

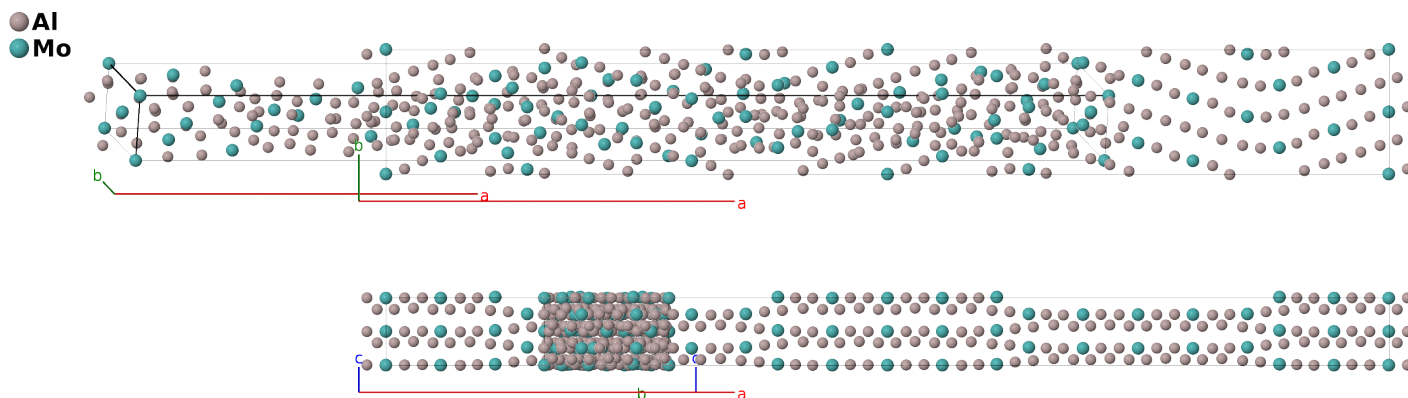
Al₂₂Mo₅ Structure:

A22B5_oF216_43_11b_a2b-001

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<https://aflow.org/p/15LF>

https://aflow.org/p/A22B5_oF216_43_11b_a2b-001

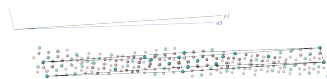


| | |
|-------------------------|---|
| Prototype | Al ₂₂ Mo ₅ |
| AFLOW prototype label | A22B5_oF216_43_11b_a2b-001 |
| ICSD | 400888 |
| Pearson symbol | oF216 |
| Space group number | 43 |
| Space group symbol | <i>Fdd2</i> |
| AFLOW prototype command | <code>aflow --proto=A22B5_oF216_43_11b_a2b-001</code> <code>--params=a, b/a, c/a, z₁, x₂, y₂, z₂, x₃, y₃, z₃, x₄, y₄, z₄, x₅, y₅, z₅, x₆, y₆, z₆, x₇, y₇, z₇, x₈, y₈, z₈, x₉, y₉, z₉, x₁₀, y₁₀, z₁₀, x₁₁, y₁₁, z₁₁, x₁₂, y₁₂, z₁₂, x₁₃, y₁₃, z₁₃, x₁₄, y₁₄, z₁₄</code> |

- Space group *Fdd2* #43 allows an arbitrary choice of the origin of the *z*-axis. Here we follow (Grin, 1995) and set $z_1 = 0$ for the Mo-I atom.

