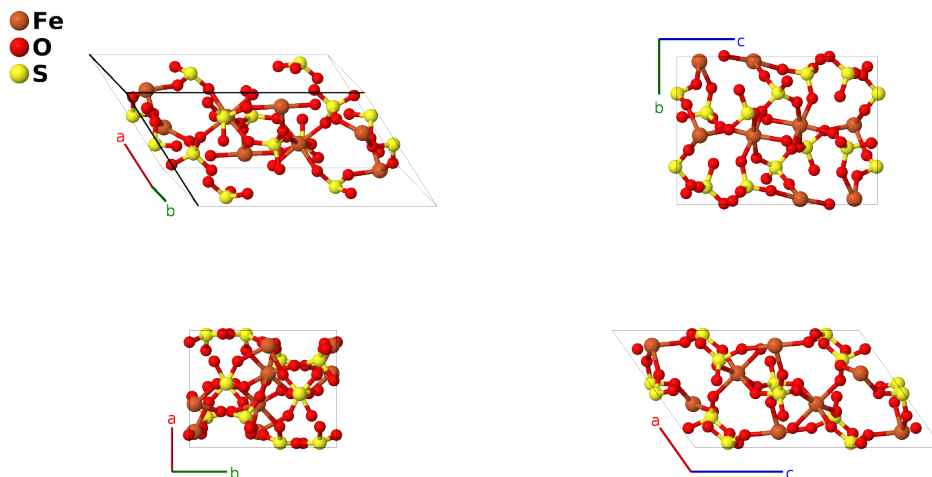


Monoclinic $\text{Fe}_2(\text{SO}_4)_3$ Structure: A2B12C3_mP68_14_2e_12e_3e-001

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<https://afLOW.org/p/LK3Z>

https://afLOW.org/p/A2B12C3_mP68_14_2e_12e_3e-001

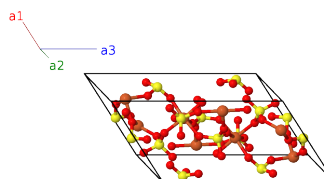


Prototype	$\text{Fe}_2\text{O}_{12}\text{S}_3$
AFLOW prototype label	A2B12C3_mP68_14_2e_12e_3e-001
ICSD	4301
Pearson symbol	mP68
Space group number	14
Space group symbol	$P2_1/c$
AFLOW prototype command	<pre>afLOW --proto=A2B12C3_mP68_14_2e_12e_3e-001 --params=a,b/a,c/a,beta,x1,y1,z1,x2,y2,z2,x3,y3,z3,x4,y4,z4,x5,y5,z5,x6,y6,z6,x7, y7,z7,x8,y8,z8,x9,y9,z9,x10,y10,z10,x11,y11,z11,x12,y12,z12,x13,y13,z13,x14,y14,z14,x15, y15,z15,x16,y16,z16,x17,y17,z17</pre>

- $\text{Fe}_2\text{O}_{12}\text{S}_3$ can also be found as the rhombohedral mineral mikasaite.

Simple Monoclinic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= a \hat{\mathbf{x}} \\ \mathbf{a}_2 &= b \hat{\mathbf{y}} \\ \mathbf{a}_3 &= c \cos \beta \hat{\mathbf{x}} + c \sin \beta \hat{\mathbf{z}} \end{aligned}$$



