

Monoclinic Nb₁₂O₂₉ Structure:

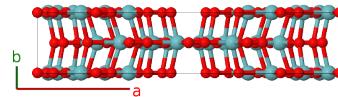
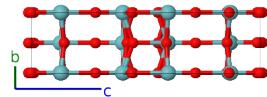
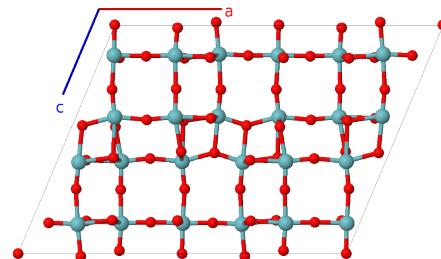
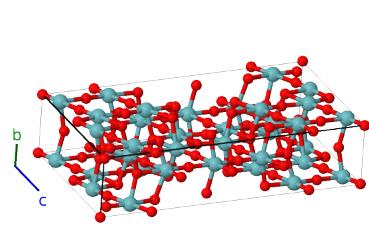
A12B29_mC82_12_6i_a14i-001

Cite this page as: H. Eckert, S. Divilov, A. Zettel, M. J. Mehl, D. Hicks, and S. Curtarolo, *The AFLOW Library of Crystallographic Prototypes: Part 4*. In preparation.

<https://aflow.org/p/BPW1>

https://aflow.org/p/A12B29_mC82_12_6i_a14i-001

● Nb
● O



Prototype	Nb ₁₂ O ₂₉
AFLOW prototype label	A12B29_mC82_12_6i_a14i-001
ICSD	24111
Pearson symbol	mC82
Space group number	12
Space group symbol	$C2/m$
AFLOW prototype command	<pre>aflow --proto=A12B29_mC82_12_6i_a14i-001 --params=a,b/a,c/a,\beta,x2,z2,x3,z3,x4,z4,x5,z5,x6,z6,x7,z7,x8,z8,x9,z9,x10,z10, x11,z11,x12,z12,x13,z13,x14,z14,x15,z15,x16,z16,x17,z17,x18,z18,x19,z19,x20,z20,x21,z21</pre>

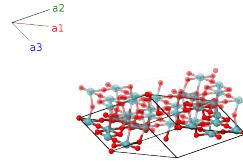
Other compounds with this structure

Ti₂Nb₁₀O₂₉

- Nb₁₂O₂₉ is known to exist in at least two phases (Norin, 1963; Norin, 1966):
 - a monoclinic phase (this structure) and
 - an orthorhombic phase.
- (Wadsley, 1961) earlier found that both known phases of Ti₂Nb₁₂O₂₉ are isostructural with the corresponding Nb₁₂O₂₉ phase, but as the titanium and niobium atoms are alloyed on the same site we use the binary Nb₁₂O₂₉ as the prototype.
- (Norin, 1966) gives the structure of orthorhombic Nb₁₂O₂₉ in the A2/a setting of space group #15, with the origin at -1 on the a-glide plane. When we checked this with FINDSYM we found that the structure could be placed in space group C2/m #12 with a unit cell half that found by (Norin, 1966), and close to the dimensions of the cell found in (Wadsley, 1961) and (Norin, 1963).

Base-centered Monoclinic primitive vectors

$$\begin{aligned}\mathbf{a}_1 &= \frac{1}{2}a\hat{\mathbf{x}} - \frac{1}{2}b\hat{\mathbf{y}} \\ \mathbf{a}_2 &= \frac{1}{2}a\hat{\mathbf{x}} + \frac{1}{2}b\hat{\mathbf{y}} \\ \mathbf{a}_3 &= c\cos\beta\hat{\mathbf{x}} + c\sin\beta\hat{\mathbf{z}}\end{aligned}$$



