

Ta₃S₂ Structure:

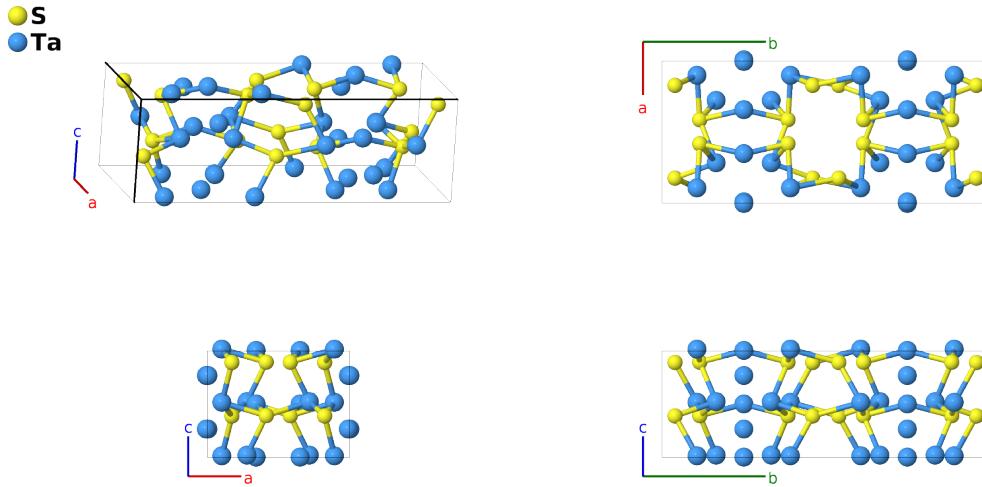
A2B3_oC40_39_2d_2c2d-001

This structure originally had the label A2B3_oC40_39_2d_2c2d. Calls to that address will be redirected here.

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<https://aflow.org/p/4YG0>

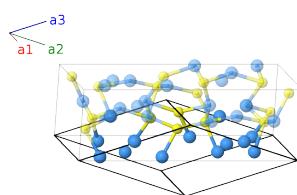
https://aflow.org/p/A2B3_oC40_39_2d_2c2d-001



Prototype	S ₂ Ta ₃
AFLOW prototype label	A2B3_oC40_39_2d_2c2d-001
ICSD	71143
Pearson symbol	oC40
Space group number	39
Space group symbol	<i>Aem</i> 2
AFLOW prototype command	<pre>aflow --proto=A2B3_oC40_39_2d_2c2d-001 --params=a,b/a,c/a,x1,z1,x2,z2,x3,y3,z3,x4,y4,z4,x5,y5,z5,x6,y6,z6</pre>