Basis vectors

	Lattice coordinates		Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	$= x_1 \mathbf{a}_1 + y_1 \mathbf{a}_2 + z_1 \mathbf{a}_3$	$=$	$(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} + by_1 \hat{\mathbf{y}} + cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Fe I
\mathbf{B}_2	$= -x_1 \mathbf{a}_1 + (y_1 + \frac{1}{2}) \mathbf{a}_2 - (z_1 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_1 + c(z_1 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_1 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_1 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Fe I
\mathbf{B}_3	$= -x_1 \mathbf{a}_1 - y_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$	$=$	$-(ax_1 + cz_1 \cos \beta) \hat{\mathbf{x}} - by_1 \hat{\mathbf{y}} - cz_1 \sin \beta \hat{\mathbf{z}}$	(4e)	Fe I
\mathbf{B}_4	$= x_1 \mathbf{a}_1 - (y_1 - \frac{1}{2}) \mathbf{a}_2 + (z_1 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_1 + c(z_1 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_1 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_1 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Fe I
\mathbf{B}_5	$= x_2 \mathbf{a}_1 + y_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$=$	$(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	Fe II
\mathbf{B}_6	$= -x_2 \mathbf{a}_1 + (y_2 + \frac{1}{2}) \mathbf{a}_2 - (z_2 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_2 + c(z_2 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_2 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_2 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Fe II
\mathbf{B}_7	$= -x_2 \mathbf{a}_1 - y_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$=$	$-(ax_2 + cz_2 \cos \beta) \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} - cz_2 \sin \beta \hat{\mathbf{z}}$	(4e)	Fe II
\mathbf{B}_8	$= x_2 \mathbf{a}_1 - (y_2 - \frac{1}{2}) \mathbf{a}_2 + (z_2 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_2 + c(z_2 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_2 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	Fe II
\mathbf{B}_9	$= x_3 \mathbf{a}_1 + y_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$=$	$(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	O I
\mathbf{B}_{10}	$= -x_3 \mathbf{a}_1 + (y_3 + \frac{1}{2}) \mathbf{a}_2 - (z_3 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_3 + c(z_3 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_3 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_3 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O I
\mathbf{B}_{11}	$= -x_3 \mathbf{a}_1 - y_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$=$	$-(ax_3 + cz_3 \cos \beta) \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} - cz_3 \sin \beta \hat{\mathbf{z}}$	(4e)	O I
\mathbf{B}_{12}	$= x_3 \mathbf{a}_1 - (y_3 - \frac{1}{2}) \mathbf{a}_2 + (z_3 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_3 + c(z_3 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_3 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O I
\mathbf{B}_{13}	$= x_4 \mathbf{a}_1 + y_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$=$	$(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	O II
\mathbf{B}_{14}	$= -x_4 \mathbf{a}_1 + (y_4 + \frac{1}{2}) \mathbf{a}_2 - (z_4 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_4 + c(z_4 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_4 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_4 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O II
\mathbf{B}_{15}	$= -x_4 \mathbf{a}_1 - y_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	$=$	$-(ax_4 + cz_4 \cos \beta) \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} - cz_4 \sin \beta \hat{\mathbf{z}}$	(4e)	O II
\mathbf{B}_{16}	$= x_4 \mathbf{a}_1 - (y_4 - \frac{1}{2}) \mathbf{a}_2 + (z_4 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_4 + c(z_4 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_4 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O II
\mathbf{B}_{17}	$= x_5 \mathbf{a}_1 + y_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	$=$	$(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	O III
\mathbf{B}_{18}	$= -x_5 \mathbf{a}_1 + (y_5 + \frac{1}{2}) \mathbf{a}_2 - (z_5 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_5 + c(z_5 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_5 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_5 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O III
\mathbf{B}_{19}	$= -x_5 \mathbf{a}_1 - y_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	$=$	$-(ax_5 + cz_5 \cos \beta) \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} - cz_5 \sin \beta \hat{\mathbf{z}}$	(4e)	O III
\mathbf{B}_{20}	$= x_5 \mathbf{a}_1 - (y_5 - \frac{1}{2}) \mathbf{a}_2 + (z_5 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_5 + c(z_5 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_5 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O III
\mathbf{B}_{21}	$= x_6 \mathbf{a}_1 + y_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	$=$	$(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	O IV
\mathbf{B}_{22}	$= -x_6 \mathbf{a}_1 + (y_6 + \frac{1}{2}) \mathbf{a}_2 - (z_6 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_6 + c(z_6 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_6 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_6 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O IV
\mathbf{B}_{23}	$= -x_6 \mathbf{a}_1 - y_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	$=$	$-(ax_6 + cz_6 \cos \beta) \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} - cz_6 \sin \beta \hat{\mathbf{z}}$	(4e)	O IV
\mathbf{B}_{24}	$= x_6 \mathbf{a}_1 - (y_6 - \frac{1}{2}) \mathbf{a}_2 + (z_6 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_6 + c(z_6 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_6 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O IV
\mathbf{B}_{25}	$= x_7 \mathbf{a}_1 + y_7 \mathbf{a}_2 + z_7 \mathbf{a}_3$	$=$	$(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \sin \beta \hat{\mathbf{z}}$	(4e)	O V
\mathbf{B}_{26}	$= -x_7 \mathbf{a}_1 + (y_7 + \frac{1}{2}) \mathbf{a}_2 - (z_7 - \frac{1}{2}) \mathbf{a}_3$	$=$	$-(ax_7 + c(z_7 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_7 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_7 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O V
\mathbf{B}_{27}	$= -x_7 \mathbf{a}_1 - y_7 \mathbf{a}_2 - z_7 \mathbf{a}_3$	$=$	$-(ax_7 + cz_7 \cos \beta) \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} - cz_7 \sin \beta \hat{\mathbf{z}}$	(4e)	O V
\mathbf{B}_{28}	$= x_7 \mathbf{a}_1 - (y_7 - \frac{1}{2}) \mathbf{a}_2 + (z_7 + \frac{1}{2}) \mathbf{a}_3$	$=$	$(ax_7 + c(z_7 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_7 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_7 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}$	(4e)	O V
\mathbf{B}_{29}	$= x_8 \mathbf{a}_1 + y_8 \mathbf{a}_2 + z_8 \mathbf{a}_3$	$=$	$(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \sin \beta \hat{\mathbf{z}}$	(4e)	O VI