Basis vectors

	Lattice coordinates	Cartesian coordinates	Wyckoff position	Atom type
\mathbf{B}_1	0	0	(2a)	O I
\mathbf{B}_2	$x_2 \mathbf{a}_1 + x_2 \mathbf{a}_2 + z_2 \mathbf{a}_3$	$(ax_2 + cz_2 \cos\beta)\hat{\mathbf{x}} + cz_2 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb I
\mathbf{B}_3	$-x_2 \mathbf{a}_1 - x_2 \mathbf{a}_2 - z_2 \mathbf{a}_3$	$-(ax_2 + cz_2 \cos\beta)\hat{\mathbf{x}} - cz_2 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb I
\mathbf{B}_4	$x_3 \mathbf{a}_1 + x_3 \mathbf{a}_2 + z_3 \mathbf{a}_3$	$(ax_3 + cz_3 \cos\beta)\hat{\mathbf{x}} + cz_3 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb II
\mathbf{B}_5	$-x_3 \mathbf{a}_1 - x_3 \mathbf{a}_2 - z_3 \mathbf{a}_3$	$-(ax_3 + cz_3 \cos\beta)\hat{\mathbf{x}} - cz_3 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb II
\mathbf{B}_6	$x_4 \mathbf{a}_1 + x_4 \mathbf{a}_2 + z_4 \mathbf{a}_3$	$(ax_4 + cz_4 \cos\beta)\hat{\mathbf{x}} + cz_4 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb III
\mathbf{B}_7	$-x_4 \mathbf{a}_1 - x_4 \mathbf{a}_2 - z_4 \mathbf{a}_3$	$-(ax_4 + cz_4 \cos\beta)\hat{\mathbf{x}} - cz_4 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb III
\mathbf{B}_8	$x_5 \mathbf{a}_1 + x_5 \mathbf{a}_2 + z_5 \mathbf{a}_3$	$(ax_5 + cz_5 \cos\beta)\hat{\mathbf{x}} + cz_5 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb IV
\mathbf{B}_9	$-x_5 \mathbf{a}_1 - x_5 \mathbf{a}_2 - z_5 \mathbf{a}_3$	$-(ax_5 + cz_5 \cos\beta)\hat{\mathbf{x}} - cz_5 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb IV
\mathbf{B}_{10}	$x_6 \mathbf{a}_1 + x_6 \mathbf{a}_2 + z_6 \mathbf{a}_3$	$(ax_6 + cz_6 \cos\beta)\hat{\mathbf{x}} + cz_6 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb V
\mathbf{B}_{11}	$-x_6 \mathbf{a}_1 - x_6 \mathbf{a}_2 - z_6 \mathbf{a}_3$	$-(ax_6 + cz_6 \cos\beta)\hat{\mathbf{x}} - cz_6 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb V
\mathbf{B}_{12}	$x_7 \mathbf{a}_1 + x_7 \mathbf{a}_2 + z_7 \mathbf{a}_3$	$(ax_7 + cz_7 \cos\beta)\hat{\mathbf{x}} + cz_7 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb VI
\mathbf{B}_{13}	$-x_7 \mathbf{a}_1 - x_7 \mathbf{a}_2 - z_7 \mathbf{a}_3$	$-(ax_7 + cz_7 \cos\beta)\hat{\mathbf{x}} - cz_7 \sin\beta\hat{\mathbf{z}}$	(4i)	Nb VI
\mathbf{B}_{14}	$x_8 \mathbf{a}_1 + x_8 \mathbf{a}_2 + z_8 \mathbf{a}_3$	$(ax_8 + cz_8 \cos\beta)\hat{\mathbf{x}} + cz_8 \sin\beta\hat{\mathbf{z}}$	(4i)	O II
\mathbf{B}_{15}	$-x_8 \mathbf{a}_1 - x_8 \mathbf{a}_2 - z_8 \mathbf{a}_3$	$-(ax_8 + cz_8 \cos\beta)\hat{\mathbf{x}} - cz_8 \sin\beta\hat{\mathbf{z}}$	(4i)	O II
\mathbf{B}_{16}	$x_9 \mathbf{a}_1 + x_9 \mathbf{a}_2 + z_9 \mathbf{a}_3$	$(ax_9 + cz_9 \cos\beta)\hat{\mathbf{x}} + cz_9 \sin\beta\hat{\mathbf{z}}$	(4i)	O III
\mathbf{B}_{17}	$-x_9 \mathbf{a}_1 - x_9 \mathbf{a}_2 - z_9 \mathbf{a}_3$	$-(ax_9 + cz_9 \cos\beta)\hat{\mathbf{x}} - cz_9 \sin\beta\hat{\mathbf{z}}$	(4i)	O III
\mathbf{B}_{18}	$x_{10} \mathbf{a}_1 + x_{10} \mathbf{a}_2 + z_{10} \mathbf{a}_3$	$(ax_{10} + cz_{10} \cos\beta)\hat{\mathbf{x}} + cz_{10} \sin\beta\hat{\mathbf{z}}$	(4i)	O IV
\mathbf{B}_{19}	$-x_{10} \mathbf{a}_1 - x_{10} \mathbf{a}_2 - z_{10} \mathbf{a}_3$	$-(ax_{10} + cz_{10} \cos\beta)\hat{\mathbf{x}} - cz_{10} \sin\beta\hat{\mathbf{z}}$	(4i)	O IV