Face-centered Orthorhombic primitive vectors

$$\begin{aligned} \mathbf{a}_1 &= \frac{1}{2}b \hat{\mathbf{y}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_2 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}c \hat{\mathbf{z}} \\ \mathbf{a}_3 &= \frac{1}{2}a \hat{\mathbf{x}} + \frac{1}{2}b \hat{\mathbf{y}} \end{aligned}$$



Basis vectors

| | Lattice coordinates | | Cartesian coordinates | Wyckoff position | Atom type |
|----------------|--|-----|-------------------------|------------------|-----------|
| \mathbf{B}_1 | $= z_1 \mathbf{a}_1 + z_1 \mathbf{a}_2 - z_1 \mathbf{a}_3$ | $=$ | $cz_1 \hat{\mathbf{z}}$ | (8a) | Mo I |

$$\begin{aligned}
\mathbf{B}_2 &= \begin{pmatrix} (z_1 + \frac{1}{4}) \mathbf{a}_1 + (z_1 + \frac{1}{4}) \mathbf{a}_2 - \\ (z_1 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = \frac{1}{4}a \hat{\mathbf{x}} + \frac{1}{4}b \hat{\mathbf{y}} + c(z_1 + \frac{1}{4}) \hat{\mathbf{z}} & (8a) & \text{Mo I} \\
\mathbf{B}_3 &= \begin{pmatrix} (-x_2 + y_2 + z_2) \mathbf{a}_1 + \\ (x_2 - y_2 + z_2) \mathbf{a}_2 + \\ (x_2 + y_2 - z_2) \mathbf{a}_3 \end{pmatrix} = ax_2 \hat{\mathbf{x}} + by_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}} & (16b) & \text{Al I} \\
\mathbf{B}_4 &= \begin{pmatrix} (x_2 - y_2 + z_2) \mathbf{a}_1 + \\ (-x_2 + y_2 + z_2) \mathbf{a}_2 - \\ (x_2 + y_2 + z_2) \mathbf{a}_3 \end{pmatrix} = -ax_2 \hat{\mathbf{x}} - by_2 \hat{\mathbf{y}} + cz_2 \hat{\mathbf{z}} & (16b) & \text{Al I} \\
\mathbf{B}_5 &= \begin{pmatrix} -(x_2 + y_2 - z_2 - \frac{1}{4}) \mathbf{a}_1 + \\ (x_2 + y_2 + z_2 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_2 - y_2 - z_2 + \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = a(x_2 + \frac{1}{4}) \hat{\mathbf{x}} - b(y_2 - \frac{1}{4}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al I} \\
\mathbf{B}_6 &= \begin{pmatrix} (x_2 + y_2 + z_2 + \frac{1}{4}) \mathbf{a}_1 - \\ (x_2 + y_2 - z_2 - \frac{1}{4}) \mathbf{a}_2 - \\ (x_2 - y_2 + z_2 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = -a(x_2 - \frac{1}{4}) \hat{\mathbf{x}} + b(y_2 + \frac{1}{4}) \hat{\mathbf{y}} + c(z_2 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al I} \\
\mathbf{B}_7 &= \begin{pmatrix} (-x_3 + y_3 + z_3) \mathbf{a}_1 + \\ (x_3 - y_3 + z_3) \mathbf{a}_2 + \\ (x_3 + y_3 - z_3) \mathbf{a}_3 \end{pmatrix} = ax_3 \hat{\mathbf{x}} + by_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}} & (16b) & \text{Al II} \\
\mathbf{B}_8 &= \begin{pmatrix} (x_3 - y_3 + z_3) \mathbf{a}_1 + \\ (-x_3 + y_3 + z_3) \mathbf{a}_2 - \\ (x_3 + y_3 + z_3) \mathbf{a}_3 \end{pmatrix} = -ax_3 \hat{\mathbf{x}} - by_3 \hat{\mathbf{y}} + cz_3 \hat{\mathbf{z}} & (16b) & \text{Al II} \\
\mathbf{B}_9 &= \begin{pmatrix} -(x_3 + y_3 - z_3 - \frac{1}{4}) \mathbf{a}_1 + \\ (x_3 + y_3 + z_3 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_3 - y_3 - z_3 + \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = a(x_3 + \frac{1}{4}) \hat{\mathbf{x}} - b(y_3 - \frac{1}{4}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al II} \\