$$\begin{aligned}
\mathbf{B}_{30} &= -x_8 \mathbf{a}_1 + \left(y_8 + \frac{1}{2}\right) \mathbf{a}_2 - (z_8 - \frac{1}{2}) \mathbf{a}_3 = -(ax_8 + c(z_8 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_8 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_8 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VI} \\
\mathbf{B}_{31} &= -x_8 \mathbf{a}_1 - y_8 \mathbf{a}_2 - z_8 \mathbf{a}_3 = -(ax_8 + cz_8 \cos \beta) \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} - cz_8 \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VI} \\
\mathbf{B}_{32} &= x_8 \mathbf{a}_1 - \left(y_8 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_8 + \frac{1}{2}\right) \mathbf{a}_3 = (ax_8 + c(z_8 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_8 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_8 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VI} \\
\mathbf{B}_{33} &= x_9 \mathbf{a}_1 + y_9 \mathbf{a}_2 + z_9 \mathbf{a}_3 = (ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VII} \\
\mathbf{B}_{34} &= -x_9 \mathbf{a}_1 + \left(y_9 + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_9 - \frac{1}{2}\right) \mathbf{a}_3 = -(ax_9 + c(z_9 - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_9 + \frac{1}{2}) \hat{\mathbf{y}} - c(z_9 - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VII} \\
\mathbf{B}_{35} &= -x_9 \mathbf{a}_1 - y_9 \mathbf{a}_2 - z_9 \mathbf{a}_3 = -(ax_9 + cz_9 \cos \beta) \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} - cz_9 \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VII} \\
\mathbf{B}_{36} &= x_9 \mathbf{a}_1 - \left(y_9 - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_9 + \frac{1}{2}\right) \mathbf{a}_3 = (ax_9 + c(z_9 + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_9 - \frac{1}{2}) \hat{\mathbf{y}} + c(z_9 + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VII} \\
\mathbf{B}_{37} &= x_{10} \mathbf{a}_1 + y_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3 = (ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} + by_{10} \hat{\mathbf{y}} + cz_{10} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VIII} \\
\mathbf{B}_{38} &= -x_{10} \mathbf{a}_1 + \left(y_{10} + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_{10} - \frac{1}{2}\right) \mathbf{a}_3 = -(ax_{10} + c(z_{10} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{10} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{10} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VIII} \\
\mathbf{B}_{39} &= -x_{10} \mathbf{a}_1 - y_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3 = -(ax_{10} + cz_{10} \cos \beta) \hat{\mathbf{x}} - by_{10} \hat{\mathbf{y}} - cz_{10} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VIII} \\
\mathbf{B}_{40} &= x_{10} \mathbf{a}_1 - \left(y_{10} - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_{10} + \frac{1}{2}\right) \mathbf{a}_3 = (ax_{10} + c(z_{10} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{10} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{10} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O VIII} \\
\mathbf{B}_{41} &= x_{11} \mathbf{a}_1 + y_{11} \mathbf{a}_2 + z_{11} \mathbf{a}_3 = (ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + by_{11} \hat{\mathbf{y}} + cz_{11} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O IX} \\
\mathbf{B}_{42} &= -x_{11} \mathbf{a}_1 + \left(y_{11} + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_{11} - \frac{1}{2}\right) \mathbf{a}_3 = -(ax_{11} + c(z_{11} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{11} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{11} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O IX} \\
\mathbf{B}_{43} &= -x_{11} \mathbf{a}_1 - y_{11} \mathbf{a}_2 - z_{11} \mathbf{a}_3 = -(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} - by_{11} \hat{\mathbf{y}} - cz_{11} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O IX} \\
