

Li₂WO₄ (II) Structure:

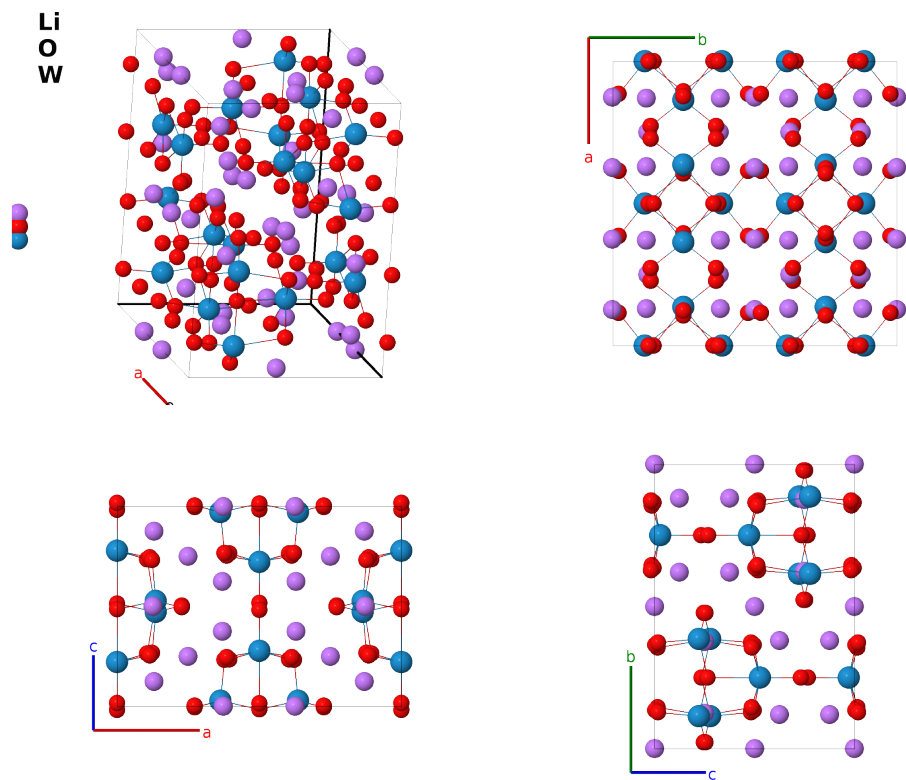
A2B4C_tI112_141_fg_2hi_h-001

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<https://aflow.org/prototype-encyclopedia/M4CM>

https://aflow.org/prototype-encyclopedia/A2B4C_tI112_141_fg_2hi_h-001

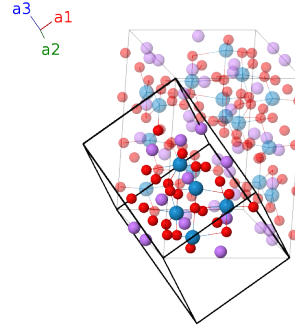


Prototype	Li ₂ O ₄ W
AFLOW prototype label	A2B4C_tI112_141_fg_2hi_h-001
ICSD	10479
CCDC	1595311
Pearson symbol	tI112
Space group number	141
Space group symbol	<i>I</i> 4 ₁ / <i>amd</i>
AFLOW prototype command	<code>aflow --proto=A2B4C_tI112_141_fg_2hi_h-001</code> <code>--params=a, c/a, x₁, x₂, y₃, z₃, y₄, z₄, y₅, z₅, x₆, y₆, z₆</code>

- Li_2WO_4 is found in a variety of phases at different pressures and temperatures (Yamaoka, 1973; Pistorius, 1975):
- $\text{Li}_2\text{WO}_4(\text{I})$, which is in the Phenakite ($S1_3$) structure, is stable at low pressures and temperatures above 300°C .
- Tetragonal $\text{Li}_2\text{WO}_4(\text{II})$ (this structure) is the ground state, and is stable below a line from (300°C , 0 kBar) to (650°C , 2 kBar) to (550°C , 12 kBar) to (380°C , 15 kBar).
- Orthorhombic $\text{Li}_2\text{WO}_4(\text{III})$ is the high temperature structure for all pressures above phases II and IV. Its exact crystal structure has not been determined. It has been conjectured to be in space group $Pna2_1$ #33, $Pnmm$ #58 or $Cmmm$ #65.
- Monoclinic $\text{Li}_2\text{WO}_4(\text{IV})$, stable at pressures higher than phase II and temperatures lower than phase III.
- Later (Hämmer, 2022) determined the structure of triclinic Li_2WO_4 (V) (this structure), which may be the phase (Belyaev, 1961) observed at ambient pressure above 660°C .
- (Horiuchi, 1979) state that this structure is similar to spinel ($H1_4$).
- The ICSD assigns this structure to the Bi_2CdO_4 prototype, but these structures do not even have the same sets of occupied Wyckoff positions, so we give Li_2WO_4 (II) its own prototype.