\mathbf{B}_{10} &= \begin{pmatrix} (x_3 + y_3 + z_3 + \frac{1}{4}) \mathbf{a}_1 - \\ (x_3 + y_3 - z_3 - \frac{1}{4}) \mathbf{a}_2 - \\ (x_3 - y_3 + z_3 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = -a(x_3 - \frac{1}{4}) \hat{\mathbf{x}} + b(y_3 + \frac{1}{4}) \hat{\mathbf{y}} + c(z_3 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al II} \\
\mathbf{B}_{11} &= \begin{pmatrix} (-x_4 + y_4 + z_4) \mathbf{a}_1 + \\ (x_4 - y_4 + z_4) \mathbf{a}_2 + \\ (x_4 + y_4 - z_4) \mathbf{a}_3 \end{pmatrix} = ax_4 \hat{\mathbf{x}} + by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}} & (16b) & \text{Al III} \\
\mathbf{B}_{12} &= \begin{pmatrix} (x_4 - y_4 + z_4) \mathbf{a}_1 + \\ (-x_4 + y_4 + z_4) \mathbf{a}_2 - \\ (x_4 + y_4 + z_4) \mathbf{a}_3 \end{pmatrix} = -ax_4 \hat{\mathbf{x}} - by_4 \hat{\mathbf{y}} + cz_4 \hat{\mathbf{z}} & (16b) & \text{Al III} \\
\mathbf{B}_{13} &= \begin{pmatrix} -(x_4 + y_4 - z_4 - \frac{1}{4}) \mathbf{a}_1 + \\ (x_4 + y_4 + z_4 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_4 - y_4 - z_4 + \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = a(x_4 + \frac{1}{4}) \hat{\mathbf{x}} - b(y_4 - \frac{1}{4}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al III} \\
\mathbf{B}_{14} &= \begin{pmatrix} (x_4 + y_4 + z_4 + \frac{1}{4}) \mathbf{a}_1 - \\ (x_4 + y_4 - z_4 - \frac{1}{4}) \mathbf{a}_2 - \\ (x_4 - y_4 + z_4 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = -a(x_4 - \frac{1}{4}) \hat{\mathbf{x}} + b(y_4 + \frac{1}{4}) \hat{\mathbf{y}} + c(z_4 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al III} \\
\mathbf{B}_{15} &= \begin{pmatrix} (-x_5 + y_5 + z_5) \mathbf{a}_1 + \\ (x_5 - y_5 + z_5) \mathbf{a}_2 + \\ (x_5 + y_5 - z_5) \mathbf{a}_3 \end{pmatrix} = ax_5 \hat{\mathbf{x}} + by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}} & (16b) & \text{Al IV} \\
\mathbf{B}_{16} &= \begin{pmatrix} (x_5 - y_5 + z_5) \mathbf{a}_1 + \\ (-x_5 + y_5 + z_5) \mathbf{a}_2 - \\ (x_5 + y_5 + z_5) \mathbf{a}_3 \end{pmatrix} = -ax_5 \hat{\mathbf{x}} - by_5 \hat{\mathbf{y}} + cz_5 \hat{\mathbf{z}} & (16b) & \text{Al IV} \\
\mathbf{B}_{17} &= \begin{pmatrix} -(x_5 + y_5 - z_5 - \frac{1}{4}) \mathbf{a}_1 + \\ (x_5 + y_5 + z_5 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_5 - y_5 - z_5 + \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = a(x_5 + \frac{1}{4}) \hat{\mathbf{x}} - b(y_5 - \frac{1}{4}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al IV} \\
\mathbf{B}_{18} &= \begin{pmatrix} (x_5 + y_5 + z_5 + \frac{1}{4}) \mathbf{a}_1 - \\ (x_5 + y_5 - z_5 - \frac{1}{4}) \mathbf{a}_2 - \\ (x_5 - y_5 + z_5 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} = -a(x_5 - \frac{1}{4}) \hat{\mathbf{x}} + b(y_5 + \frac{1}{4}) \hat{\mathbf{y}} + c(z_5 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al IV}
\end{aligned}$$