\mathbf{B}_{44} &= x_{11} \mathbf{a}_1 - \left(y_{11} - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_{11} + \frac{1}{2}\right) \mathbf{a}_3 = (ax_{11} + c(z_{11} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{11} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{11} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O IX} \\
\mathbf{B}_{45} &= x_{12} \mathbf{a}_1 + y_{12} \mathbf{a}_2 + z_{12} \mathbf{a}_3 = (ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} + by_{12} \hat{\mathbf{y}} + cz_{12} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O X} \\
\mathbf{B}_{46} &= -x_{12} \mathbf{a}_1 + \left(y_{12} + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_{12} - \frac{1}{2}\right) \mathbf{a}_3 = -(ax_{12} + c(z_{12} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{12} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{12} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O X} \\
\mathbf{B}_{47} &= -x_{12} \mathbf{a}_1 - y_{12} \mathbf{a}_2 - z_{12} \mathbf{a}_3 = -(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} - by_{12} \hat{\mathbf{y}} - cz_{12} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O X} \\
\mathbf{B}_{48} &= x_{12} \mathbf{a}_1 - \left(y_{12} - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_{12} + \frac{1}{2}\right) \mathbf{a}_3 = (ax_{12} + c(z_{12} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{12} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{12} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O X} \\
\mathbf{B}_{49} &= x_{13} \mathbf{a}_1 + y_{13} \mathbf{a}_2 + z_{13} \mathbf{a}_3 = (ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + by_{13} \hat{\mathbf{y}} + cz_{13} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O XI} \\
\mathbf{B}_{50} &= -x_{13} \mathbf{a}_1 + \left(y_{13} + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_{13} - \frac{1}{2}\right) \mathbf{a}_3 = -(ax_{13} + c(z_{13} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{13} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{13} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O XI} \\
\mathbf{B}_{51} &= -x_{13} \mathbf{a}_1 - y_{13} \mathbf{a}_2 - z_{13} \mathbf{a}_3 = -(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} - by_{13} \hat{\mathbf{y}} - cz_{13} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O XI} \\
\mathbf{B}_{52} &= x_{13} \mathbf{a}_1 - \left(y_{13} - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_{13} + \frac{1}{2}\right) \mathbf{a}_3 = (ax_{13} + c(z_{13} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{13} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{13} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O XI} \\
\mathbf{B}_{53} &= x_{14} \mathbf{a}_1 + y_{14} \mathbf{a}_2 + z_{14} \mathbf{a}_3 = (ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} + by_{14} \hat{\mathbf{y}} + cz_{14} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O XII} \\
\mathbf{B}_{54} &= -x_{14} \mathbf{a}_1 + \left(y_{14} + \frac{1}{2}\right) \mathbf{a}_2 - \left(z_{14} - \frac{1}{2}\right) \mathbf{a}_3 = -(ax_{14} + c(z_{14} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + b(y_{14} + \frac{1}{2}) \hat{\mathbf{y}} - c(z_{14} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O XII} \\
\mathbf{B}_{55} &= -x_{14} \mathbf{a}_1 - y_{14} \mathbf{a}_2 - z_{14} \mathbf{a}_3 = -(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} - by_{14} \hat{\mathbf{y}} - cz_{14} \sin \beta \hat{\mathbf{z}} & (4e) & \text{O XII} \\
\mathbf{B}_{56} &= x_{14} \mathbf{a}_1 - \left(y_{14} - \frac{1}{2}\right) \mathbf{a}_2 + \left(z_{14} + \frac{1}{2}\right) \mathbf{a}_3 = (ax_{14} + c(z_{14} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - b(y_{14} - \frac{1}{2}) \hat{\mathbf{y}} + c(z_{14} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} & (4e) & \text{O XII}
\end{aligned}$$

