

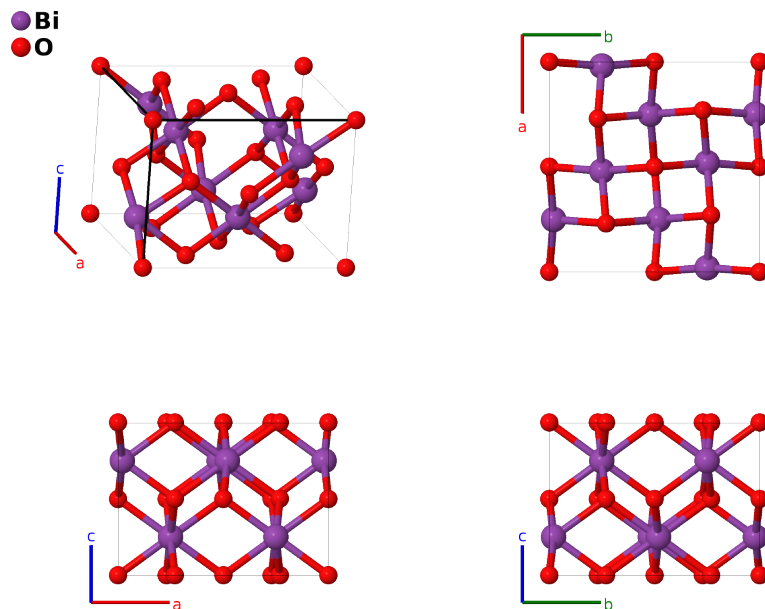
β -Bi₂O₃ ($D_{5_{12}}$) Structure: A2B3_tP20_117_i_adgh-001

This structure originally had the label A2B3_tP20_117_i_adgh. Calls to that address will be redirected here.

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<https://afLOW.org/p/B48H>

https://afLOW.org/p/A2B3_tP20_117_i_adgh-001



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|------------------------------------|--|
| Prototype | Bi ₂ O ₃ |
| AFLOW prototype label | A2B3_tP20_117_i_adgh-001 |
| <i>Strukturbericht</i> designation | $D_{5_{12}}$ |
| ICSD | 27151 |
| Pearson symbol | tP20 |
| Space group number | 117 |
| Space group symbol | $P\bar{4}b2$ |
| AFLOW prototype command | <code>afLOW --proto=A2B3_tP20_117_i_adgh-001 --params=a, c/a, x₃, x₄, x₅, y₅, z₅</code> |

- Bi₂O₃ can be found in at least six forms (Harwig, 1978; Locherer, 2011):
 - monoclinic α -Bi₂O₃, the ground state, stable up to 729°,
 - tetragonal β -Bi₂O₃, $D_{5_{12}}$, a metastable state observed at 650°C (this structure),
 - body-centered cubic γ -Bi₂O₃, another metastable phase observed at 639°C,

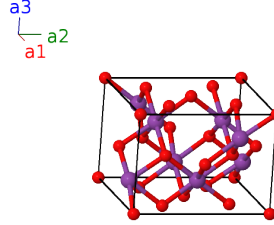
- face-centered cubic δ - Bi_2O_3 , the stable phase from 729° up to the melting point at 824°C,
 - a high-pressure HP- Bi_2O_3 , and
 - a second “nonquenchable” high-pressure structure, HPC- Bi_2O_3 .
- (Sillén, 1937) presented this structure in the doubled-unit cell $C\bar{4}2b$ setting of space group #117, and the ICSD entry is from that paper. We follow (Harwig, 1978) and use the standard $P\bar{4}b2$ setting. We have shifted the origin so that the O-I atom is at the (2a) site.