\mathbf{B}_{20}	$x_{11} \mathbf{a}_1 + x_{11} \mathbf{a}_2 + z_{11} \mathbf{a}_3$	$=$	$(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} + cz_{11} \sin \beta \hat{\mathbf{z}}$	(4i)	O V
\mathbf{B}_{21}	$-x_{11} \mathbf{a}_1 - x_{11} \mathbf{a}_2 - z_{11} \mathbf{a}_3$	$=$	$-(ax_{11} + cz_{11} \cos \beta) \hat{\mathbf{x}} - cz_{11} \sin \beta \hat{\mathbf{z}}$	(4i)	O V
\mathbf{B}_{22}	$x_{12} \mathbf{a}_1 + x_{12} \mathbf{a}_2 + z_{12} \mathbf{a}_3$	$=$	$(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} + cz_{12} \sin \beta \hat{\mathbf{z}}$	(4i)	O VI
\mathbf{B}_{23}	$-x_{12} \mathbf{a}_1 - x_{12} \mathbf{a}_2 - z_{12} \mathbf{a}_3$	$=$	$-(ax_{12} + cz_{12} \cos \beta) \hat{\mathbf{x}} - cz_{12} \sin \beta \hat{\mathbf{z}}$	(4i)	O VI
\mathbf{B}_{24}	$x_{13} \mathbf{a}_1 + x_{13} \mathbf{a}_2 + z_{13} \mathbf{a}_3$	$=$	$(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} + cz_{13} \sin \beta \hat{\mathbf{z}}$	(4i)	O VII
\mathbf{B}_{25}	$-x_{13} \mathbf{a}_1 - x_{13} \mathbf{a}_2 - z_{13} \mathbf{a}_3$	$=$	$-(ax_{13} + cz_{13} \cos \beta) \hat{\mathbf{x}} - cz_{13} \sin \beta \hat{\mathbf{z}}$	(4i)	O VII
\mathbf{B}_{26}	$x_{14} \mathbf{a}_1 + x_{14} \mathbf{a}_2 + z_{14} \mathbf{a}_3$	$=$	$(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} + cz_{14} \sin \beta \hat{\mathbf{z}}$	(4i)	O VIII
\mathbf{B}_{27}	$-x_{14} \mathbf{a}_1 - x_{14} \mathbf{a}_2 - z_{14} \mathbf{a}_3$	$=$	$-(ax_{14} + cz_{14} \cos \beta) \hat{\mathbf{x}} - cz_{14} \sin \beta \hat{\mathbf{z}}$	(4i)	O VIII
\mathbf{B}_{28}	$x_{15} \mathbf{a}_1 + x_{15} \mathbf{a}_2 + z_{15} \mathbf{a}_3$	$=$	$(ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} + cz_{15} \sin \beta \hat{\mathbf{z}}$	(4i)	O IX
\mathbf{B}_{29}	$-x_{15} \mathbf{a}_1 - x_{15} \mathbf{a}_2 - z_{15} \mathbf{a}_3$	$=$	$-(ax_{15} + cz_{15} \cos \beta) \hat{\mathbf{x}} - cz_{15} \sin \beta \hat{\mathbf{z}}$	(4i)	O IX
\mathbf{B}_{30}	$x_{16} \mathbf{a}_1 + x_{16} \mathbf{a}_2 + z_{16} \mathbf{a}_3$	$=$	$(ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} + cz_{16} \sin \beta \hat{\mathbf{z}}$	(4i)	O X
\mathbf{B}_{31}	$-x_{16} \mathbf{a}_1 - x_{16} \mathbf{a}_2 - z_{16} \mathbf{a}_3$	$=$	$-(ax_{16} + cz_{16} \cos \beta) \hat{\mathbf{x}} - cz_{16} \sin \beta \hat{\mathbf{z}}$	(4i)	O X