$$\begin{aligned}
\mathbf{B}_{19} &= \begin{pmatrix} (-x_6 + y_6 + z_6) \mathbf{a}_1 + \\ (x_6 - y_6 + z_6) \mathbf{a}_2 + \\ (x_6 + y_6 - z_6) \mathbf{a}_3 \end{pmatrix} &= & ax_6 \hat{\mathbf{x}} + by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16b) & \text{Al V} \\
\mathbf{B}_{20} &= \begin{pmatrix} (x_6 - y_6 + z_6) \mathbf{a}_1 + \\ (-x_6 + y_6 + z_6) \mathbf{a}_2 - \\ (x_6 + y_6 + z_6) \mathbf{a}_3 \end{pmatrix} &= & -ax_6 \hat{\mathbf{x}} - by_6 \hat{\mathbf{y}} + cz_6 \hat{\mathbf{z}} & (16b) & \text{Al V} \\
\mathbf{B}_{21} &= \begin{pmatrix} -(x_6 + y_6 - z_6 - \frac{1}{4}) \mathbf{a}_1 + \\ (x_6 + y_6 + z_6 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_6 - y_6 - z_6 + \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} &= & a(x_6 + \frac{1}{4}) \hat{\mathbf{x}} - b(y_6 - \frac{1}{4}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al V} \\
\mathbf{B}_{22} &= \begin{pmatrix} (x_6 + y_6 + z_6 + \frac{1}{4}) \mathbf{a}_1 - \\ (x_6 + y_6 - z_6 - \frac{1}{4}) \mathbf{a}_2 - \\ (x_6 - y_6 + z_6 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} &= & -a(x_6 - \frac{1}{4}) \hat{\mathbf{x}} + b(y_6 + \frac{1}{4}) \hat{\mathbf{y}} + c(z_6 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al V} \\
\mathbf{B}_{23} &= \begin{pmatrix} (-x_7 + y_7 + z_7) \mathbf{a}_1 + \\ (x_7 - y_7 + z_7) \mathbf{a}_2 + \\ (x_7 + y_7 - z_7) \mathbf{a}_3 \end{pmatrix} &= & ax_7 \hat{\mathbf{x}} + by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16b) & \text{Al VI} \\
\mathbf{B}_{24} &= \begin{pmatrix} (x_7 - y_7 + z_7) \mathbf{a}_1 + \\ (-x_7 + y_7 + z_7) \mathbf{a}_2 - \\ (x_7 + y_7 + z_7) \mathbf{a}_3 \end{pmatrix} &= & -ax_7 \hat{\mathbf{x}} - by_7 \hat{\mathbf{y}} + cz_7 \hat{\mathbf{z}} & (16b) & \text{Al VI} \\
\mathbf{B}_{25} &= \begin{pmatrix} -(x_7 + y_7 - z_7 - \frac{1}{4}) \mathbf{a}_1 + \\ (x_7 + y_7 + z_7 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_7 - y_7 - z_7 + \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} &= & a(x_7 + \frac{1}{4}) \hat{\mathbf{x}} - b(y_7 - \frac{1}{4}) \hat{\mathbf{y}} + c(z_7 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al VI} \\
\mathbf{B}_{26} &= \begin{pmatrix} (x_7 + y_7 + z_7 + \frac{1}{4}) \mathbf{a}_1 - \\ (x_7 + y_7 - z_7 - \frac{1}{4}) \mathbf{a}_2 - \\ (x_7 - y_7 + z_7 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} &= & -a(x_7 - \frac{1}{4}) \hat{\mathbf{x}} + b(y_7 + \frac{1}{4}) \hat{\mathbf{y}} + c(z_7 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al VI} \\
