}_3 = -(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} - cz_{10} \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VII} \\
\mathbf{B}_{38} &= (x_{10} + y_{10}) \mathbf{a}_1 + (x_{10} - y_{10}) \mathbf{a}_2 + (z_{10} + \frac{1}{2}) \mathbf{a}_3 = (ax_{10} + c(z_{10} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} + c(z_{10} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VII} \\
\mathbf{B}_{39} &= (x_{11} - y_{11}) \mathbf{a}_1 + (x_{11} + y_{11}) \mathbf{a}_2 + z_{11} \mathbf{a}_3 = (ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} + cz_{11} \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VIII} \\
\mathbf{B}_{40} &= -(x_{11} + y_{11}) \mathbf{a}_1 - (x_{11} - y_{11}) \mathbf{a}_2 - (z_{11} - \frac{1}{2}) \mathbf{a}_3 = -(ax_{11} + c(z_{11} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} - c(z_{11} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VIII} \\
\mathbf{B}_{41} &= -(x_{11} - y_{11}) \mathbf{a}_1 - (x_{11} + y_{11}) \mathbf{a}_2 - z_{11} \mathbf{a}_3 = -(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} - cz_{11} \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VIII} \\
\mathbf{B}_{42} &= (x_{11} + y_{11}) \mathbf{a}_1 + (x_{11} - y_{11}) \mathbf{a}_2 + (z_{11} + \frac{1}{2}) \mathbf{a}_3 = (ax_{11} + c(z_{11} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} + c(z_{11} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (8f) & \text{Te VIII}
\end{aligned}$$

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