Body-centered Tetragonal primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= -\frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}a\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a\hat{\mathbf{x}} - \frac{1}{2}a\hat{\mathbf{y}} + \frac{1}{2}c\hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}a\hat{\mathbf{y}} - \frac{1}{2}c\hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= x_1 \mathbf{a}_2 + x_1 \mathbf{a}_3$	$=$	$ax_1 \hat{\mathbf{x}}$	(16f)	Li I
$\mathbf{B}_2$	$= \frac{1}{2} \mathbf{a}_1 - x_1 \mathbf{a}_2 - (x_1 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-ax_1 \hat{\mathbf{x}} + \frac{1}{2}a\hat{\mathbf{y}}$	(16f)	Li I
$\mathbf{B}_3$	$= x_1 \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2 + x_1 \mathbf{a}_3$	$=$	$\frac{1}{4}a\hat{\mathbf{x}} + a(x_1 - \frac{1}{4})\hat{\mathbf{y}} + \frac{1}{4}c\hat{\mathbf{z}}$	(16f)	Li I
$\mathbf{B}_4$	$= -x_1 \mathbf{a}_1 - (x_1 - \frac{1}{2}) \mathbf{a}_3$	$=$	$\frac{1}{4}a\hat{\mathbf{x}} - a(x_1 - \frac{1}{4})\hat{\mathbf{y}} - \frac{1}{4}c\hat{\mathbf{z}}$	(16f)	Li I
$\mathbf{B}_5$	$= -x_1 \mathbf{a}_2 - x_1 \mathbf{a}_3$	$=$	$-ax_1 \hat{\mathbf{x}}$	(16f)	Li I
$\mathbf{B}_6$	$= \frac{1}{2} \mathbf{a}_1 + x_1 \mathbf{a}_2 + (x_1 + \frac{1}{2}) \mathbf{a}_3$	$=$	$ax_1 \hat{\mathbf{x}} + \frac{1}{2}a\hat{\mathbf{y}}$	(16f)	Li I
$\mathbf{B}_7$	$= -x_1 \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2 - x_1 \mathbf{a}_3$	$=$	$\frac{1}{4}a\hat{\mathbf{x}} - a(x_1 + \frac{1}{4})\hat{\mathbf{y}} + \frac{1}{4}c\hat{\mathbf{z}}$	(16f)	Li I
$\mathbf{B}_8$	$= x_1 \mathbf{a}_1 + (x_1 + \frac{1}{2}) \mathbf{a}_3$	$=$	$\frac{1}{4}a\hat{\mathbf{x}} + a(x_1 + \frac{1}{4})\hat{\mathbf{y}} - \frac{1}{4}c\hat{\mathbf{z}}$	(16f)	Li I
$\mathbf{B}_9$	$= (x_2 + \frac{1}{8}) \mathbf{a}_1 + (x_2 + \frac{7}{8}) \mathbf{a}_2 + (2x_2 + \frac{1}{4}) \mathbf{a}_3$	$=$	$a(x_2 + \frac{1}{2})\hat{\mathbf{x}} + a(x_2 - \frac{1}{4})\hat{\mathbf{y}} + \frac{3}{8}c\hat{\mathbf{z}}$	(16g)	Li II
$\mathbf{B}_{10}$	$= -(x_2 - \frac{1}{8}) \mathbf{a}_1 - (x_2 - \frac{7}{8}) \mathbf{a}_2 - (2x_2 - \frac{1}{4}) \mathbf{a}_3$	$=$	$-a(x_2 - \frac{1}{2})\hat{\mathbf{x}} - a(x_2 + \frac{1}{4})\hat{\mathbf{y}} + \frac{3}{8}c\hat{\mathbf{z}}$	(16g)	Li II
$\mathbf{B}_{11}$	$= (x_2 + \frac{7}{8}) \mathbf{a}_1 - (x_2 - \frac{1}{8}) \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} + a(x_2 + \frac{3}{4})\hat{\mathbf{y}} + \frac{1}{8}c\hat{\mathbf{z}}$	(16g)	Li II
$\mathbf{B}_{12}$	$= -(x_2 - \frac{7}{8}) \mathbf{a}_1 + (x_2 + \frac{1}{8}) \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$ax_2 \hat{\mathbf{x}} - a(x_2 - \frac{3}{4})\hat{\mathbf{y}} + \frac{1}{8}c\hat{\mathbf{z}}$	(16g)	Li II
$\mathbf{B}_{13}$	$= -(x_2 - \frac{7}{8}) \mathbf{a}_1 - (x_2 - \frac{1}{8}) \mathbf{a}_2 - (2x_2 - \frac{3}{4}) \mathbf{a}_3$	$=$	$-ax_2 \hat{\mathbf{x}} - a(x_2 - \frac{3}{4})\hat{\mathbf{y}} + \frac{1}{8}c\hat{\mathbf{z}}$	(16g)	Li II