\mathbf{B}_{27} &= \begin{pmatrix} (-x_8 + y_8 + z_8) \mathbf{a}_1 + \\ (x_8 - y_8 + z_8) \mathbf{a}_2 + \\ (x_8 + y_8 - z_8) \mathbf{a}_3 \end{pmatrix} &= & ax_8 \hat{\mathbf{x}} + by_8 \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (16b) & \text{Al VII} \\
\mathbf{B}_{28} &= \begin{pmatrix} (x_8 - y_8 + z_8) \mathbf{a}_1 + \\ (-x_8 + y_8 + z_8) \mathbf{a}_2 - \\ (x_8 + y_8 + z_8) \mathbf{a}_3 \end{pmatrix} &= & -ax_8 \hat{\mathbf{x}} - by_8 \hat{\mathbf{y}} + cz_8 \hat{\mathbf{z}} & (16b) & \text{Al VII} \\
\mathbf{B}_{29} &= \begin{pmatrix} -(x_8 + y_8 - z_8 - \frac{1}{4}) \mathbf{a}_1 + \\ (x_8 + y_8 + z_8 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_8 - y_8 - z_8 + \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} &= & a(x_8 + \frac{1}{4}) \hat{\mathbf{x}} - b(y_8 - \frac{1}{4}) \hat{\mathbf{y}} + c(z_8 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al VII} \\
\mathbf{B}_{30} &= \begin{pmatrix} (x_8 + y_8 + z_8 + \frac{1}{4}) \mathbf{a}_1 - \\ (x_8 + y_8 - z_8 - \frac{1}{4}) \mathbf{a}_2 - \\ (x_8 - y_8 + z_8 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} &= & -a(x_8 - \frac{1}{4}) \hat{\mathbf{x}} + b(y_8 + \frac{1}{4}) \hat{\mathbf{y}} + c(z_8 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al VII} \\
\mathbf{B}_{31} &= \begin{pmatrix} (-x_9 + y_9 + z_9) \mathbf{a}_1 + \\ (x_9 - y_9 + z_9) \mathbf{a}_2 + \\ (x_9 + y_9 - z_9) \mathbf{a}_3 \end{pmatrix} &= & ax_9 \hat{\mathbf{x}} + by_9 \hat{\mathbf{y}} + cz_9 \hat{\mathbf{z}} & (16b) & \text{Al VIII} \\
\mathbf{B}_{32} &= \begin{pmatrix} (x_9 - y_9 + z_9) \mathbf{a}_1 + \\ (-x_9 + y_9 + z_9) \mathbf{a}_2 - \\ (x_9 + y_9 + z_9) \mathbf{a}_3 \end{pmatrix} &= & -ax_9 \hat{\mathbf{x}} - by_9 \hat{\mathbf{y}} + cz_9 \hat{\mathbf{z}} & (16b) & \text{Al VIII} \\
\mathbf{B}_{33} &= \begin{pmatrix} -(x_9 + y_9 - z_9 - \frac{1}{4}) \mathbf{a}_1 + \\ (x_9 + y_9 + z_9 + \frac{1}{4}) \mathbf{a}_2 + \\ (x_9 - y_9 - z_9 + \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} &= & a(x_9 + \frac{1}{4}) \hat{\mathbf{x}} - b(y_9 - \frac{1}{4}) \hat{\mathbf{y}} + c(z_9 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al VIII} \\
\mathbf{B}_{34} &= \begin{pmatrix} (x_9 + y_9 + z_9 + \frac{1}{4}) \mathbf{a}_1 - \\ (x_9 + y_9 - z_9 - \frac{1}{4}) \mathbf{a}_2 - \\ (x_9 - y_9 + z_9 - \frac{1}{4}) \mathbf{a}_3 \end{pmatrix} &= & -a(x_9 - \frac{1}{4}) \hat{\mathbf{x}} + b(y_9 + \frac{1}{4}) \hat{\mathbf{y}} + c(z_9 + \frac{1}{4}) \hat{\mathbf{z}} & (16b) & \text{Al VIII}
\end{aligned}$$