Base-centered Orthorhombic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= \frac{1}{2}b \hat{\mathbf{y}} - \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates	Cartesian coordinates	Wyckoff position	Atom type
B₁	$x_1 \mathbf{a}_1 - (z_1 - \frac{1}{4}) \mathbf{a}_2 + (z_1 + \frac{1}{4}) \mathbf{a}_3 =$	$ax_1 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(4c)	Ta I
B₂	$-x_1 \mathbf{a}_1 - (z_1 - \frac{3}{4}) \mathbf{a}_2 + (z_1 + \frac{3}{4}) \mathbf{a}_3 =$	$-ax_1 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + cz_1 \hat{\mathbf{z}}$	(4c)	Ta I
B₃	$x_2 \mathbf{a}_1 - (z_2 - \frac{1}{4}) \mathbf{a}_2 + (z_2 + \frac{1}{4}) \mathbf{a}_3 =$	$ax_2 \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(4c)	Ta II
B₄	$-x_2 \mathbf{a}_1 - (z_2 - \frac{3}{4}) \mathbf{a}_2 + (z_2 + \frac{3}{4}) \mathbf{a}_3 =$	$-ax_2 \hat{\mathbf{x}} + \frac{3}{4}b \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}}$	(4c)	Ta II
B₅	$x_3 \mathbf{a}_1 + (y_3 - z_3) \mathbf{a}_2 + (y_3 + z_3) \mathbf{a}_3 =$	$ax_3 \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8d)	S I
B₆	$-x_3 \mathbf{a}_1 - (y_3 + z_3) \mathbf{a}_2 - (y_3 - z_3) \mathbf{a}_3 =$	$-ax_3 \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8d)	S I
B₇	$x_3 \mathbf{a}_1 - (y_3 + z_3 - \frac{1}{2}) \mathbf{a}_2 + (-y_3 + z_3 + \frac{1}{2}) \mathbf{a}_3 =$	$ax_3 \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8d)	S I
B₈	$-x_3 \mathbf{a}_1 + (y_3 - z_3 + \frac{1}{2}) \mathbf{a}_2 + (y_3 + z_3 + \frac{1}{2}) \mathbf{a}_3 =$	$-ax_3 \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}}$	(8d)	S I
B₉	$x_4 \mathbf{a}_1 + (y_4 - z_4) \mathbf{a}_2 + (y_4 + z_4) \mathbf{a}_3 =$	$ax_4 \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8d)	S II
B₁₀	$-x_4 \mathbf{a}_1 - (y_4 + z_4) \mathbf{a}_2 - (y_4 - z_4) \mathbf{a}_3 =$	$-ax_4 \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8d)	S II
B₁₁	$x_4 \mathbf{a}_1 - (y_4 + z_4 - \frac{1}{2}) \mathbf{a}_2 + (-y_4 + z_4 + \frac{1}{2}) \mathbf{a}_3 =$	$ax_4 \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8d)	S II
B₁₂	$-x_4 \mathbf{a}_1 + (y_4 - z_4 + \frac{1}{2}) \mathbf{a}_2 + (y_4 + z_4 + \frac{1}{2}) \mathbf{a}_3 =$	$-ax_4 \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}}$	(8d)	S II
B₁₃	$x_5 \mathbf{a}_1 + (y_5 - z_5) \mathbf{a}_2 + (y_5 + z_5) \mathbf{a}_3 =$	$ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8d)	Ta III
B₁₄	$-x_5 \mathbf{a}_1 - (y_5 + z_5) \mathbf{a}_2 - (y_5 - z_5) \mathbf{a}_3 =$	$-ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8d)	Ta III
B₁₅	$x_5 \mathbf{a}_1 - (y_5 + z_5 - \frac{1}{2}) \mathbf{a}_2 + (-y_5 + z_5 + \frac{1}{2}) \mathbf{a}_3 =$	$ax_5 \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8d)	Ta III
B₁₆	$-x_5 \mathbf{a}_1 + (y_5 - z_5 + \frac{1}{2}) \mathbf{a}_2 + (y_5 + z_5 + \frac{1}{2}) \mathbf{a}_3 =$	$-ax_5 \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}}$	(8d)	Ta III
B₁₇	$x_6 \mathbf{a}_1 + (y_6 - z_6) \mathbf{a}_2 + (y_6 + z_6) \mathbf{a}_3 =$	$ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8d)	Ta IV
B₁₈	$-x_6 \mathbf{a}_1 - (y_6 + z_6) \mathbf{a}_2 - (y_6 - z_6) \mathbf{a}_3 =$	$-ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8d)	Ta IV
B₁₉	$x_6 \mathbf{a}_1 - (y_6 + z_6 - \frac{1}{2}) \mathbf{a}_2 + (-y_6 + z_6 + \frac{1}{2}) \mathbf{a}_3 =$	$ax_6 \hat{\mathbf{x}} - b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8d)	Ta IV
B₂₀	$-x_6 \mathbf{a}_1 + (y_6 - z_6 + \frac{1}{2}) \mathbf{a}_2 + (y_6 + z_6 + \frac{1}{2}) \mathbf{a}_3 =$	$-ax_6 \hat{\mathbf{x}} + b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}}$	(8d)	Ta IV

References

- [1] S. J. Kim, K. S. Nanjundaswamy, and T. Hughbanks, *Single-crystal structure of tantalum sulfide (Ta_3S_2). Structure and bonding in the Ta_6S_n ($n = 1,3,4,5?$) pentagonal-antiprismatic chain compounds*, Inorg. Chem. **30**, 159–164 (1991), doi:10.1021/ic00002a004.

Found in

- [1] P. Villars and K. Cenzual, *Pearson's Crystal Data – Crystal Structure Database for Inorganic Compounds* (2013). ASM International.