$$\begin{aligned}
\mathbf{B}_{57} &= x_{15} \mathbf{a}_1 + y_{15} \mathbf{a}_2 + z_{15} \mathbf{a}_3 &= (ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} + by_{15} \hat{\mathbf{y}} + cz_{15} \sin \beta \hat{\mathbf{z}} &(4e) & \text{S I} \\
\mathbf{B}_{58} &= -x_{15} \mathbf{a}_1 + (y_{15} + \frac{1}{2}) \mathbf{a}_2 - &= - (ax_{15} + c (z_{15} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + &(4e) & \text{S I} \\
& (z_{15} - \frac{1}{2}) \mathbf{a}_3 & b (y_{15} + \frac{1}{2}) \hat{\mathbf{y}} - c (z_{15} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{59} &= -x_{15} \mathbf{a}_1 - y_{15} \mathbf{a}_2 - z_{15} \mathbf{a}_3 &= - (ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} - by_{15} \hat{\mathbf{y}} - &(4e) & \text{S I} \\
& & cz_{15} \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{60} &= x_{15} \mathbf{a}_1 - (y_{15} - \frac{1}{2}) \mathbf{a}_2 + &= (ax_{15} + c (z_{15} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - &(4e) & \text{S I} \\
& (z_{15} + \frac{1}{2}) \mathbf{a}_3 & b (y_{15} - \frac{1}{2}) \hat{\mathbf{y}} + c (z_{15} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{61} &= x_{16} \mathbf{a}_1 + y_{16} \mathbf{a}_2 + z_{16} \mathbf{a}_3 &= (ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} + by_{16} \hat{\mathbf{y}} + cz_{16} \sin \beta \hat{\mathbf{z}} &(4e) & \text{S II} \\
\mathbf{B}_{62} &= -x_{16} \mathbf{a}_1 + (y_{16} + \frac{1}{2}) \mathbf{a}_2 - &= - (ax_{16} + c (z_{16} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + &(4e) & \text{S II} \\
& (z_{16} - \frac{1}{2}) \mathbf{a}_3 & b (y_{16} + \frac{1}{2}) \hat{\mathbf{y}} - c (z_{16} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{63} &= -x_{16} \mathbf{a}_1 - y_{16} \mathbf{a}_2 - z_{16} \mathbf{a}_3 &= - (ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} - by_{16} \hat{\mathbf{y}} - &(4e) & \text{S II} \\
& & cz_{16} \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{64} &= x_{16} \mathbf{a}_1 - (y_{16} - \frac{1}{2}) \mathbf{a}_2 + &= (ax_{16} + c (z_{16} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - &(4e) & \text{S II} \\
& (z_{16} + \frac{1}{2}) \mathbf{a}_3 & b (y_{16} - \frac{1}{2}) \hat{\mathbf{y}} + c (z_{16} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{65} &= x_{17} \mathbf{a}_1 + y_{17} \mathbf{a}_2 + z_{17} \mathbf{a}_3 &= (ax_{17} + cz_{17} \cos \beta) \hat{\mathbf{x}} + by_{17} \hat{\mathbf{y}} + cz_{17} \sin \beta \hat{\mathbf{z}} &(4e) & \text{S III} \\
\mathbf{B}_{66} &= -x_{17} \mathbf{a}_1 + (y_{17} + \frac{1}{2}) \mathbf{a}_2 - &= - (ax_{17} + c (z_{17} - \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} + &(4e) & \text{S III} \\
& (z_{17} - \frac{1}{2}) \mathbf{a}_3 & b (y_{17} + \frac{1}{2}) \hat{\mathbf{y}} - c (z_{17} - \frac{1}{2}) \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{67} &= -x_{17} \mathbf{a}_1 - y_{17} \mathbf{a}_2 - z_{17} \mathbf{a}_3 &= - (ax_{17} + cz_{17} \cos \beta) \hat{\mathbf{x}} - by_{17} \hat{\mathbf{y}} - &(4e) & \text{S III} \\
& & cz_{17} \sin \beta \hat{\mathbf{z}} \\
\mathbf{B}_{68} &= x_{17} \mathbf{a}_1 - (y_{17} - \frac{1}{2}) \mathbf{a}_2 + &= (ax_{17} + c (z_{17} + \frac{1}{2}) \cos \beta) \hat{\mathbf{x}} - &(4e) & \text{S III} \\
& (z_{17} + \frac{1}{2}) \mathbf{a}_3 & b (y_{17} - \frac{1}{2}) \hat{\mathbf{y}} + c (z_{17} + \frac{1}{2}) \sin \beta \hat{\mathbf{z}}
\end{aligned}$$

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