$$\mathbf{B}_{51} = \begin{pmatrix} -x_{14} + y_{14} + z_{14} \\ x_{14} - y_{14} + z_{14} \\ x_{14} + y_{14} - z_{14} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_{14} - y_{14} + z_{14} \\ -x_{14} + y_{14} + z_{14} \\ x_{14} + y_{14} - z_{14} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_{14} - y_{14} + z_{14} \\ -x_{14} + y_{14} + z_{14} \\ x_{14} + y_{14} - z_{14} \end{pmatrix} \mathbf{a}_3 = ax_{14} \hat{\mathbf{x}} + by_{14} \hat{\mathbf{y}} + cz_{14} \hat{\mathbf{z}} \quad (16b) \quad \text{Mo III}$$

$$\mathbf{B}_{52} = \begin{pmatrix} x_{14} - y_{14} + z_{14} \\ -x_{14} + y_{14} + z_{14} \\ x_{14} + y_{14} + z_{14} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_{14} - y_{14} + z_{14} \\ -x_{14} + y_{14} + z_{14} \\ x_{14} + y_{14} + z_{14} \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_{14} - y_{14} + z_{14} \\ -x_{14} + y_{14} + z_{14} \\ x_{14} + y_{14} + z_{14} \end{pmatrix} \mathbf{a}_3 = -ax_{14} \hat{\mathbf{x}} - by_{14} \hat{\mathbf{y}} + cz_{14} \hat{\mathbf{z}} \quad (16b) \quad \text{Mo III}$$

$$\mathbf{B}_{53} = -\begin{pmatrix} x_{14} + y_{14} - z_{14} - \frac{1}{4} \\ x_{14} + y_{14} + z_{14} + \frac{1}{4} \\ x_{14} - y_{14} - z_{14} + \frac{1}{4} \end{pmatrix} \mathbf{a}_1 + \begin{pmatrix} x_{14} + y_{14} + z_{14} + \frac{1}{4} \\ x_{14} + y_{14} + z_{14} + \frac{1}{4} \\ x_{14} - y_{14} - z_{14} + \frac{1}{4} \end{pmatrix} \mathbf{a}_2 + \begin{pmatrix} x_{14} + y_{14} + z_{14} + \frac{1}{4} \\ x_{14} + y_{14} + z_{14} + \frac{1}{4} \\ x_{14} - y_{14} - z_{14} + \frac{1}{4} \end{pmatrix} \mathbf{a}_3 = a \left(x_{14} + \frac{1}{4}\right) \hat{\mathbf{x}} - b \left(y_{14} - \frac{1}{4}\right) \hat{\mathbf{y}} + c \left(z_{14} + \frac{1}{4}\right) \hat{\mathbf{z}} \quad (16b) \quad \text{Mo III}$$

$$\mathbf{B}_{54} = \begin{pmatrix} x_{14} + y_{14} + z_{14} + \frac{1}{4} \\ x_{14} + y_{14} - z_{14} - \frac{1}{4} \\ x_{14} - y_{14} + z_{14} - \frac{1}{4} \end{pmatrix} \mathbf{a}_1 - \begin{pmatrix} x_{14} + y_{14} + z_{14} + \frac{1}{4} \\ x_{14} + y_{14} - z_{14} - \frac{1}{4} \\ x_{14} - y_{14} + z_{14} - \frac{1}{4} \end{pmatrix} \mathbf{a}_2 - \begin{pmatrix} x_{14} + y_{14} + z_{14} + \frac{1}{4} \\ x_{14} + y_{14} - z_{14} - \frac{1}{4} \\ x_{14} - y_{14} + z_{14} - \frac{1}{4} \end{pmatrix} \mathbf{a}_3 = -a \left(x_{14} - \frac{1}{4}\right) \hat{\mathbf{x}} + b \left(y_{14} + \frac{1}{4}\right) \hat{\mathbf{y}} + c \left(z_{14} + \frac{1}{4}\right) \hat{\mathbf{z}} \quad (16b) \quad \text{Mo III}$$

References

- [1] Y. N. Grin, M. Ellner, K. Peters, and J. C. Schuster, *The crystal structures of $\text{Mo}_4\text{Al}_{17}$ and $\text{Mo}_5\text{Al}_{22}$* , *Z. Kristallogr.* **210**, 96–99 (1995), doi:10.1524/zkri.1995.210.2.96.