

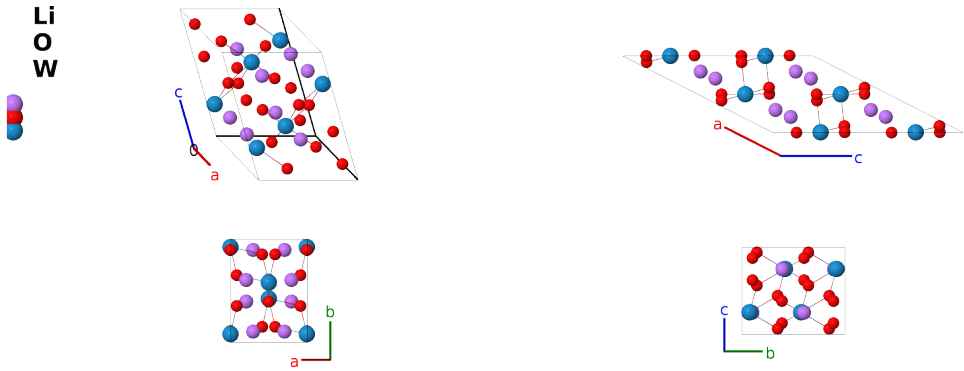
Li₂WO₄ (IV) Structure: A2B4C_mC28_15_f_2f_e-003

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<https://aflow.org/prototype-encyclopedia/GV2Q>

https://aflow.org/prototype-encyclopedia/A2B4C_mC28_15_f_2f_e-003



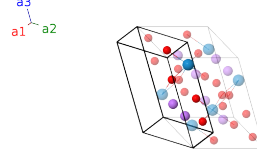
Prototype	Li ₂ O ₄ W
AFLOW prototype label	A2B4C_mC28_15_f_2f_e-003
ICSD	14196
CCDC	1595595
Pearson symbol	mC28
Space group number	15
Space group symbol	<i>C</i> 2/ <i>c</i>
AFLOW prototype command	<code>aflow --proto=A2B4C_mC28_15_f_2f_e-003</code> <code>--params=a, b/a, c/a, β, y_1, x_2, y_2, z_2, x_3, y_3, z_3, x_4, y_4, z_4</code>

- Li₂WO₄ is found in a variety of phases at different pressures and temperatures (Yamaoka, 1973; Pistorius, 1975):
- Li₂WO₄(I), which is in the Phenakite (*S*₁₃) structure, is stable at low pressures and temperatures above 300°C.
- Tetragonal Li₂WO₄(II) is the ground state, and is stable below a line from (300°C, 0 kBar) to (650°C, 2 kBar) to (550°C, 12 kBar) to (380°C, 15 kBar).
- Orthorhombic Li₂WO₄(III) is the high temperature structure for all pressures above phases II and IV. Its exact crystal structure has not been determined. It has been conjectured to be in space group *Pna*2₁ #33, *Pnnm* #58 or *Cmmm* #65.
- Monoclinic Li₂WO₄(IV) (this structure), stable at pressures higher than phase II and temperatures lower than phase III.
- Later (Hämmer, 2022) determined the structure of triclinic Li₂WO₄ (V) (this structure), which may be the phase (Belyaev, 1961) observed at ambient pressure above 660°C.

- The measured sample of phase IV was synthesized at 40 kBar and 850°C.
- (Horiuchi, 1980) state that this structure is similar to wolframite.
- $\text{Li}_2\text{WO}_4(\text{IV})$ and H_2SO_4 have the same AFLOW prototype label, A2B4C_mC28_15_f_2f_e. They are generated by the same symmetry operations with different sets of parameters (`--params`) specified in their corresponding CIF files.

Base-centered Monoclinic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a \hat{\mathbf{x}} - \frac{1}{2}b \hat{\mathbf{y}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
$\mathbf{B}_1$	$= -y_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + \frac{1}{4} \mathbf{a}_3$	$=$	$\frac{1}{4}c \cos \beta \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + \frac{1}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	W I
$\mathbf{B}_2$	$= y_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 + \frac{3}{4} \mathbf{a}_3$	$=$	$\frac{3}{4}c \cos \beta \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} + \frac{3}{4}c \sin \beta \hat{\mathbf{z}}$	(4e)	W I
$\mathbf{B}_3$	$= (x_2 - y_2) \mathbf{a}_1 + (x_2 + y_2) \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(8f)	Li I
$\mathbf{B}_4$	$= -(x_2 + y_2) \mathbf{a}_1 - (x_2 - y_2) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	Li I
$\mathbf{B}_5$	$= -(x_2 - y_2) \mathbf{a}_1 - (x_2 + y_2) \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(8f)	Li I
$\mathbf{B}_6$	$= (x_2 + y_2) \mathbf{a}_1 + (x_2 - y_2) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	Li I
$\mathbf{B}_7$	$= (x_3 - y_3) \mathbf{a}_1 + (x_3 + y_3) \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(8f)	O I
$\mathbf{B}_8$	$= -(x_3 + y_3) \mathbf{a}_1 - (x_3 - y_3) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	O I
$\mathbf{B}_9$	$= -(x_3 - y_3) \mathbf{a}_1 - (x_3 + y_3) \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(8f)	O I
$\mathbf{B}_{10}$	$= (x_3 + y_3) \mathbf{a}_1 + (x_3 - y_3) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	O I
$\mathbf{B}_{11}$	$= (x_4 - y_4) \mathbf{a}_1 + (x_4 + y_4) \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B}_{12}$	$= -(x_4 + y_4) \mathbf{a}_1 - (x_4 - y_4) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B}_{13}$	$= -(x_4 - y_4) \mathbf{a}_1 - (x_4 + y_4) \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(8f)	O II
$\mathbf{B}_{14}$	$= (x_4 + y_4) \mathbf{a}_1 + (x_4 - y_4) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(8f)	O II

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