

K₂Te₃ Structure:

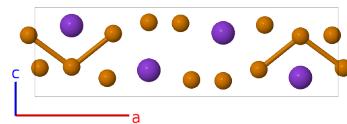
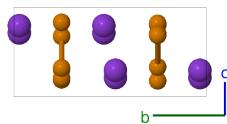
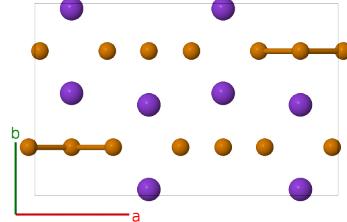
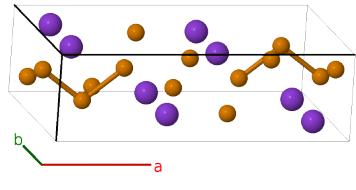
A2B3_oP20_62_d_3c-001

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<https://aflow.org/p/GCVK>

https://aflow.org/p/A2B3_oP20_62_d_3c-001

● K
● Te



Prototype

K₂Te₃

AFLOW prototype label

A2B3_oP20_62_d_3c-001

ICSD

2453

Pearson symbol

oP20

Space group number

62

Space group symbol

Pnma

AFLOW prototype command

```
aflow --proto=A2B3_oP20_62_d_3c-001
--params=a,b/a,c/a,x1,z1,x2,z2,x3,z3,x4,y4,z4
```

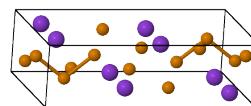
Other compounds with this structure

Rb₂Te₃

Simple Orthorhombic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \hat{\mathbf{z}} \end{aligned}$$

\mathbf{a}_1
 \mathbf{a}_2
 \mathbf{a}_3



Basis vectors

| | Lattice coordinates | | Cartesian coordinates | Wyckoff position | Atom type |
|-------------------|---|---|--|---------------------|--------------|
| \mathbf{B}_1 | $x_1 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_1 \mathbf{a}_3$ | = | $ax_1 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$ | (4c) | Te I |
| \mathbf{B}_2 | $-(x_1 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$ | = | $-a(x_1 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \hat{\mathbf{z}}$ | (4c) | Te I |
| \mathbf{B}_3 | $-x_1 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_1 \mathbf{a}_3$ | = | $-ax_1 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_1 \hat{\mathbf{z}}$ | (4c) | Te I |
| \mathbf{B}_4 | $(x_1 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$ | = | $a(x_1 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \hat{\mathbf{z}}$ | (4c) | Te I |
| \mathbf{B}_5 | $x_2 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_2 \mathbf{a}_3$ | = | $ax_2 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$ | (4c) | Te II |
| \mathbf{B}_6 | $-(x_2 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$ | = | $-a(x_2 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \hat{\mathbf{z}}$ | (4c) | Te II |
| \mathbf{B}_7 | $-x_2 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_2 \mathbf{a}_3$ | = | $-ax_2 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_2 \hat{\mathbf{z}}$ | (4c) | Te II |
| \mathbf{B}_8 | $(x_2 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$ | = | $a(x_2 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \hat{\mathbf{z}}$ | (4c) | Te II |
| \mathbf{B}_9 | $x_3 \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 + z_3 \mathbf{a}_3$ | = | $ax_3 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$ | (4c) | Te III |
| \mathbf{B}_{10} | $-(x_3 - \frac{1}{2}) \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$ | = | $-a(x_3 - \frac{1}{2}) \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \hat{\mathbf{z}}$ | (4c) | Te III |
| \mathbf{B}_{11} | $-x_3 \mathbf{a}_1 + \frac{3}{4} \mathbf{a}_2 - z_3 \mathbf{a}_3$ | = | $-ax_3 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} - cz_3 \hat{\mathbf{z}}$ | (4c) | Te III |
| \mathbf{B}_{12} | $(x_3 + \frac{1}{2}) \mathbf{a}_1 + \frac{1}{4} \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$ | = | $a(x_3 + \frac{1}{2}) \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \hat{\mathbf{z}}$ | (4c) | Te III |
| \mathbf{B}_{13} | $x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$ | = | $ax_4 \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$ | (8d) | K I |
| \mathbf{B}_{14} | $-(x_4 - \frac{1}{2}) \mathbf{a}_1 - y_4 \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$ | = | $-a(x_4 - \frac{1}{2}) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \hat{\mathbf{z}}$ | (8d) | K I |
| \mathbf{B}_{15} | $-x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - z_4 \mathbf{a}_3$ | = | $-ax_4 \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$ | (8d) | K I |
| \mathbf{B}_{16} | $(x_4 + \frac{1}{2}) \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$ | = | $a(x_4 + \frac{1}{2}) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \hat{\mathbf{z}}$ | (8d) | K I |
| \mathbf{B}_{17} | $-x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$ | = | $-ax_4 \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \hat{\mathbf{z}}$ | (8d) | K I |
| \mathbf{B}_{18} | $(x_4 + \frac{1}{2}) \mathbf{a}_1 + y_4 \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$ | = | $a(x_4 + \frac{1}{2}) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \hat{\mathbf{z}}$ | (8d) | K I |
| \mathbf{B}_{19} | $x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + z_4 \mathbf{a}_3$ | = | $ax_4 \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$ | (8d) | K I |
| \mathbf{B}_{20} | $-(x_4 - \frac{1}{2}) \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$ | = | $-a(x_4 - \frac{1}{2}) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \hat{\mathbf{z}}$ | (8d) | K I |

References

- [1] B. Eisenmann and H. Schäfer, *K₂Te₃: The First Binary Alkali-Metal Polytelluride with Te₃²⁻ Ions*, Angew. Chem. Int. Ed. **17**, 684 (1978), doi:10.1002/anie.197806841.

Found in

- [1] P. Böttcher, *Synthesis and crystal structure of Rb₂Te₃ and Cs₂Te₃*, J. Less-Common Met. **70**, 263–271 (1980), doi:10.1016/0022-5088(80)90235-0.