\mathbf{B}_{32}	$x_{17} \mathbf{a}_1 + x_{17} \mathbf{a}_2 + z_{17} \mathbf{a}_3$	$=$	$(ax_{17} + cz_{17} \cos \beta) \hat{\mathbf{x}} + cz_{17} \sin \beta \hat{\mathbf{z}}$	(4i)	O XI
\mathbf{B}_{33}	$-x_{17} \mathbf{a}_1 - x_{17} \mathbf{a}_2 - z_{17} \mathbf{a}_3$	$=$	$-(ax_{17} + cz_{17} \cos \beta) \hat{\mathbf{x}} - cz_{17} \sin \beta \hat{\mathbf{z}}$	(4i)	O XI
\mathbf{B}_{34}	$x_{18} \mathbf{a}_1 + x_{18} \mathbf{a}_2 + z_{18} \mathbf{a}_3$	$=$	$(ax_{18} + cz_{18} \cos \beta) \hat{\mathbf{x}} + cz_{18} \sin \beta \hat{\mathbf{z}}$	(4i)	O XII
\mathbf{B}_{35}	$-x_{18} \mathbf{a}_1 - x_{18} \mathbf{a}_2 - z_{18} \mathbf{a}_3$	$=$	$-(ax_{18} + cz_{18} \cos \beta) \hat{\mathbf{x}} - cz_{18} \sin \beta \hat{\mathbf{z}}$	(4i)	O XII
\mathbf{B}_{36}	$x_{19} \mathbf{a}_1 + x_{19} \mathbf{a}_2 + z_{19} \mathbf{a}_3$	$=$	$(ax_{19} + cz_{19} \cos \beta) \hat{\mathbf{x}} + cz_{19} \sin \beta \hat{\mathbf{z}}$	(4i)	O XIII
\mathbf{B}_{37}	$-x_{19} \mathbf{a}_1 - x_{19} \mathbf{a}_2 - z_{19} \mathbf{a}_3$	$=$	$-(ax_{19} + cz_{19} \cos \beta) \hat{\mathbf{x}} - cz_{19} \sin \beta \hat{\mathbf{z}}$	(4i)	O XIII
\mathbf{B}_{38}	$x_{20} \mathbf{a}_1 + x_{20} \mathbf{a}_2 + z_{20} \mathbf{a}_3$	$=$	$(ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} + cz_{20} \sin \beta \hat{\mathbf{z}}$	(4i)	O XIV
\mathbf{B}_{39}	$-x_{20} \mathbf{a}_1 - x_{20} \mathbf{a}_2 - z_{20} \mathbf{a}_3$	$=$	$-(ax_{20} + cz_{20} \cos \beta) \hat{\mathbf{x}} - cz_{20} \sin \beta \hat{\mathbf{z}}$	(4i)	O XIV
\mathbf{B}_{40}	$x_{21} \mathbf{a}_1 + x_{21} \mathbf{a}_2 + z_{21} \mathbf{a}_3$	$=$	$(ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} + cz_{21} \sin \beta \hat{\mathbf{z}}$	(4i)	O XV
\mathbf{B}_{41}	$-x_{21} \mathbf{a}_1 - x_{21} \mathbf{a}_2 - z_{21} \mathbf{a}_3$	$=$	$-(ax_{21} + cz_{21} \cos \beta) \hat{\mathbf{x}} - cz_{21} \sin \beta \hat{\mathbf{z}}$	(4i)	O XV

References

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- [3] A. D. Wadsley, *Mixed oxides of titanium and niobium. II. The crystal structures of the dimorphic forms $Ti_2Nb_{10}O_{29}$* , Acta Cryst. **14**, 664–670 (1961), doi:10.1107/S0365110X6100200X.