$$\begin{aligned}
\mathbf{B}_{44} &= \begin{matrix} -(x_6 - z_6) \mathbf{a}_1 + (y_6 + z_6) \mathbf{a}_2 + \\ (-x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 \end{matrix} = a \left(y_6 + \frac{1}{4} \right) \hat{\mathbf{x}} - a \left(x_6 - \frac{1}{4} \right) \hat{\mathbf{y}} + c \left(z_6 - \frac{1}{4} \right) \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{45} &= \begin{matrix} (y_6 - z_6 + \frac{1}{2}) \mathbf{a}_1 - (x_6 + z_6) \mathbf{a}_2 + \\ (-x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 \end{matrix} = -ax_6 \hat{\mathbf{x}} + a \left(y_6 + \frac{1}{2} \right) \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{46} &= \begin{matrix} -(y_6 + z_6) \mathbf{a}_1 + (x_6 - z_6) \mathbf{a}_2 + \\ (x_6 - y_6) \mathbf{a}_3 \end{matrix} = ax_6 \hat{\mathbf{x}} - ay_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{47} &= \begin{matrix} (x_6 - z_6) \mathbf{a}_1 + \\ (y_6 - z_6 + \frac{1}{2}) \mathbf{a}_2 + (x_6 + y_6) \mathbf{a}_3 \end{matrix} = a \left(y_6 + \frac{1}{4} \right) \hat{\mathbf{x}} + a \left(x_6 - \frac{1}{4} \right) \hat{\mathbf{y}} - c \left(z_6 - \frac{1}{4} \right) \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{48} &= \begin{matrix} -(x_6 + z_6) \mathbf{a}_1 - (y_6 + z_6) \mathbf{a}_2 - \\ (x_6 + y_6 - \frac{1}{2}) \mathbf{a}_3 \end{matrix} = -a \left(y_6 - \frac{1}{4} \right) \hat{\mathbf{x}} - a \left(x_6 - \frac{1}{4} \right) \hat{\mathbf{y}} - c \left(z_6 + \frac{1}{4} \right) \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{49} &= \begin{matrix} -(y_6 + z_6) \mathbf{a}_1 - (x_6 + z_6) \mathbf{a}_2 - \\ (x_6 + y_6) \mathbf{a}_3 \end{matrix} = -ax_6 \hat{\mathbf{x}} - ay_6 \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{50} &= \begin{matrix} (y_6 - z_6 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_6 - z_6) \mathbf{a}_2 + (x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 \end{matrix} = ax_6 \hat{\mathbf{x}} + a \left(y_6 + \frac{1}{2} \right) \hat{\mathbf{y}} - cz_6 \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{51} &= \begin{matrix} -(x_6 + z_6) \mathbf{a}_1 + \\ (y_6 - z_6 + \frac{1}{2}) \mathbf{a}_2 - (x_6 - y_6) \mathbf{a}_3 \end{matrix} = a \left(y_6 + \frac{1}{4} \right) \hat{\mathbf{x}} - a \left(x_6 + \frac{1}{4} \right) \hat{\mathbf{y}} - c \left(z_6 - \frac{1}{4} \right) \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{52} &= \begin{matrix} (x_6 - z_6) \mathbf{a}_1 - (y_6 + z_6) \mathbf{a}_2 + \\ (x_6 - y_6 + \frac{1}{2}) \mathbf{a}_3 \end{matrix} = -a \left(y_6 - \frac{1}{4} \right) \hat{\mathbf{x}} + a \left(x_6 + \frac{1}{4} \right) \hat{\mathbf{y}} - c \left(z_6 + \frac{1}{4} \right) \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{53} &= \begin{matrix} (-y_6 + z_6 + \frac{1}{2}) \mathbf{a}_1 + \\ (x_6 + z_6) \mathbf{a}_2 + (x_6 - y_6 + \frac{1}{2}) \mathbf{a}_3 \end{matrix} = ax_6 \hat{\mathbf{x}} - a \left(y_6 - \frac{1}{2} \right) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{54} &= \begin{matrix} (y_6 + z_6) \mathbf{a}_1 - (x_6 - z_6) \mathbf{a}_2 - \\ (x_6 - y_6) \mathbf{a}_3 \end{matrix} = -ax_6 \hat{\mathbf{x}} + ay_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{55} &= \begin{matrix} -(x_6 - z_6) \mathbf{a}_1 + \\ (-y_6 + z_6 + \frac{1}{2}) \mathbf{a}_2 - (x_6 + y_6) \mathbf{a}_3 \end{matrix} = -a \left(y_6 - \frac{1}{4} \right) \hat{\mathbf{x}} - a \left(x_6 + \frac{1}{4} \right) \hat{\mathbf{y}} + c \left(z_6 + \frac{1}{4} \right) \hat{\mathbf{z}} & (32i) & \text{O III} \\
\mathbf{B}_{56} &= \begin{matrix} (x_6 + z_6) \mathbf{a}_1 + (y_6 + z_6) \mathbf{a}_2 + \\ (x_6 + y_6 + \frac{1}{2}) \mathbf{a}_3 \end{matrix} = a \left(y_6 + \frac{1}{4} \right) \hat{\mathbf{x}} + a \left(x_6 + \frac{1}{4} \right) \hat{\mathbf{y}} + c \left(z_6 - \frac{1}{4} \right) \hat{\mathbf{z}} & (32i) & \text{O III}
\end{aligned}$$

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Found in

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