Simple Tetragonal primitive vectors

$$\mathbf{a}_1 = a \hat{\mathbf{x}}$$

$$\mathbf{a}_2 = a \hat{\mathbf{y}}$$

$$\mathbf{a}_3 = c \hat{\mathbf{z}}$$



Basis vectors

| | Lattice coordinates | | Cartesian coordinates | Wyckoff position | Atom type |
|---------------------|---|---|--|------------------|-----------|
| $\mathbf{B}_1 =$ | 0 | = | 0 | (2a) | O I |
| $\mathbf{B}_2 =$ | $\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_2$ | = | $\frac{1}{2} a \hat{\mathbf{x}} + \frac{1}{2} a \hat{\mathbf{y}}$ | (2a) | O I |
| $\mathbf{B}_3 =$ | $\frac{1}{2} \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | = | $\frac{1}{2} a \hat{\mathbf{y}} + \frac{1}{2} c \hat{\mathbf{z}}$ | (2d) | O II |
| $\mathbf{B}_4 =$ | $\frac{1}{2} \mathbf{a}_1 + \frac{1}{2} \mathbf{a}_3$ | = | $\frac{1}{2} a \hat{\mathbf{x}} + \frac{1}{2} c \hat{\mathbf{z}}$ | (2d) | O II |
| $\mathbf{B}_5 =$ | $x_3 \mathbf{a}_1 + (x_3 + \frac{1}{2}) \mathbf{a}_2$ | = | $ax_3 \hat{\mathbf{x}} + a(x_3 + \frac{1}{2}) \hat{\mathbf{y}}$ | (4g) | O III |
| $\mathbf{B}_6 =$ | $-x_3 \mathbf{a}_1 - (x_3 - \frac{1}{2}) \mathbf{a}_2$ | = | $-ax_3 \hat{\mathbf{x}} - a(x_3 - \frac{1}{2}) \hat{\mathbf{y}}$ | (4g) | O III |
| $\mathbf{B}_7 =$ | $(x_3 + \frac{1}{2}) \mathbf{a}_1 - x_3 \mathbf{a}_2$ | = | $a(x_3 + \frac{1}{2}) \hat{\mathbf{x}} - ax_3 \hat{\mathbf{y}}$ | (4g) | O III |
| $\mathbf{B}_8 =$ | $-(x_3 - \frac{1}{2}) \mathbf{a}_1 + x_3 \mathbf{a}_2$ | = | $-a(x_3 - \frac{1}{2}) \hat{\mathbf{x}} + ax_3 \hat{\mathbf{y}}$ | (4g) | O III |
| $\mathbf{B}_9 =$ | $x_4 \mathbf{a}_1 + (x_4 + \frac{1}{2}) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | = | $ax_4 \hat{\mathbf{x}} + a(x_4 + \frac{1}{2}) \hat{\mathbf{y}} + \frac{1}{2} c \hat{\mathbf{z}}$ | (4h) | O IV |
| $\mathbf{B}_{10} =$ | $-x_4 \mathbf{a}_1 - (x_4 - \frac{1}{2}) \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | = | $-ax_4 \hat{\mathbf{x}} - a(x_4 - \frac{1}{2}) \hat{\mathbf{y}} + \frac{1}{2} c \hat{\mathbf{z}}$ | (4h) | O IV |
| $\mathbf{B}_{11} =$ | $(x_4 + \frac{1}{2}) \mathbf{a}_1 - x_4 \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | = | $a(x_4 + \frac{1}{2}) \hat{\mathbf{x}} - ax_4 \hat{\mathbf{y}} + \frac{1}{2} c \hat{\mathbf{z}}$ | (4h) | O IV |
| $\mathbf{B}_{12} =$ | $-(x_4 - \frac{1}{2}) \mathbf{a}_1 + x_4 \mathbf{a}_2 + \frac{1}{2} \mathbf{a}_3$ | = | $-a(x_4 - \frac{1}{2}) \hat{\mathbf{x}} + ax_4 \hat{\mathbf{y}} + \frac{1}{2} c \hat{\mathbf{z}}$ | (4h) | O IV |
| $\mathbf{B}_{13} =$ | $x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$ | = | $ax_5 \hat{\mathbf{x}} + ay_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$ | (8i) | Bi I |
| $\mathbf{B}_{14} =$ | $-x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$ | = | $-ax_5 \hat{\mathbf{x}} - ay_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$ | (8i) | Bi I |
| $\mathbf{B}_{15} =$ | $y_5 \mathbf{a}_1 - x_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$ | = | $ay_5 \hat{\mathbf{x}} - ax_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$ | (8i) | Bi I |
| $\mathbf{B}_{16} =$ | $-y_5 \mathbf{a}_1 + x_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$ | = | $-ay_5 \hat{\mathbf{x}} + ax_5 \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$ | (8i) | Bi I |
| $\mathbf{B}_{17} =$ | $(x_5 + \frac{1}{2}) \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 + z_5 \mathbf{a}_3$ | = | $a(x_5 + \frac{1}{2}) \hat{\mathbf{x}} - a(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$ | (8i) | Bi I |
| $\mathbf{B}_{18} =$ | $-(x_5 - \frac{1}{2}) \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 + z_5 \mathbf{a}_3$ | = | $-a(x_5 - \frac{1}{2}) \hat{\mathbf{x}} + a(y_5 + \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$ | (8i) | Bi I |
| $\mathbf{B}_{19} =$ | $(y_5 + \frac{1}{2}) \mathbf{a}_1 + (x_5 + \frac{1}{2}) \mathbf{a}_2 - z_5 \mathbf{a}_3$ | = | $a(y_5 + \frac{1}{2}) \hat{\mathbf{x}} + a(x_5 + \frac{1}{2}) \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$ | (8i) | Bi I |
| $\mathbf{B}_{20} =$ | $-(y_5 - \frac{1}{2}) \mathbf{a}_1 - (x_5 - \frac{1}{2}) \mathbf{a}_2 - z_5 \mathbf{a}_3$ | = | $-a(y_5 - \frac{1}{2}) \hat{\mathbf{x}} - a(x_5 - \frac{1}{2}) \hat{\mathbf{y}} - cz_5 \hat{\mathbf{z}}$ | (8i) | Bi I |

References

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